

**ADOMAIN COMPUTATION OF RADIATIVE-CONVECTIVE BI-DIRECTIONAL STRETCHING FLOW
OF A MAGNETIC NON-NEWTONIAN FLUID IN POROUS MEDIA WITH HOMOGENEOUS-
HETEROGENEOUS REACTIONS**

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ABSTRACT: In the present communication, laminar, incompressible, hydromagnetic flow of an electrically conducting non-Newtonian (Sisko) fluid over a bi-directional stretching sheet in a porous medium is studied theoretically. Thermal radiation flux, homogeneous-heterogeneous chemical reactions and convective wall heating are included in the model. Darcy's model is employed for the porous medium and Rosseland's model for radiation heat transfer. The governing partial differential equations for mass, momentum, energy and concentration are reduced into ordinary differential equations via similarity transformations. The resultant nonlinear ordinary differential equations with transformed boundary conditions are then solved via the semi-analytical Adomain decomposition method (ADM). Validation with earlier studies is included for the non-radiative case. Extensive visualization of velocity, temperature and species concentration distributions for various emerging parameters is included. Increasing magnetic field and inverse permeability parameter are observed to decelerate both the primary and secondary velocity magnitudes whereas they increase temperatures in the regime. Increasing sheet stretching ratio weakly accelerates the primary flow throughout the boundary layer whereas it more dramatically accelerates the secondary flow near sheet surface. Temperature is consistently reduced with increasing stretching sheet ratio whereas it is strongly enhanced with greater radiative parameter. With greater Sisko non-Newtonian power-law index the primary velocity and temperature are decreased whereas the secondary velocity is increased. Increasing both homogenous and heterogenous chemical reaction parameters is found to weakly and more strongly, respectively, deplete concentration magnitudes whereas greater Schmidt number enhances them. Primary and secondary skin friction and Nusselt number profiles are also computed. The study is relevant to electro-conductive (magnetic polymer) materials processing operations.

KEYWORDS: *Sisko fluid, homogeneous-heterogenous reactions, porous medium, thermal radiation, ADM, bi-axial stretching, thermal magnetic polymer processing.*

1. INTRODUCTION

Magnetic polymers are being increasingly deployed in modern engineering applications. Such materials combine magnetohydrodynamic and rheological properties and can be customized for different systems including power-generation [1], smart coating technologies [2,3],

supercapacitor electrodes [4] and solar collector receiver surface enhancement [5]. The use of advanced multi-physical fluid dynamics models can significantly improve fabrication processes for such materials and leads to an optimization of quality control, in particular for heat and mass transfer. With judicious use of an applied magnetic field the polymer constitution and performance can be manipulated. Since magnetic polymers exhibit non-Newtonian properties it is essential to utilize appropriate constitutive models which correctly characterize the rheology of such fluids. Conventional Newtonian models are inadequate. Engineers have therefore explored many different rheological models to predict more closely the shear-stress strain behavior of magnetic polymers. Examples of models employed include fractional Burgers viscoelastic models [6], Eringen micropolar models [7] and couple stress nanofluid models [8]. The Sisko model [9] is a relatively simple non-Newtonian model which provides robust predictions for high shear rate flows and is a modification of the power-law model. Originally introduced for lubricants, the Sisko model has been adopted in a wide spectrum of applications including materials processing, biomechanics and thermal engineering systems. These applications include heat and mass transfer and employ a number of numerical approaches to solve nonlinear boundary value problems. Malik *et al.* [10] used a Runge-Kutta-Fehlberg method to compute thermal conductivity effects on velocity and temperature characteristics in Sisko fluid dissipative boundary layer flow from a stretching cylindrical body. Khan *et al.* [11] studied the hydromagnetic Sisko flow in a pipe annulus considering both shear-thinning and thickening behavior. Khan *et al.* [12] deployed both homotopy and finite difference methods to simulate thermal transport in Sisko fluids in an annulus. El-Dabe *et al.* [13] studied the magnetic pumping of Sisko fluid in a porous conduit under peristaltic wave motion. Zaman *et al.* [14] computed the time-dependent blood flow in a cylindrical vessel using the Sisko model. Khan *et al.* [15] used the homotopy analysis method (HAM) to compute the influence of rheological power-law index, Sisko material parameter and stretching parameter on the radially stretching flow of a Sisko liquid. Munir *et al.* [16] examined the impact of forced convection on stretching sheet flow of a Sisko fluid.

In many materials processing operations (including magnetic polymer synthesis), chemical reactions arise. There are two major classifications of chemical reactions, namely homogeneous and heterogeneous. Chemical changes occurring with liquids or gases depend on the type of interactions of these chemical substances. Homogeneous reactions occur in one phase only whereas heterogeneous reactions occur in two or more phases. Chemically reactive materials processing often features purely heterogeneous chemical reactions (catalytic

techniques) and also homogeneous-heterogeneous reactions (magnetic materials, corrosive processes, ceramics, polymers etc). Recently a number of investigators have addressed chemically reactive non-Newtonian and magnetized flows. Shamshuddin *et al.* [17] used a finite element code to simulate double-diffusive convection in reactive micropolar flow. Rajesh *et al.* [18] studied homogenous reaction effects on oscillating magnetic boundary layer flow from a curved surface. Doh *et al.* [19] employed a homotopy method to study the impact of homogeneous and heterogeneous reactions on hydromagnetic silver-water nanofluid Von Karman swirling flow, heat and mass transfer. Nadeem *et al.* [20] analysed ferrofluid rheological flow from a stretching cylinder with magnetization and homogeneous and heterogeneous reactions. Further studies of non-Newtonian reactive flows include Ravi Kiran *et al.* [21] (who employed a micropolar model), Alshomrani and Ullah [22] (who considered carbon nanotube reactive fluid flow from a bi-directional stretching sheet) and Abbas and Sheikh [23] (who studied stagnation ferrofluid flow with homogeneous–heterogeneous reactions). These studies have generally shown that there is a considerable deviation between solutions for higher order chemical effects compared with lower order chemical reaction models.

In high-temperature fabrication of polymers [24, 25], *radiative heat transfer* arises in addition to thermal conduction and thermal convection. To simulate radiative flux many approaches are available. The most general is the solution of the integro-differential equation of radiative heat transfer. This furnishes detailed information on radiative behavior at different spectra and wavelengths. However, it is very challenging computationally. When other effects are present e.g. rheology, magnetohydrodynamics etc, simpler approaches are more pragmatic and these usually feature an *algebraic flux approximation* which may be (in progressively increasing complexity) of the Rosseland type, Milne-Eddington type, Schuster-Schwartzchild type, Traugott P1 flux model, Hamaker six flux model etc. In multi-physical coating flows, the Rosseland model has been shown to be reasonably accurate for high optical thicknesses. Although it does not allow optical thickness or spectral effects to be simulated, it does provide a mechanism for evaluating the relative role of thermal conduction and thermal radiation flux. Several researchers have studied radiative heat transfer in materials processing including Lu *et al.* [26] (magnetic non-Newtonian reactive polymer flows), Kumpaty and Roux [27] (glass synthesis), Rozzi *et al.* [28] (laser-processing of ceramics) and Bég *et al.* [29] (dissipative magnetic coating flows).

In the present article, motivated by providing more comprehensive insight into magnetic polymer processing at high temperature, a mathematical model is developed for radiative magnetohydrodynamic Sisko fluid flow from a bidirectional stretching embedded in a Darcian porous medium with homogeneous and heterogeneous reactions. This model extends the earlier study of Hayat *et al.* [30] to consider radiative heat transfer and also porous medium drag effects. The partial differential boundary value problem is converted to a nonlinear dimensionless ordinary differential boundary value problem with appropriate similarity transformations. A robust solution is obtained with the semi-analytical Adomain decomposition method (ADM) [31] and validation with the non-radiative case [30] is included. A detailed parametric study of the influence of magnetic, Darcy (permeability), stretching sheet ratio, Sisko non-Newtonian power-law index, Schmidt number and homogenous and heterogeneous chemical reaction parameters on velocity, temperature and species concentration distributions is conducted with graphical visualization of results. Primary and secondary skin friction and Nusselt number profiles are also computed. The computations may be beneficial in further understanding the complex interplay between chemical reactions, magnetic field and rheology in materials processing operations.

2. MATHEMATICAL REACTIVE MAGNETIC POLYMER STRETCHING FLOW MODEL

Consider the flow of an incompressible electrically conducting polymeric Sisko fluid with heat and mass transfer from a bi-directional stretching sheet under a transverse (vertical) magnetic field of strength B_0 adjacent to a porous medium. Hall and electric field effects are ignored. The porous medium is assumed to isotropic and homogenous and Darcy's model is employed for viscous-dominated low Reynolds number transport. We consider a Cartesian coordinate system such that the sheet coincides with the xy -plane and fluid occupies the space $z \geq 0$ as illustrated in **Figure.1**. Let $U_w(x) = cx$ and $V_w(x) = dy$ denote the surface stretching velocities along the x, y directions and $c, d > 0$. The temperature at the sheet is governed by a convective heating process which is described by a heat transfer coefficient h_f and temperature of the hot fluid T_f below the sheet. Viscous dissipation effects are ignored. The corresponding equations, under the above assumptions, describing the three-dimensional Sisko fluid motion are given by extending the model of Hayat *et al.* [30] with Darcian drag force and radiative heat flux terms, leading to:

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0 \quad (1)$$

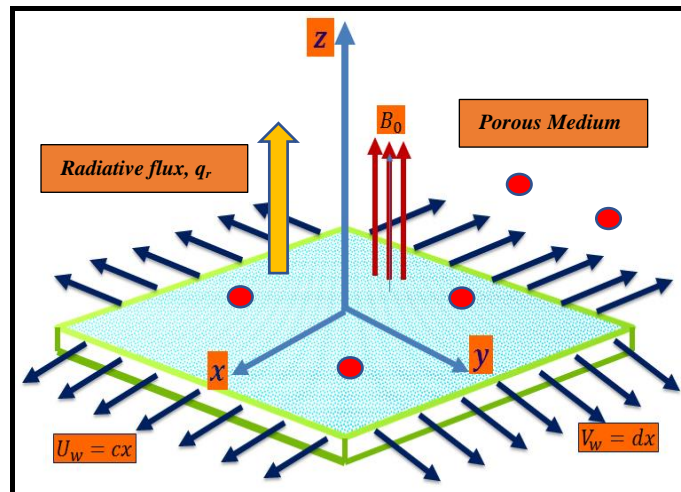


Figure 1: Schematic physical model for bi-directional stretching flow of a Sisko fluid

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = \frac{a}{\rho} \frac{\partial^2 u}{\partial z^2} - \frac{b}{\rho} \frac{\partial}{\partial z} \left(-\frac{\partial u}{\partial z} \right)^n - \frac{\mu}{k} u - \frac{\sigma B_0^2}{\rho} u, \quad (2)$$

$$u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} = \frac{a}{\rho} \frac{\partial^2 v}{\partial z^2} + \frac{b}{\rho} \frac{\partial}{\partial z} \left(-\frac{\partial u}{\partial z} \right)^{n-1} \frac{\partial v}{\partial z} - \frac{\mu}{k} v - \frac{\sigma B_0^2}{\rho} v, \quad (3)$$

$$u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial y} + w \frac{\partial T}{\partial z} = \alpha_m \frac{\partial^2 T}{\partial z^2} - \frac{1}{\rho C_p} \frac{\partial q_r}{\partial z}, \quad (4)$$

$$u \frac{\partial a_1}{\partial x} + v \frac{\partial a_1}{\partial y} + w \frac{\partial a_1}{\partial z} = D_A \frac{\partial^2 a_1}{\partial z^2} - k_c a_1 b_1^2, \quad (5)$$

$$u \frac{\partial b_1}{\partial x} + v \frac{\partial b_1}{\partial y} + w \frac{\partial b_1}{\partial z} = D_B \frac{\partial^2 b_1}{\partial z^2} + k_c a_1 b_1^2. \quad (6)$$

The appropriate boundary conditions for the regime are:

$$\text{at } z=0: u=U_w=cx, v=V_w=dy, w=0, -k \frac{\partial T}{\partial z} = h_f (T_f - T), D_A \frac{\partial a_1}{\partial z} = k_s a_1, D_B \frac{\partial b_1}{\partial z} = -k_s a_1 \quad (7)$$

$$\text{at } z \rightarrow \infty: u \rightarrow 0, v \rightarrow 0, T \rightarrow T_\infty, a_1 \rightarrow a_0, b_1 \rightarrow 0$$

A simple model of heterogeneous-homogeneous reactions is adopted in Eqns. (5) and (6) [32]



Here the *catalyst surface heterogeneous reaction* is defined as follows:



Here the chemical species A_1 and A_2 have concentrations a_1 and b_1 respectively. k_c and k_s are the rate constants. In Eqns. (1)-(7) u, v and w designate the velocity components, ρ denotes base fluid density, D_A and D_B are the respective diffusion species coefficients, a_0 is the positive dimensionless constant, T denotes the surface fluid temperature, $\alpha_m = \kappa / \rho C_p$ represents thermal diffusivity, κ the thermal conductivity of the magnetic polymer (Sisko fluid), ρC_p heat capacity of fluid, a and b denote material parameters of the Sisko fluid and n is the Sisko power-law rheological index ($n > 0$ characterizes the non-Newtonian features of the fluid). q_r signifies radiative heat flux which is assumed from [33] and is denoted in the Rosseland model [29] as $\frac{\partial q_r}{\partial z} = -\frac{16\sigma^*}{3k^*} \frac{\partial}{\partial z} \left(T^3 \frac{\partial T}{\partial z} \right)$. It should be noted that unlike classical cases, the nonlinear form of thermal radiation is considered here. Furthermore, the nonlinear thermal radiation effect in the linearized Rosseland approximation is a simple rescaling of the Prandtl number by a factor involving the radiation parameter. The solution of the radiation problem in the linearized Rosseland approximation does not require any additional numerical or analytical efforts. It is seen that the energy equation in case of nonlinear radiation is strongly nonlinear and contains an additional temperature parameter which is the ratio of wall and ambient temperature. To facilitate a numerical solution of the boundary value problem, it is judicious to introduce the following dimensionless variables [34-35]:

$$\left. \begin{aligned} u &= cxf'(\eta), v = dg'(\eta), w = -c \left(\frac{c^{n-2}}{\rho/b} \right)^{1/(n+1)} \left(\frac{2n}{n+1} f + \frac{1-n}{n+1} \eta f' + g \right) x^{\frac{n-1}{n+1}}, \\ \theta(\eta) &= \frac{T - T_\infty}{T_f - T_\infty}, \quad a_1 = a_0 h(\eta), \quad b_1 = a_0 h(\eta), \quad \eta = z \left(\frac{c^{2-n}}{\rho/b} \right)^{1/n+1} x^{\frac{1-n}{1+n}} \end{aligned} \right\} \quad (10)$$

Implementing Eqn. (10) in Eqns. (2)-(7) produces the following dimensionless similarity equations in which equation (1) is automatically satisfied:

$$A f''' + n(-f'')^{n-1} f''' + \left(\frac{2n}{n+1} \right) f f'' - (-f')^2 + g f'' - K f' - M^2 f' = 0 \quad (11)$$

$$A g''' + (-f'')^{n-1} g''' - (n-1)(-f'')^{n-2} f''' g'' + \left(\frac{2n}{n+1} \right) f g'' - (-g')^2 + g g'' - K g' - M^2 g' = 0 \quad (12)$$

$$\left[\left\{ 1 + R(1 + (\theta_w - 1)\theta)^3 \right\} \theta' \right]' + \text{Pr} \left(\frac{2n}{n+1} \right) f \theta' + \text{Pr} g \theta' = 0 \quad (13)$$

$$\phi'' + Sc \left(\frac{2n}{n+1} \right) f \phi' + Sc g \phi' - Sc k_1 h^2 \phi = 0 \quad (14)$$

$$\delta_1 h'' + Sc \left(\frac{2n}{n+1} \right) f h' + Sc g h' + Sc k_1 h^2 \phi = 0 \quad (15)$$

$$\left. \begin{aligned} f = 0, g = 0, f' = 1, g' = \alpha, \theta' = -\gamma(1-\theta), \phi' = k_2 \phi, \delta_1 h' = -k_2 \phi \text{ at } \eta = 0 \\ f' \rightarrow 0, g' \rightarrow 0, \theta \rightarrow 0, \phi \rightarrow 0, h \rightarrow 0 \text{ when } \eta \rightarrow \infty \end{aligned} \right\} \quad (16)$$

The dimensionless flow parameters featured in Eqns. (11)-(16) are defined illustrated as below:

$$\begin{aligned} A = \frac{\text{Re}_b^{2/n+1}}{\text{Re}_a}, \quad \text{Re}_a = \frac{\rho x U_w}{a}, \quad \text{Re}_b = \frac{\rho x^n U_w^{2-n}}{b}, \quad K = \frac{\mu}{k U_w} x, \quad M^2 = \frac{\sigma B_0^2}{\rho c}, \\ \alpha = \frac{d}{c}, \quad k_1 = \frac{k_c a_0^2}{c}, \quad k_2 = \frac{k_s c x}{D_A z} \text{Re}_b^{-1/(n+1)}, \quad \gamma = \frac{h_f}{k} x \text{Re}_b^{-1/(n+1)}, \quad \delta_1 = \frac{D_A}{D_B}, \quad (17) \\ \text{Pr} = \frac{x U_w}{\alpha_m} \text{Re}_b^{-2/(n+1)}, \quad R = \frac{16 \sigma^*}{3 k k^*} T_\infty^3, \quad \theta_w = \frac{T_f}{T_\infty}, \quad Sc = \frac{U_w x}{D_A} \text{Re}_b^{-2/(n+1)}, \end{aligned}$$

Here A signifies the Sisko rheological fluid material parameter, Re_a and Re_b are local Reynolds numbers, K indicates inverse permeability parameter, M indicates the magnetic body force parameter, α designates the stretching sheet ratio parameter, k_1 and k_2 define the intensity (strength) of the homogenous and heterogeneous reactions respectively, Pr denotes Prandtl number, R denotes thermal radiation parameter, Sc denotes Schmidt number, δ_1 represents the diffusion coefficient ratio, γ denotes generalized Biot number. It is noted that an additional temperature ratio parameter θ_w arises and due to this reason the energy equation will

be more nonlinear; by using $q_r = -\frac{16 \sigma^*}{3 k^*} T_\infty^3 \frac{\partial T}{\partial z}$ in Eqn. (4) leads to the more appropriate form

i.e. Eqn. (13). The similarity solutions are possible only in the case $n = 1$ (for viscous fluid) and the parameters $A=0$ and γ are independent of x , i.e. γ is constant. Herein local similar solutions are developed since in general the parameters in the derived model are functions of the independent variable x ([36-37]). The coefficients of diffusion of chemical species A_1 and A_2 may be taken to be the same so that the diffusion coefficients D_A and D_B are identical i.e. $\delta_1 = 1$ and thus the following relation will be obtained:

$$\phi(\eta) + h(\eta) = 1 \quad (18)$$

Eqns. (14) and (15) may therefore be combined to yield the following *single* concentration equation [30]:

$$\phi'' + Sc \left(\frac{2n}{n+1} \right) f \phi' + Sc g \phi' - Sc k_1 \phi (1-\phi)^2 = 0, \quad (19)$$

The associated concentration boundary conditions:

$$\phi'(0) = k_2 \phi(0) \text{ as } \phi(\infty) \rightarrow 1 \quad (20)$$

The final transformed coupled ordinary differential equations with boundary conditions emerge as follows:

$$A f''' + n(-f'')^{n-1} f''' + \left(\frac{2n}{n+1}\right) f f'' - (-f')^2 + g f'' - K f' - M^2 f' = 0 \quad (21)$$

$$A g''' + (-f'')^{n-1} g''' - (n-1)(-f'')^{n-2} f''' g'' + \left(\frac{2n}{n+1}\right) f g'' - (-g')^2 + g g'' - K g' - M^2 g' = 0 \quad (22)$$

$$\left[\left\{ 1 + R(1 + (\theta_w - 1)\theta)^3 \right\} \theta' \right]' + \text{Pr} \left(\frac{2n}{n+1} \right) f \theta' + \text{Pr} g \theta' = 0 \quad (23)$$

$$\phi'' + \text{Sc} \left(\frac{2n}{n+1} \right) f \phi' + \text{Sc} g \phi' - \text{Sc} k_1 \phi (1 - \phi)^2 = 0, \quad (24)$$

$$\left. \begin{aligned} f = 0, \quad g = 0, \quad f' = 1, \quad g' = \alpha, \quad \theta' = -\gamma(1 - \theta), \quad \phi'(0) = k_2 \phi(0) \text{ at } \eta = 0 \\ f' \rightarrow 0, \quad g' \rightarrow 0, \quad \theta \rightarrow 0, \quad \phi(\infty) \rightarrow 1 \text{ when } \eta \rightarrow \infty \end{aligned} \right\} \quad (25)$$

Here skin friction coefficient along x , y directions and local Nusselt number, which are important engineering design quantities in materials processing, take the form:

$$Cf_x = \frac{A f''(0) - (-f''(0))^n}{\text{Re}_b^{1/n+1}}, \quad (26)$$

$$Cf_y = \frac{\frac{V_w}{U_w} \left[A g''(0) + (-f''(0))^{n-1} g''(0) \right]}{\text{Re}_b^{1/n+1}}, \quad (27)$$

$$Nu_x = - \frac{\left[1 + R \left\{ 1 + (\theta_w - 1)\theta(0) \right\}^3 \right]}{\text{Re}_b^{\frac{1}{n+1}}} \theta'(0) \quad (28)$$

It is noted that the dimensionless mass flux denoted by Sherwood number Sh_x is now identically zero.

3.ADM SOLUTION

The system of coupled ordinary differential equations (21)-(24) with associated boundary conditions (25) constitute a 10th order, nonlinear, multi-degree boundary value problem. Numerous methods are available to solve such systems including shooting methods, finite element methods, homotopy methods etc. Here a semi-analytical/numerical method called the Adomain Decomposition Method (ADM) is employed. In ADM, the analytic approximate solutions to a nonlinear equation are obtained without linearization and discretization yielding more accurate results. Therefore, ADM has been deployed recently in many sophisticated

multi-physical fluid dynamic problems including magnetic bio-lubrication [38], hydromagnetic cilia propulsion [39] and swirling bioconvection nanofluid flows [40]. Adomian [31] deployed an infinite series solution for the unknown functions, utilized recursive relations and also produced an alternative approach for polynomial expansions to achieve faster convergence. Applying the standard procedure of ADM with standard notation i.e.,

$$L u(y) + R u(y) + N u(y) = Q(y) \quad (29)$$

which is derived from the form $D\{u\} = Q(y)$. Here D signifies differential operator of linear term $\{L + R\}$ with L being the highest ordered derivative which is easily invertible and R is the remaining linear part. The nonlinear part is $N u(y)$. It follows that the standard form can be written as follows:

$$u(y) = L^{-1}\{Q(y)\} - L^{-1}\{R u(y)\} - L^{-1}\{N u(y)\} \quad (30)$$

Next we introduce $L_1 = \frac{d^3}{d\eta^3}(\cdot)$ and $L_2 = \frac{d^2}{d\eta^2}(\cdot)$ with invertible operators $L_1^{-1}(\cdot) = \int_0^\eta \int_0^\eta \int_0^\eta (\cdot) d\eta d\eta d\eta$

and $L_2^{-1}(\cdot) = \int_0^\eta \int_0^\eta (\cdot) d\eta d\eta$. Thus, arranging all the Eqns. (21)-(24) and by writing them as infinite

series using recursive relations with initial guesses, the approximate analytical solutions can be obtained for the variables (primary velocity, f' , secondary velocity g' , temperature θ , concentration ϕ). The ADM power series expansions are listed in the Appendix.

4. RESULTS AND DISCUSSION

The influence of selected parameters on primary and secondary velocity components, temperature and concentration distributions is visualized in **Figs. 2-17**. Moreover, computed values of the primary and secondary skin friction ($-f''(0), -g''(0)$) and Nusselt number ($-\theta'(0)$) are displayed in **Table 2**. Validation of the ADM solutions is provided for the primary and secondary skin friction coefficients with different stretching sheet ratio parameter (α) in **Table 1** for comparison with the ND Solve shooting quadrature Mathematica solutions of Hayat *et al.* [30] $A=M=K=R=0$ i.e. in the absence of Sisko non-Newtonian, magnetic, porous medium and radiative effects. Reasonable agreement is achieved and confidence in the present ADM solutions is therefore high.

Table 1: Comparison of skin friction coefficients for different values of α when $A=M=K=R=0$.

α	$-f''(0)$	$-f''(0)$	$-g''(0)$	$-g''(0)$
	Hayat <i>et al.</i> , [30]	ADM results	Hayat <i>et al.</i> , [30]	ADM results
0.3	1.055234	0.9475	0.234632	0.2500
0.5	1.090504	0.9828	0.458035	0.4527
0.8	1.149069	1.0413	0.859627	1.1684
1.0	1.172897	1.0651	1.698852	1.6936

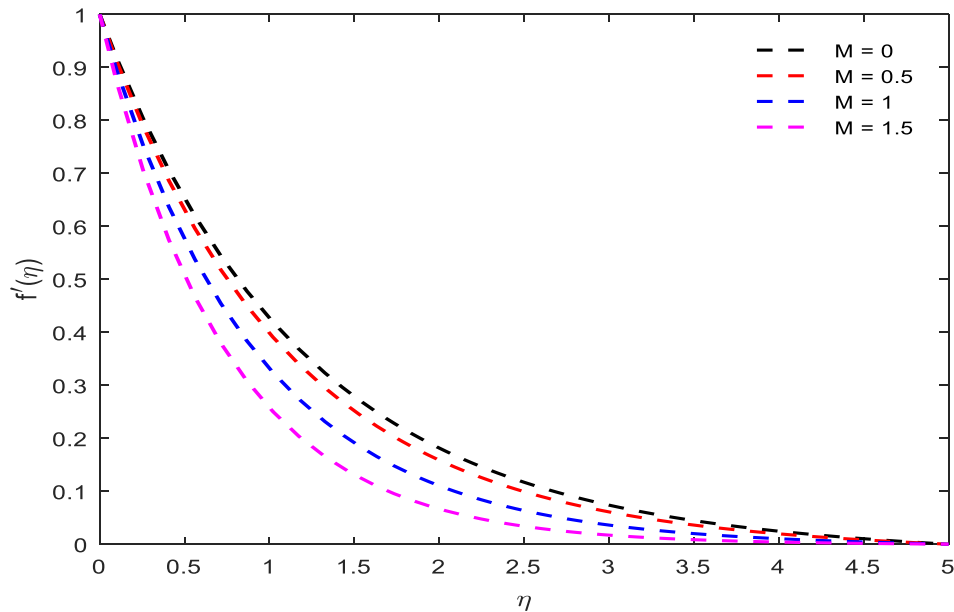


Figure 2: Influence of magnetic parameter on velocity component in x-direction for $\gamma = 0.3, K = 0.5, A = \alpha = n = Sc = 1.0, Pr = 4.0, R = 0.3, k_1 = k_2 = 0.5$

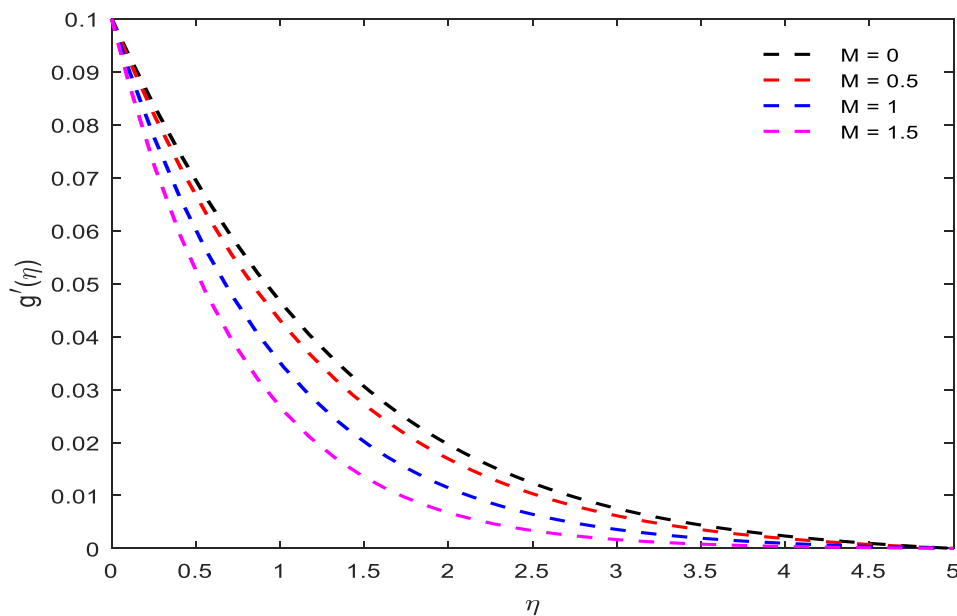


Figure 3: Influence of magnetic parameter on velocity component in y-direction for $\gamma = 0.3, K = 0.5, A = \alpha = n = Sc = 1.0, R = 0.3, Pr = 4.0, k_1 = k_2 = 0.5$

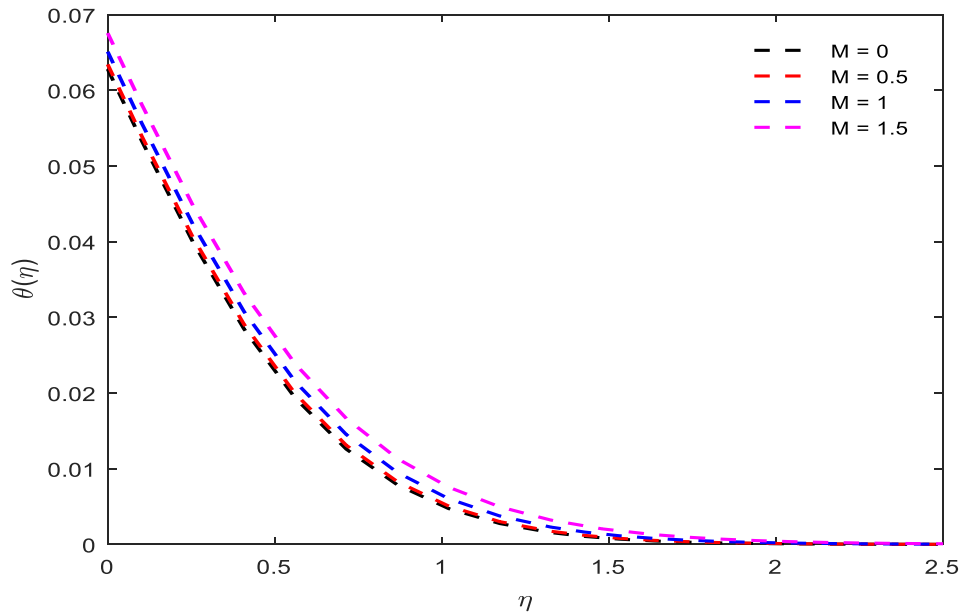


Figure 4: Influence of magnetic parameter on temperature for $\gamma = 0.3, K = 0.5, A = \alpha = n = Sc = 1.0, R = 0.3, Pr = 4.0, k_1 = k_2 = 0.5$

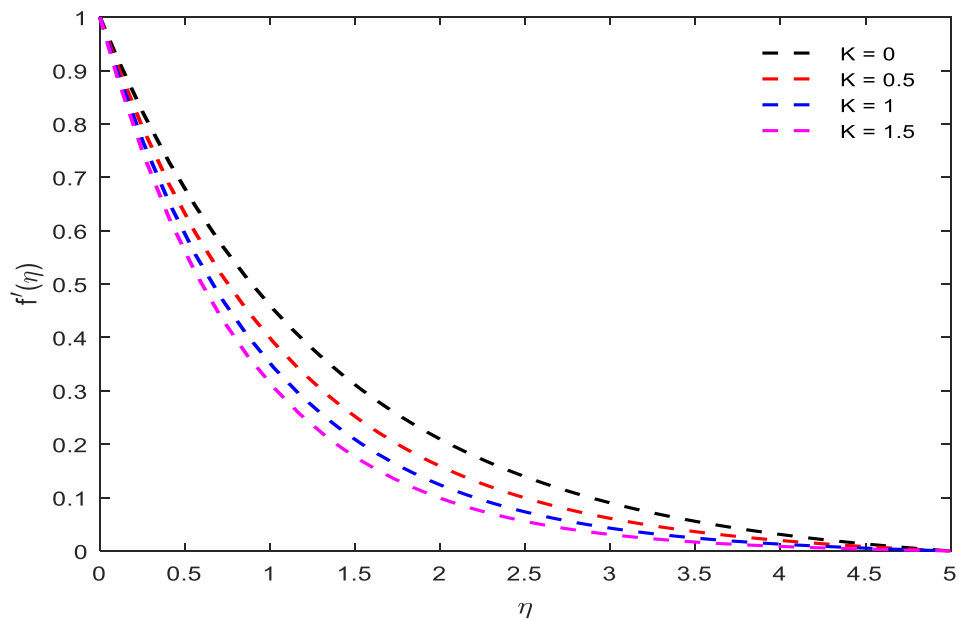


Figure 5: Influence of permeability parameter on velocity component in x-direction for $\gamma = 0.3, M = 0.3, A = \alpha = n = Sc = 1.0, R = 0.3, Pr = 4.0, k_1 = k_2 = 0.5$

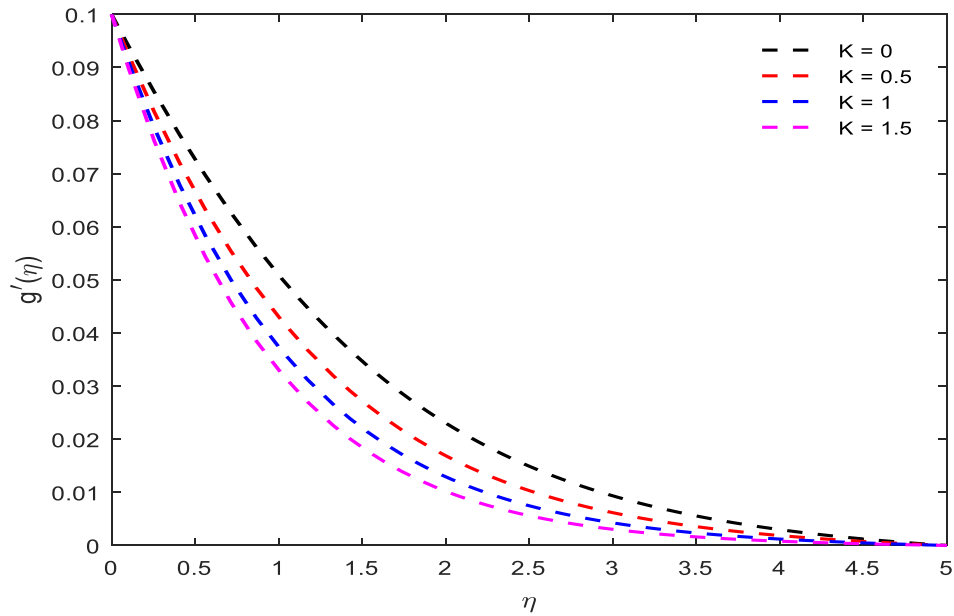


Figure 6: Influence of permeability parameter on velocity component in y-direction for $\gamma = 0.3, M = 0.3, A = \alpha = n = Sc = 1.0, R = 0.3, Pr = 4.0, k_1 = k_2 = 0.5$

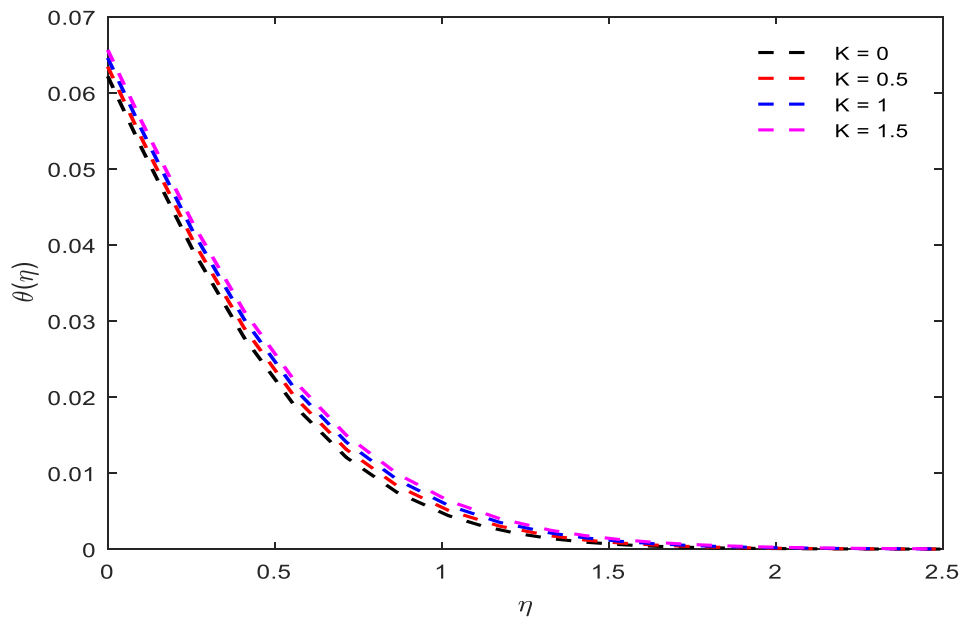


Figure 7: Influence of permeability parameter on temperature for $\gamma = 0.3, M = 0.3, A = \alpha = n = Sc = 1.0, R = 0.3, Pr = 4.0, k_1 = k_2 = 0.5$

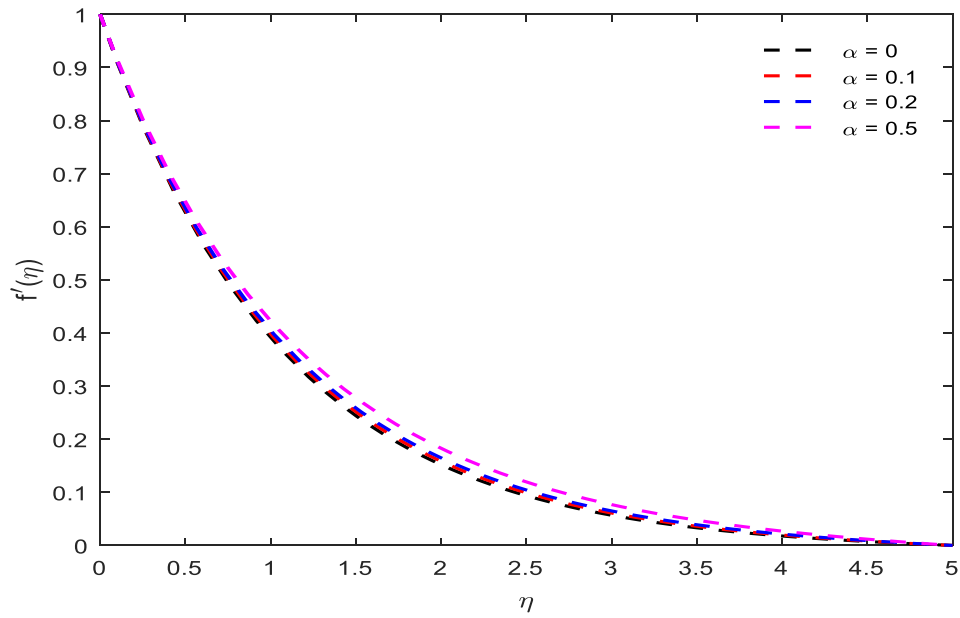


Figure 8: Influence of ratio parameter on velocity component in x-direction for $\gamma = 0.3, M = 0.3, K = 0.5, A = n = Sc = 1.0, R = 0.3, Pr = 4.0, k_1 = k_2 = 0.5$

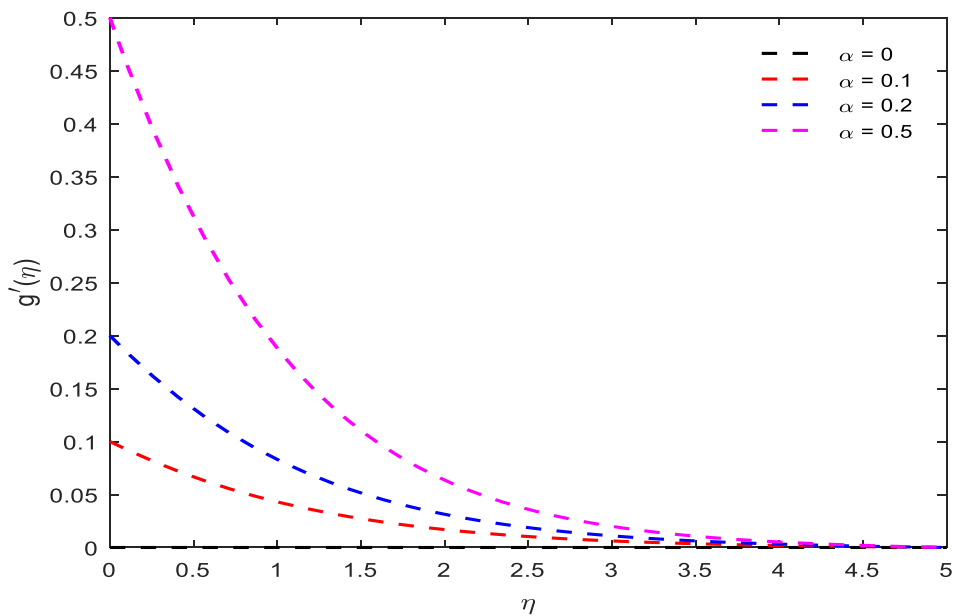


Figure 9: Influence of ratio parameter on velocity component in y-direction for $\gamma = 0.3, M = 0.3, K = 0.5, A = n = Sc = 1.0, R = 0.3, Pr = 4.0, k_1 = k_2 = 0.5$

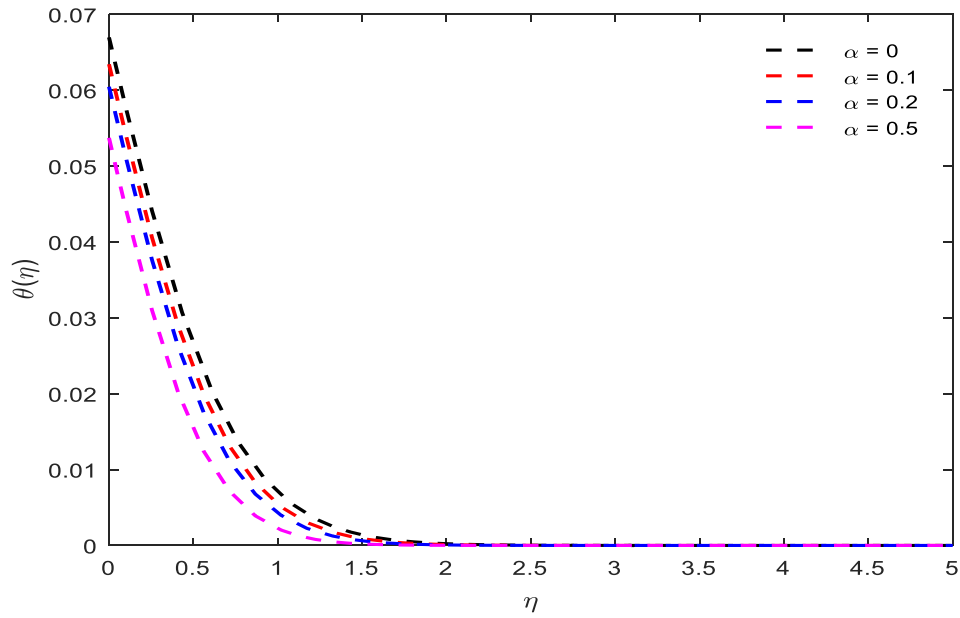


Figure 10: Influence of ratio parameter on temperature for $\gamma = 0.3, M = 0.3, K = 0.5, A = n = Sc = 1.0, R = 0.3, Pr = 4.0, k_1 = k_2 = 0.5$

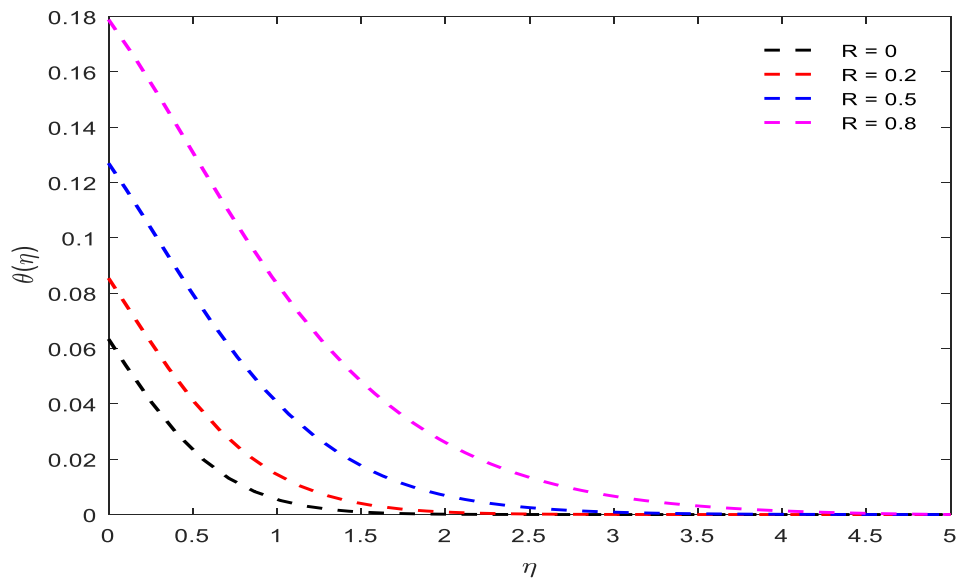


Figure 11: Influence of thermal radiation parameter on temperature for $\gamma = 0.3, M = 0.3, K = 0.5, A = \alpha = n = Sc = 1.0, Pr = 4.0, k_1 = k_2 = 0.5$

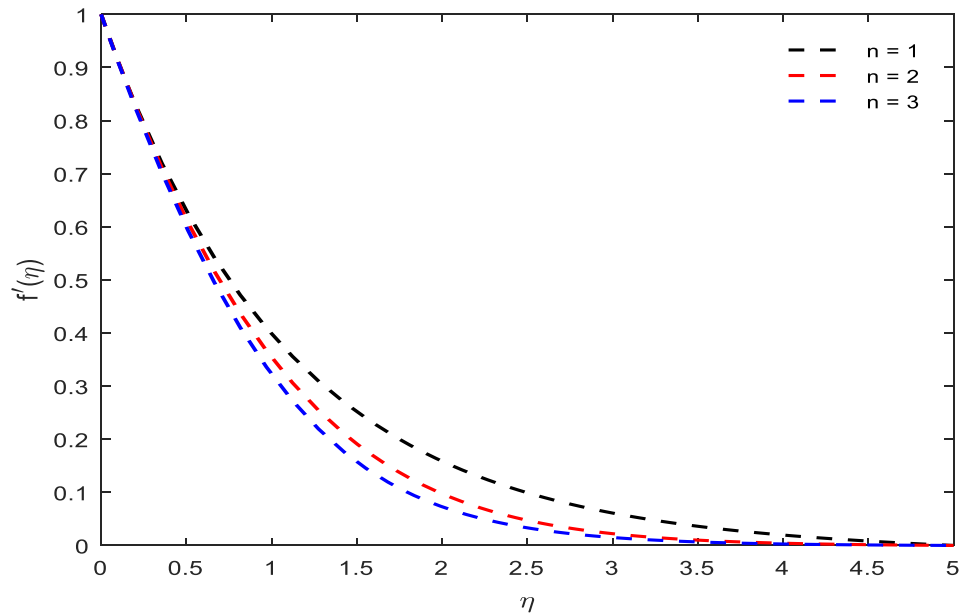


Figure 12: Influence of material parameter on velocity component in x-direction for $\gamma = 0.3, M = 0.3, K = 0.5, A = \alpha = Sc = 1.0, R = 0.3, Pr = 4.0, k_1 = k_2 = 0.5$

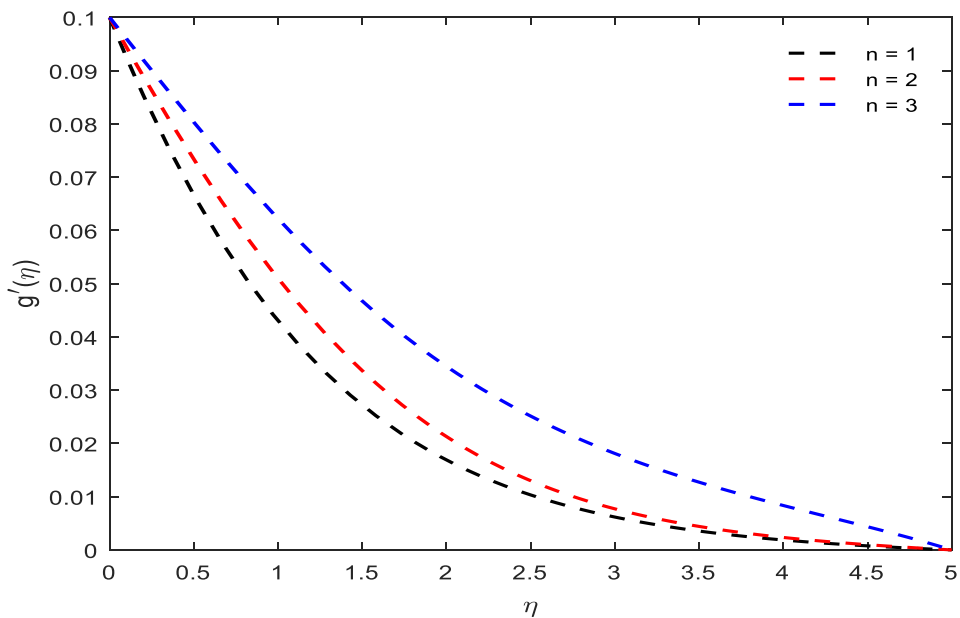


Figure 13: Influence of material parameter on velocity component in y-direction for $\gamma = 0.3, M = 0.3, K = 0.5, A = \alpha = Sc = 1.0, R = 0.3, Pr = 4.0, k_1 = k_2 = 0.5$

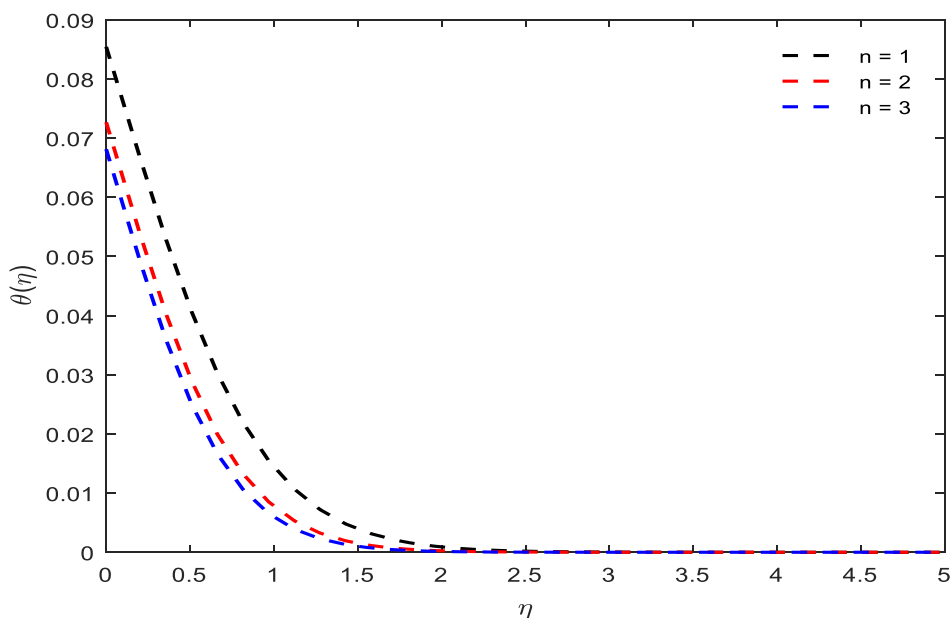


Figure 14: Influence of material parameter on temperature for $\gamma = 0.3, M = 0.3, K = 0.5, A = \alpha = Sc = 1.0, R = 0.3, Pr = 4.0, k_1 = k_2 = 0.5$

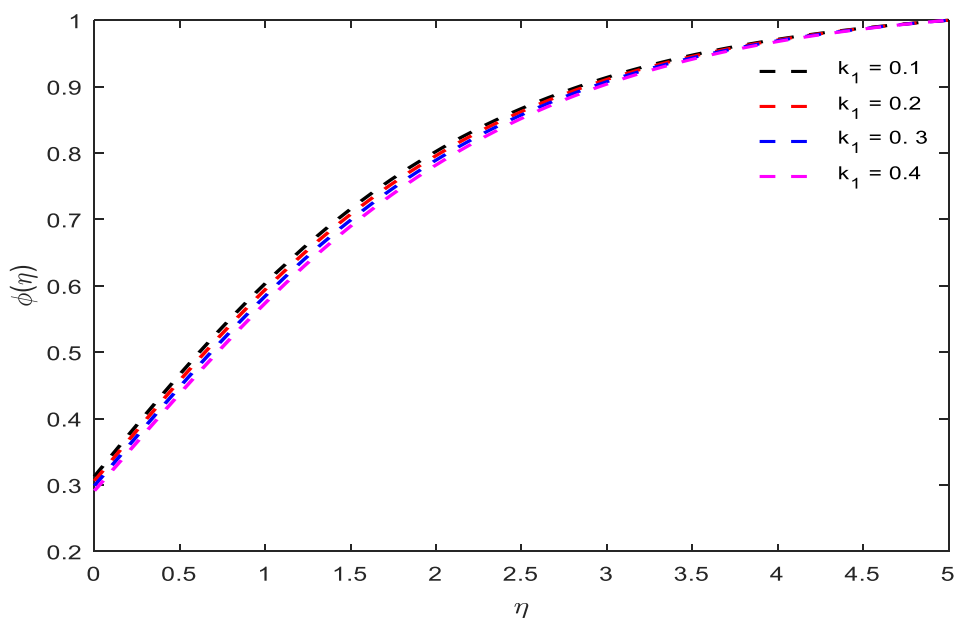


Figure 15: Influence of strength of homogenous chemical reaction parameter on concentration for $\gamma = 0.3, M = 0.3, K = 0.5, A = \alpha = n = Sc = 1.0, R = 0.3, Pr = 4.0, k_2 = 0.5$

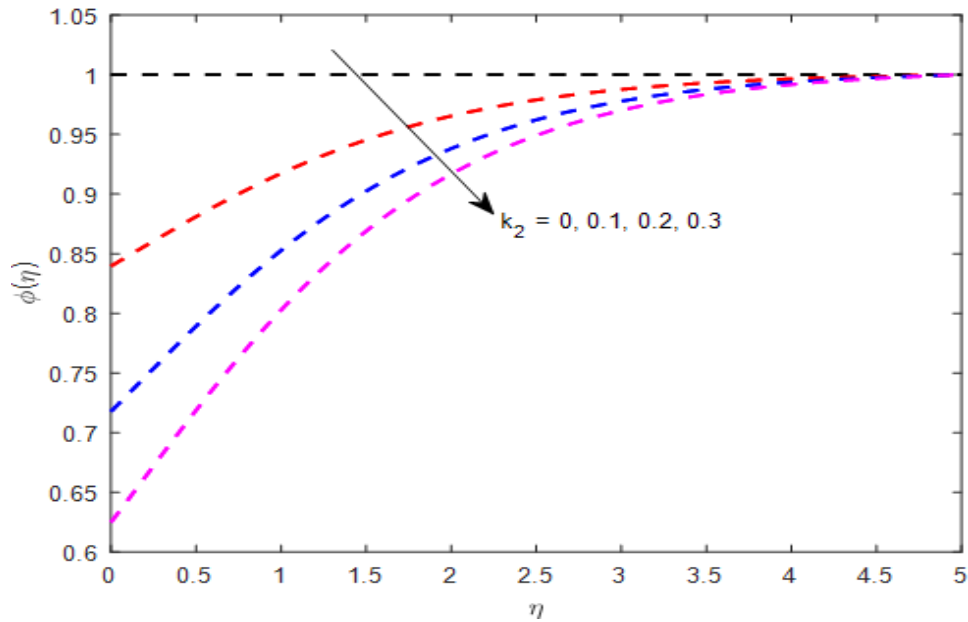


Figure 16: Influence of strength of heterogenous chemical reaction parameter on concentration for $\gamma = 0.3, M = 0.3, K = 0.5, A = \alpha = n = Sc = 1.0, R = 0.3, Pr = 4.0, k_1 = 0.5$

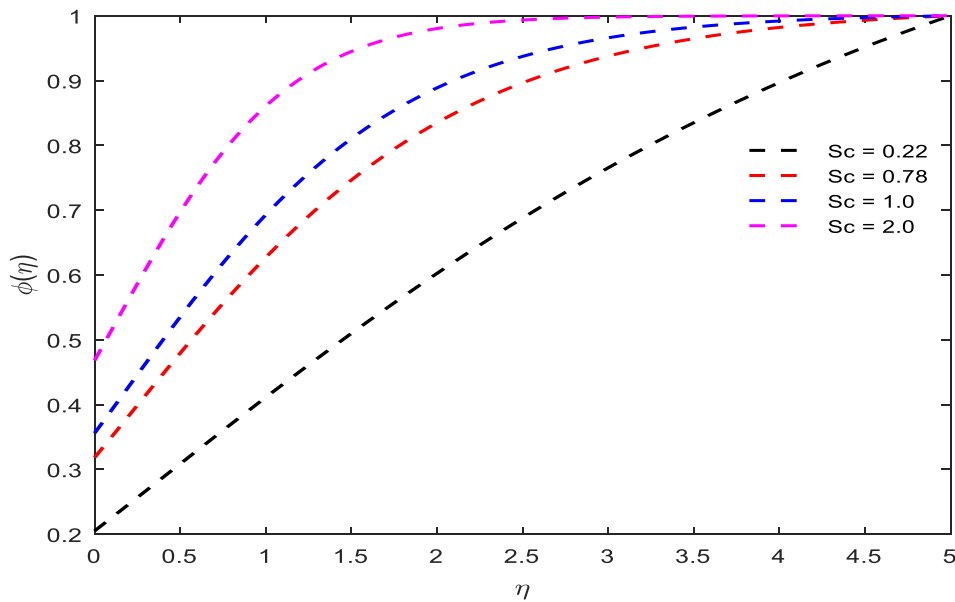


Figure 17: Influence of Schmidt number on concentration for $\gamma = 0.3, M = 0.3, K = 0.5, A = \alpha = n = 1.0, R = 0.3, Pr = 4.0, k_1 = k_2 = 0.5$

Table 2: Values of $-f''(0)$, $-g''(0)$ and $-\theta'(0)$ for different values of A, M, K, α, n and R

A	M	K	α	n	R	$-f''(0)$	$-g''(0)$	$-\theta'(0)$
0.0	0.0	0.0	0.3	1.0	0.2	0.9475	0.25	0.0923
0.5						0.7761	0.2045	0.0925
1.0						0.6751	0.1778	0.0926
	0.5					0.7597	0.2049	0.0925
	1.0					0.9743	0.2731	0.0923
	1.5					1.2546	0.361	0.0918
		0.5				0.8369	0.2295	0.0924
		1.0				0.9743	0.2731	0.0923
		1.5				1.095	0.3111	0.0921
			0.1			0.699	0.049	0.0918
			0.2			0.6751	0.1778	0.0926
			0.5			0.654	0.3391	0.0932
				1.0		0.6751	0.1778	0.0926
				1.5		0.9914	0.0599	0.1275
				2.0		0.7245	0.1211	0.0936
					1.0	0.7597	0.2049	0.0826
					2.0	0.7597	0.2049	0.0671
					3.0	0.7597	0.2049	0.0551

In the model Eqns. (21)-(24) with boundary conditions (25), 12 parameters arise and the default values set in the ADM computations are as follows: A (Sisko material parameter) = 1.0, n (Sisko power-law index) = 1.0, K (permeability parameter) = 1.0, M (magnetic parameter) = 1.0, α (bidirectional sheet stretching ratio) = 1.0, θ_w (temperature ratio parameter) = 0.1, k_1 (homogenous reaction strength) = 0.5, k_2 (heterogeneous reaction strength) = 0.5, Pr (Prandtl number) = 4.0, R (radiative parameter) = 1.0, Sc (Schmidt number) = 1.0, γ (thermal Biot number) = 0.3.

Figs. 2-4 illustrate the influence of magnetic body force parameter on the primary (x -direction) and secondary (y -direction) velocity components and temperature. There is a significant reduction in the primary velocity (velocity component in x -direction) with greater magnetic field, as observed in Fig. 2. The Lorentz body force associated with the vertical magnetic field has components in both the x - and y -directions, which appear as the terms $-M^2 f'$ and $-M^2 g'$ in eqns. (21) and (22), respectively. This is a retarding force and impedes the motion of the sheet. Clearly maximum primary velocity is achieved in the absence of a magnetic field i.e. $M=0$ (electrically non-conducting case) and the minimum primary velocity corresponds to the strongest magnetic field case of $M=1.5$. Fig. 3 demonstrates that while a similar reduction in secondary velocity is induced with increasing magnetic parameter, the magnitudes of the

secondary velocity are significantly lower than the primary velocity. In both Figs 2 and 3 asymptotically smooth profiles in velocity components from the sheet surface (wall) to the edge of the boundary layer (free stream) are observed indicating that a sufficiently high infinity boundary condition has been prescribed in the ADM computations. In fig. 3 the increase in magnetic parameter is seen to enhance temperatures throughout the flow domain. Although magnetic terms do not arise in the energy conservation Eqn. (23), the coupling of the temperature (θ) Eqn. with the primary and secondary momentum equations via for example the terms, $\text{Pr} \left(\frac{2n}{n+1} \right) f \theta'$, $\text{Pr} g \theta'$ implies that there is an *indirect influence* of the magnetic field on the temperature. The supplementary work done in dragging the Sisko fluid against the action of the transverse magnetic field is expended as heat i.e. thermal energy. This energizes the Sisko fluid and leads to an elevation in temperatures with greater magnetic parameter, M . Clearly the regime is cooled in the absence of a magnetic field and heated substantially with strong vertical magnetic field strength. This also concurs with the findings of Hayat *et al.* [30].

Figs. 5-7 illustrate the impact of the inverse permeability parameter, K , on primary (x -direction) and secondary (y -direction) velocity components and temperature. As in the case of the magnetic body force, the impedance due to the porous medium also results in a Darcian drag force component in both primary and secondary momentum equations. These components are linear in nature i.e. $-K f'$ and $-K g'$ clearly resistive. The parameter K is in fact inversely related to the actual permeability of the porous medium, k , as defined in Eqn. (17). As K is increased, k is decreased implying that there is greater solid fiber resistance to the percolating flow since the permeability is lower. This manifests in an increase in Darcian drag force components in both primary and secondary momentum equations and leads to significant deceleration in both primary and secondary flows, as observed in Figs. 5 and 6. Conversely with increasing K parameter (decreasing permeability, k , of the medium) there is a boost in temperatures, as observed in Fig. 7. This is attributable to the enhanced thermal conduction present in the porous medium with greater concentration of solid fibers at lower permeabilities. Evidently therefore cooling of the regime is achieved with purely fluid regimes i.e. the vanishing porous medium case ($K = 0$ implying $k \rightarrow \infty$).

Figs. 8-10 depict the variations in primary (x -direction) and secondary (y -direction) velocity components and temperature with sheet stretching ratio ($\alpha = d/c$). When $\alpha = 0$ the sheet is stagnant i.e. no stretching occurs and *two-dimensional* flow is achieved. For $\alpha = 1$,

axisymmetric stretching is produced i.e. equal stretching rates in both x and y directions. A weak acceleration is induced in the primary flow with increasing sheet stretching ratio, α (fig. 8); a much stronger enhancement in secondary velocity is induced in Fig. 9, and the effect is greater at the wall and progressively diminishes into the free stream. Again, asymptotically smooth profiles are achieved in both Figs. 8 and 9 in the free stream confirming the implementation of adequately large infinity boundary conditions in the ADM solution. A notable depletion in temperature accompanies a rise in stretching ratio parameter (Fig. 10) and again this is largely concentrated in the near-wall region.

Fig. 11 illustrates the distribution in temperature with various radiation parameter (R) values. This parameter features in the augmented diffusion term in the energy conservation Eqn. (23) i.e. $[\{1 + R(1 + (\theta_w - 1)\theta)^3\}\theta']'$. $R = \frac{16 \sigma^*}{3 k k^*} T \infty^3$ and embodies the relative contribution of thermal radiation heat transfer to thermal conduction heat transfer. For $R = 0$ radiative flux vanishes. As R increases the Sisko fluid regime is progressively energized via radiation and temperatures are strongly boosted. The most dramatic impact is nearer the wall although the temperature elevation is sustained some distance from the wall. Evidently in mathematical models of high-temperature materials processing of magnetic polymers, the neglect of radiative heat transfer will significantly under-predict temperatures. It is important to include radiative effects albeit with simple algebraic flux models and in this regard the Rosseland model does capture the modification in temperatures quite reasonably. Similar observations have been made in Lu *et al.* [26] and Bég *et al.* [29].

Figs. 12-14 depict the evolution in primary (x -direction) and secondary (y -direction) velocity components and temperature with Sisko rheological power-law index (material parameter), n . There is a significant reduction in primary velocity, $f'(\eta)$, with greater n values. Higher values of this parameter imply a significant escalation in polymer viscosity and increasingly shear-thickening (dilatant) this results in a *deceleration* in the primary flow of the bi-directional stretching sheet (Fig. 12). Conversely the momentum lost in the primary flow is re-distributed in the secondary flow and this leads to an elevation in secondary flow velocities (Fig. 13). Secondary flow is therefore accelerated for the strong dilatant polymer whereas primary flow is decelerated. The shear-thinning case ($0 < n < 1$) has been considered elsewhere [30] and is not studied here. A strong decrease in temperatures is also generated with increasing dilatant behavior ($n > 1$) as observed in Fig. 14.

Figs. 15-16 depict the impact of k_1 (homogenous reaction strength) and k_2 (heterogeneous reaction strength), respectively, on concentration distribution, $\phi(\eta)$. There is a weak decrease

in concentration with increasing k_1 values i.e. homogenous destructive reaction depletes the concentration of the original species due to conversion to another, as observed in Fig. 15. The k_1 parameter arises in the reduced diffusion Eqn. (24), whereas k_2 (heterogeneous reaction strength) features in the concentration wall boundary condition (25) i.e. $\phi'(0) = k_2 \phi(0)$. A much stronger depletion in the concentration magnitudes is induced with increasing k_2 values. Maximum concentration is achieved in the absence of heterogenous reaction ($k_2 = 0$) as seen in Fig. 16.

Fig. 17 the response in concentration $\phi(\eta)$ with Schmidt number, Sc . Schmidt number provides a quantification of the relative rate of momentum diffusion to species diffusion. When $Sc = 1$ both rates of diffusion are the same. $Sc < 1$ is representative of for example oxygen diffusion in low-weight polymers and $Sc > 1$ corresponds to diffusion of gases in higher density polymers. A marked enhancement in concentration magnitudes is generated with increasing Schmidt number and there is also a morphing in profiles from the approximately linear case ($Sc = 0.22$) to the strongly parabolic case ($Sc = 2.0$).

Table 2 shows the variation in $-f''(0)$ i.e. primary skin friction, $-g''(0)$ i.e. secondary skin friction and $-\theta'(0)$ i.e. Nusselt number with several selected parameters i.e. A, M, K, α, n and R . Again, default values for the other parameters are as noted earlier. Primary skin friction is strongly reduced with increasing A values (Sisko material parameter) whereas secondary skin friction is weakly reduced and Nusselt number is slightly increased. With increasing magnetic parameter, M , the primary skin friction and secondary skin friction are elevated whereas the Nusselt number is weakly reduced. An increase in inverse permeability parameter, K , also enhances primary and secondary skin friction whereas it reduces Nusselt number. Increasing stretching ratio parameter (α) weakly reduces primary skin friction but strongly elevates secondary skin friction and slightly boosts the Nusselt number at the wall. Increasing Sisko power-law index (n) i.e. greater dilatant behavior is found to elevate primary skin friction and reduce secondary skin friction whereas it initially increases and thereafter reduces Nusselt number. Finally, increasing radiative parameter, R , exerts no tangible influence on either primary or secondary friction but strongly reduces the Nusselt number (since heat is transferred away from the wall into the body of the bi-directional stretching sheet flow leading to greater temperatures in the boundary layer).

5. CONCLUSIONS

A mathematical model has been presented for steady-state, laminar, incompressible, magnetohydrodynamic flow of an electrically conducting polymeric non-Newtonian (Sisko) fluid from a bidirectional stretching sheet in a porous medium is studied theoretically. Thermal radiation flux and homogeneous-heterogeneous chemical reactions are included. Darcy's model is employed for the porous medium and Rosseland's diffusion flux model for radiation heat transfer. Convective heating conditions at the wall are also considered. The transformed dimensionless nonlinear ordinary differential equation boundary value problem with transformed boundary conditions has been solved with the semi-analytical Adomian decomposition method (ADM). Validation with earlier studies has been included. A parametric study of the impact of selected parameters on transport characteristics has been conducted. The simulations have shown that:

- Increasing sheet stretching ratio weakly accelerates the primary flow throughout the boundary layer whereas it more dramatically accelerates the secondary flow near sheet surface.
- Increasing magnetic field and inverse permeability parameter decrease both the primary and secondary velocity magnitudes and also the primary and secondary friction values, whereas they increase temperatures in the regime and reduce Nusselt number.
- Temperature is consistently reduced with increasing stretching sheet ratio whereas Nusselt number at the wall is enhanced.
- Temperature is strongly enhanced with greater radiative parameter whereas Nusselt number is reduced and there is no noticeable effect on either primary or secondary friction.
- With greater Sisko non-Newtonian power-law index the primary velocity and temperature are decreased whereas the secondary velocity is increased.
- Increasing both homogenous and heterogenous chemical reaction parameters is found to weakly and more strongly, respectively, reduce concentration magnitudes whereas greater Schmidt number enhances the concentration values in the bi-directional sheet.
- Primary skin friction is strongly reduced with increasing A values (Sisko material parameter) whereas secondary skin friction is weakly reduced and Nusselt number is slightly increased.
- Increasing Sisko power-law index i.e. greater *dilatant non-Newtonian* behavior is found to elevate primary skin friction and reduce secondary skin friction whereas it initially increases and thereafter reduces Nusselt number.

The present study has shown that ADM is a powerful approach for studying multi-physical high-temperature bi-axial stretching reactive materials processing flows of electro-conductive (magnetic) polymers. Future studies will explore alternative radiative flux models and also unsteady effects and will be communicated imminently.

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APPENDIX:

The ADM power series expansions are

$$f(\eta) = \eta + \frac{\eta^2}{2} p + (T_1 + T_7)\eta^3 + (T_2 + T_8)\eta^4 + (T_3 + T_9)\eta^5 + T_{10}\eta^6 + T_{11}\eta^7 + T_{12}\eta^8$$

$$g(\eta) = \alpha\eta + \frac{\eta^2}{2} q + (T_4 + T_{13})\eta^3 + (T_5 + T_{14})\eta^4 + (T_6 + T_{15})\eta^5 + T_{16}\eta^6 + T_{17}\eta^7 + T_{18}\eta^8$$

$$\theta(\eta) = 1 + \frac{1}{\gamma} r + r\eta + (T_{19} + T_{22})\eta^2 + (T_{20} + T_{23})\eta^3 + (T_{21} + T_{24})\eta^4 + T_{25}\eta^5 \\ + T_{26}\eta^6 + T_{27}\eta^7 + T_{28}\eta^8 + T_{29}\eta^9 + T_{30}\eta^{10}$$

$$\phi(\eta) = \frac{1}{k_2} s + s\eta + (T_{31} + T_{35})\eta^2 + (T_{32} + T_{36})\eta^3 + (T_{33} + T_{37})\eta^4 + (T_{34} + T_{38})\eta^5 \\ + T_{39}\eta^6 + T_{40}\eta^7 + T_{41}\eta^8 + T_{42}\eta^9 + T_{43}\eta^{10} + T_{44}\eta^{11} + T_{45}\eta^{12}$$

The values of the notations T_i 's, $i = 1 - 45$ are presented below:

$$T_1 = \frac{1 + K + M^2}{6A}, T_2 = \left(-\frac{2n}{n+1} + 2p - \alpha p + Kp + M^2 p \right) / 24A, T_3 = \left(-\frac{2n}{n+1} p + p^2 - \frac{pq}{2} \right) / 6A,$$

$$T_4 = \frac{\alpha^2 + M^2 + K}{6A}, T_5 = \left(-\frac{2n}{n+1} + \alpha q + (M^2 + K)\alpha \right) / 24A, T_6 = \left(-\frac{2n}{n+1} q + \frac{q^2}{2} \right) / 60A,$$

$$T_4 = \frac{n p^{n-1}}{A} T_4, T_8 = \frac{n p^{n-1}}{A} T_5, T_9 = \left(-60 n p^{n-1} T_6 - \frac{12n}{n+1} T_1 + 6T_1 - 6\alpha T_1 + 3(K + M^2) T_1 \right) / 60A,$$

$$T_{10} = \left(-\frac{24n}{n+1} T_2 - \frac{6n}{n+1} T_1 p - \frac{2n}{n+1} T_1 + 8T_2 + 6T_1 p - 12\alpha T_2 + 3T_1 q + T_4 p + 4(K + M^2) T_2 \right) / 120A,$$

$$T_{11} = \left(-\frac{40n}{n+1} T_3 - \frac{12n}{n+1} T_2 p + 9T_2 p + 10T_3 - 20\alpha T_3 - 6T_2 q + T_5 p + 5(K + M^2) T_3 \right) / 210A,$$

$$T_{12} = \left(-\frac{22n}{n+1} T_3 p - 10T_3 p - 10T_3 q + T_6 p \right) / 336A, T_{13} = -\frac{p^{n-1}}{A} T_4, T_{14} = -\frac{p^{n-1}}{A} T_5,$$

$$T_{15} = \left(-60 p^{n-1} T_6 - \frac{12n}{n+1} T_4 - 12\alpha T_4 + 3(K + M^2) T_4 \right) / 60A,$$

$$T_{16} = \left(-\frac{24n}{n+1} T_5 - \frac{6n}{n+1} T_4 p - \frac{2n}{n+1} T_1 q - 4T_5 \alpha + 2T_4 q + 4(K + M^2) T_5 \right) / 120A,$$

$$T_{17} = \left(-\frac{40n}{n+1} T_6 - \frac{12n}{n+1} T_5 p - \frac{2n}{n+1} T_2 q - 10T_6 \alpha + 2T_5 q + 5(K + M^2) T_6 \right) / 210A,$$

$$T_{18} = \left(-\frac{20n}{n+1} T_6 p - \frac{2n}{n+1} T_5 p - \frac{2n}{n+1} T_3 q - T_6 q \right) / 336A, T_{19} = -\frac{3}{2} (\theta_w - 1) R r \left\{ 1 + (\theta_w - 1) \left(1 + \frac{r}{\gamma} \right) \right\},$$

$$T_{20} = \left[-6(\theta_w - 1) R r^2 \left\{ (\theta_w - 1) \left(1 + \frac{r}{\gamma} \right) + 1 \right\} - \frac{2n}{n+1} r \Pr - r \Pr \alpha \right] / 6,$$

$$T_{21} = \left[-3(\theta_w - 1)^3 R r^3 - \frac{n}{n+1} r \Pr p - 2r \Pr q \right] / 12,$$

$$T_{22} = \left[-2R \left(1 + (\theta_w - 1) \left(1 + \frac{r}{\gamma} \right) \right)^3 T_{19} - 6(\theta_w - 1) R \left(1 + (\theta_w - 1) \left(1 + \frac{r}{\gamma} \right) \right)^2 T_{19} - 3(\theta_w - 1) R r \right] / 2,$$

$$T_{23} = \left[-6R \left(1 + (\theta_w - 1) \left(1 + \frac{r}{\gamma} \right) \right)^3 T_{20} - 6R \left(1 + (\theta_w - 1) \left(1 + \frac{r}{\gamma} \right) \right)^2 r T_{19} - 6(\theta_w - 1) R \left(1 + (\theta_w - 1) \left(1 + \frac{r}{\gamma} \right) \right)^2 T_{19} \right] / 6,$$

$$T_{24} = \left[\begin{array}{l} -12R \left(1 + (\theta_w - 1) \left(1 + \frac{r}{\gamma} \right) \right)^3 T_{21} - 18R \left(1 + (\theta_w - 1) \left(1 + \frac{r}{\gamma} \right) \right)^2 r T_{20} \\ -3R \left(1 + (\theta_w - 1) \left(1 + \frac{r}{\gamma} \right) \right)^2 r^2 T_{19} - 9(\theta_w - 1) R \left(1 + (\theta_w - 1) \left(1 + \frac{r}{\gamma} \right) \right)^2 T_{20} \\ -12(\theta_w - 1) R \left(1 + (\theta_w - 1) \left(1 + \frac{r}{\gamma} \right) \right) r T_{19} - \frac{4n}{n+1} \Pr T_{19} - 2\alpha \Pr T_{19} \end{array} \right] / 12,$$

$$T_{25} = \left[\begin{array}{l} -36R \left(1 + (\theta_w - 1) \left(1 + \frac{r}{\gamma} \right) \right)^3 r T_{21} - 18R \left(1 + (\theta_w - 1) \left(1 + \frac{r}{\gamma} \right) \right)^2 r T_{20} - 2R r^3 T_{19} \\ -12(\theta_w - 1)R \left(1 + (\theta_w - 1) \left(1 + \frac{r}{\gamma} \right) \right)^2 T_{21} - 18(\theta_w - 1)R \left(1 + (\theta_w - 1) \left(1 + \frac{r}{\gamma} \right) \right) r T_{20} \\ -6(\theta_w - 1)R r^2 T_{19} - \frac{6n}{n+1} Pr T_{20} - \frac{2n}{n+1} Pr T_1 p - \frac{2n}{n+1} Pr T_{19} r - 3\alpha Pr T_{20} \\ -Pr p T_{19} - Pr r T_4 \end{array} \right] / 20,$$

$$T_{26} = \left[\begin{array}{l} -36R \left(1 + (\theta_w - 1) \left(1 + \frac{r}{\gamma} \right) \right) r^2 T_{21} - 18R r^3 T_{20} - 24(\theta_w - 1)R \left(1 + (\theta_w - 1) \left(1 + \frac{r}{\gamma} \right) \right) T_{21} \\ -9(\theta_w - 1)R r^2 T_{20} - 3(\theta_w - 1)^2 R r T_{19} - \frac{8n}{n+1} Pr T_{21} - \frac{3n}{n+1} Pr T_{20} - \frac{2n}{n+1} r Pr T_2 \\ -4\alpha Pr T_{21} - \frac{3}{2} Pr T_{20} - Pr r T_5 \end{array} \right] / 30,$$

$$T_{27} = \left[\begin{array}{l} -12R r^3 T_{21} - 12(\theta_w - 1)R r^2 T_{21} - 6(\theta_w - 1)^2 R T_{19} T_{20} - \frac{4n}{n+1} Pr T_{21} - \frac{2n}{n+1} r Pr T_3 \\ -2Pr T_{21} - r Pr T_6 \end{array} \right] / 42,$$

$$T_{28} = (-3(\theta_w - 1)^3 R r T_{20}^2) / 56, \quad T_{29} = (-6(\theta_w - 1)^2 R r T_{20} T_{21}) / 72, \quad T_{30} = (-3(\theta_w - 1)^3 R r T_{21}^2) / 90,$$

$$T_{31} = \frac{1}{2} Sc k_1 s^3 \frac{1}{k_2} \left(1 - \frac{1}{k_2} \right), \quad T_{32} = \left(-Sc \frac{2n}{n+1} s - Sc \alpha s + Sc k_1 s^3 \left(\left(1 - \frac{1}{k_2} \right) \left(1 - \frac{2}{k_2} \right) \right) \right) / 6,$$

$$T_{33} = \left(-Sc \frac{n}{n+1} p s - \frac{Sc q s}{2} + Sc k_1 s^3 \left(\frac{1}{k_2} - 2 \left(1 - \frac{2}{k_2} \right) \right) \right) / 12, \quad T_{34} = Sc k_1 s^3 / 20, \quad T_{35} = \frac{Sc k_1}{2k_1} s,$$

$$T_{36} = \left(-2Sc \frac{n}{n+1} + Sc k_1 s \right) / 6, \quad T_{37} = \left[-\frac{n}{n+1} Sc p - 2 Sc \alpha T_{31} + Sc k_1 T_{31} \left(1 - \frac{1}{k_2} s \right)^2 - Sc k_1 \frac{s}{k_2} T_{31} \right] / 12,$$

$$T_{38} = \left[Sc \frac{2n}{n+1} T_1 s - 3 Sc \alpha s T_{32} - Sc s T_{31} + Sc k_1 \left(T_{32} \left(1 - \frac{1}{k_2} s \right)^2 - T_{31} s^2 \right) + Sc k_1 \left(-\frac{s}{k_2} T_{32} - s T_{31} \right) \right] / 20,$$

$$T_{39} = \left[Sc \frac{2n}{n+1} T_2 s - 4 Sc s T_{33} - \frac{3}{2} Sc s T_{32} + Sc k_1 \left(T_{33} \left(1 - \frac{1}{k_2} s \right)^2 - T_{32} s^2 \right) + Sc k_1 \left(-\frac{s}{k_2} T_{33} - s T_{32} \right) \right] / 30,$$

$$T_{40} = \left[Sc \frac{2n}{n+1} T_3 s - 5 Sc s T_{34} - 2 Sc s T_{33} + Sc k_1 \left(T_{34} \left(1 - \frac{1}{k_2} s \right)^2 - T_{33} s^2 \right) + Sc k_1 \left(-\frac{s}{k_2} T_{34} - s T_{33} \right) \right] / 42,$$

$$T_{41} = \left[\frac{5}{2} Sc T_{34} s - 2 Sc k_1 T_{34} \left(1 - \frac{1}{k_2} s \right) s + Sc k_1 T_{33} s^2 - Sc k_1 s T_{34} \right] / 56,$$

$$T_{42} = \left[Sc k_1 T_{34} s^2 + Sc k_1 \left(2 \frac{1}{k_2} s T_{32} T_{33} + s T_{32}^2 \right) \right] / 72, \quad T_{43} = Sc k_1 \left(\frac{s}{k_2} T_{33}^2 + s T_{32} T_{34} \right) / 90,$$

$$T_{44} = Sc k_1 \left(2 T_{33} T_{34} \frac{s}{k_2} + s T_{33}^2 \right) / 110, \quad T_{45} = Sc k_1 \left(T_{34}^2 \frac{s}{k_2} + 2 s T_{33} T_{34} \right) / 132$$