

## **Response-Surface-Model-Based System Sizing for Nearly/Net Zero Energy Buildings under Uncertainty**

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### **Abstract**

Properly treating uncertainty is critical for robust system sizing of nearly/net zero energy buildings (ZEBs). To treat uncertainty, the conventional method conducts Monte Carlo simulations for thousands of possible design options, which inevitably leads to computation load that is heavy or even impossible to handle. In order to reduce the number of Monte Carlo simulations, this study proposes a response-surface-model-based system sizing method. The response surface models of design criteria (i.e., the annual energy match ratio, self-consumption ratio and initial investment) are established based on Monte Carlo simulations for 29 specific design points which are determined by Box-Behnken design. With the response surface models, the overall performances (i.e., the weighted performance of the design criteria) of all design options (i.e., sizing combinations of photovoltaic, wind turbine and electric storage) are evaluated, and the design option with the maximal overall performance is finally

selected. Cases studies with 1331 design options have validated the proposed method for 10,000 randomly produced decision scenarios (i.e., users' preferences to the design criteria). The results show that the established response surface models reasonably predict the design criteria with errors no greater than 3.5% at a cumulative probability of 95%. The proposed method reduces the number of Monte Carlo simulations by 97.8%, and robustly sorts out top 1.1% design options in expectation. With the largely reduced Monte Carlo simulations and high overall performance of the selected design option, the proposed method provides a practical and efficient means for system sizing of nearly/net ZEBs under uncertainty.

**Keywords:** Response surface model; Monte Carlo simulation; System sizing; Zero energy building; Uncertainty

## 1. Introduction

Nearly/net zero energy buildings (ZEBs) remain as promising solutions to the increasing energy and environment problems [1, 2]. Buildings account for about 40% primary energy and 24% CO<sub>2</sub> emission worldwide [3]. Nearly/net ZEBs are characterized by a high degree of energy autonomy [4, 5]. With reduced energy consumption by energy efficient technologies (e.g., ground source heat pumps [6, 7] and thermal driven cooling systems [8]), nearly/net ZEBs are configured with the renewable energy system to achieve a targeted annual energy match ratio (AEMR) [9, 10]. By definition, AEMR is the ratio of annual energy generation from the renewable energy system to annual energy consumption of buildings [11, 12]. AEMR of a net ZEB is targeted at 100%, and that of a nearly ZEB is allowed to be less than 100% but larger than the minimal value stipulated by the policy [13, 14].

When designing a nearly/net ZEB, it is challenging to properly size the renewable energy system with multiple and mutually contradictory design criteria [14, 15]. Design

optimization of the renewable energy system stands as one of the major concerns in the field of nearly/net ZEBs [14]. While an under-sized renewable energy system fails to fulfill the requirements on AEMR [16], an over-sized renewable energy system leads to an unnecessary increase in its initial investment. Meanwhile, a properly sized renewable energy system is supposed to minimize the grid stress caused by the energy interaction between the nearly/net ZEBs and grid [17, 18]. Due to the intermittent and fluctuant renewable energy generation and building energy consumption, nearly/net ZEBs dynamically export the surplus energy generation to the grid and import the complementary energy from the grid. To mitigate the grid stress, the renewable energy system is desired to be sized with a high self-consumption ratio (SCR) [18, 19]. SCR is the percentage of the annual renewable energy generation consumed directly by the nearly/net ZEBs [20, 21]. A smaller size of the renewable energy generation device could elevate SCR, but decrease AEMR, and a larger size of the renewable energy storage device could elevate SCR, but increase the initial investment.

Common methods size the renewable energy system for nearly/net ZEBs in a deterministic manner [22, 23]. Firstly, the building energy generation and consumption are estimated under the worst scenario or standard scenario with a safety factor [24]. Thus, the building energy generation is under-estimated and the building energy consumption is over-estimated. Secondly, the renewable energy system is sized based on the under-estimated building energy generation and over-estimated building energy consumption. As a result, the renewable energy system is commonly oversized, with unnecessarily high initial investment and a low SCR [24, 25]. On the other hand, the building energy generation and consumption are vulnerable to uncertainties associated with weather, building physical properties and etc. [26, 27]. Due to these uncertainties, the actual performance of a nearly/net ZEB sized from the deterministic methods could deviate significantly from the designed performance [28, 29]. For example, the real operation of an occupied ZEB in China was reported by Zhou et al [30] that the annual

energy consumption was larger than the designed value by 30.9% and the annual energy generation was smaller than the designed value by 36.8%. Attia et al. [31] comprehensively analyzed the present situations of seven European countries and pointed out that the treatment of uncertainty was a future challenge for the design of nearly/net ZEBs.

To address the problems above, the multi-criteria system sizing method for nearly/net ZEBs under uncertainty was proposed by Zhang et al. [16] and Sun et al. [29]. The multiple design criteria were weighted according to users' preference. Uncertainties in the physical, design and scenario parameters were treated with Monte Carlo simulations. An improvement of 44% in the overall performance by the optimization was reported [16]. This method was further improved by Yu et al. [32] to achieve a user-defined confidence level of the designed performance. Also, Lu et al. [15] quantified the actual performance of a nearly/net ZEB in different years under uncertainty with Monte Carlo simulations, and identified the relationship between the probability to achieve the actual performance and designed AEMR. These methods could comprehensively make trade-offs among the conflicting design criteria and harvest robust design. However, they faced a limitation of excessive computation load due to the large number of Monte Carlo simulations [33]. Monte Carlo simulations are the main technology used to treat uncertainty in the field of building energy [34, 35]. To achieve the robust design of nearly/net ZEBs, existing methods conducted Monte Carlos simulations for thousands of design options [15, 16, 29]. For instance, Lu et al. [15] repeated 500-years Monte Carlo simulations for 2457 different design options of the renewable energy system. That is, the annual energy consumption and generation simulations of the nearly/net ZEB were repeated by 1,228,500 times (i.e.,  $500 \times 2457$ ).

To reduce the number of Monte Carlo simulations for nearly/net ZEB design under uncertainty, this paper proposes a response-surface–model-based system sizing method. The response surface methodology is an easy-to-use meta-modeling technique, which

can identify the relationship between a design response and a set of design parameters based on a limited number of controlled experiments/simulations [36, 37]. The identified relationship (i.e., the response surface model) reveals the effects of the design parameters on the design response. So that the design parameters could be optimally determined to achieve the most desirable design response, requiring no more experiments/simulations. The response surface methodology has been applied to the building environment design for indoor air quality and thermal comfort, such as the design of natural ventilation [38, 39], underfloor air distribution [40], impinging jet ventilation [41] and other mechanical ventilation modes [42, 43]. The response surface methodology has also been employed to model the building energy consumption for improved energy efficiency, including passive retrofit optimization [44], window geometry optimization [45], exergy optimization of the cooling tower [46] and optimal control of the variable refrigerant flow system [47]). However, it is unknown whether the response surface methodology could function satisfactorily for nearly/net ZEBs, due to the increased complexities from interactions among the renewable energy system, building energy consumption system and grid [14]. Kneifel et al. [48] reported that it was challenging for the meta-models to accurately predict the energy performances of nearly/net ZEBs without considering the uncertainty. Moreover, uncertainty analysis also contributes to the complexities of nearly/net ZEB design [29], which further challenges the application of the response surface methodology.

In this study, the response surface methodology will be employed to identify the relationship between the size of the renewable energy system (including photovoltaic (PV), wind turbine (WT) and electric storages [16, 32]) and each design criterion (i.e., AEMR, SCR and initial investment [16]). With the response surface models, the overall performances (i.e., the weighted performance of AEMR, SCR and initial investment) of all the design options are calculated for decision making purposes. The establishment of the response surface models requires Monte Carlo simulations for only 29 specific

design points. As a consequence, the proposed method largely reduces the number of Monte Carlo simulations, when compared with the conventional method conducting Monte Carlo simulations for thousands of design options [16, 29].

With the largely reduced Monte Carlo simulations, the primary concern of the proposed response-surface-model-based system sizing method is that whether it can sort out the design option with high overall performance. This study first introduces and explains the proposed response-surface-model-based system sizing method for nearly/net ZEBs under uncertainty (Section 2). Case studies are then conducted to demonstrate the effectiveness and robustness of the proposed method in sorting out the design option with high overall performance (Section 3). The case studies consider 10,000 decision scenarios (i.e., users' preferences to the design criteria). The users' preferences in practice can significantly affect the overall performance of the finally selected design option [25]. Thus, different users' preferences should be taken into consideration to ensure the robustness of the proposed method. Lastly, several application issues of the proposed method are discussed in Section 4.

There are two main contributions of this study. (1) The response surface methodology is confirmed to work satisfactorily for the energy performances of nearly/net ZEBs. Compared with other meta-modeling techniques (e.g., the one used in Reference [48]), the response surface methodology can generate more accurate meta-models requiring fewer data due to the utilization of the methods of Design of Experiment [50]. The effectiveness of the response surface methodology needs to be tested for different applications. Many studies are focusing on testing the response surface methodology for a specific application (e.g., modeling the thermal environment of natural ventilation [39], displacement ventilation [40], impinging jet ventilation [41] and task/ambient air conditioning system [51]). This is the first time for the response surface methodology to be tested for the energy performances of nearly/net ZEBs. (2) This study proposes a method which can substantially reduce the number of Monte Carlo simulations and

robustly sort out the optimal design option. Existing methods [15, 16, 29] for the robust system sizing of nearly/net ZEBs conducted Monte Carlo simulations for thousands of design options, leading to computational load that is heavy or even impossible to handle for practical applications. The proposed method conducts Monte Carlo simulations only for 29 specific design points. Thus, this study provides a practical and efficient means for system sizing of nearly/net ZEBs under uncertainty.

## 2. Methodology

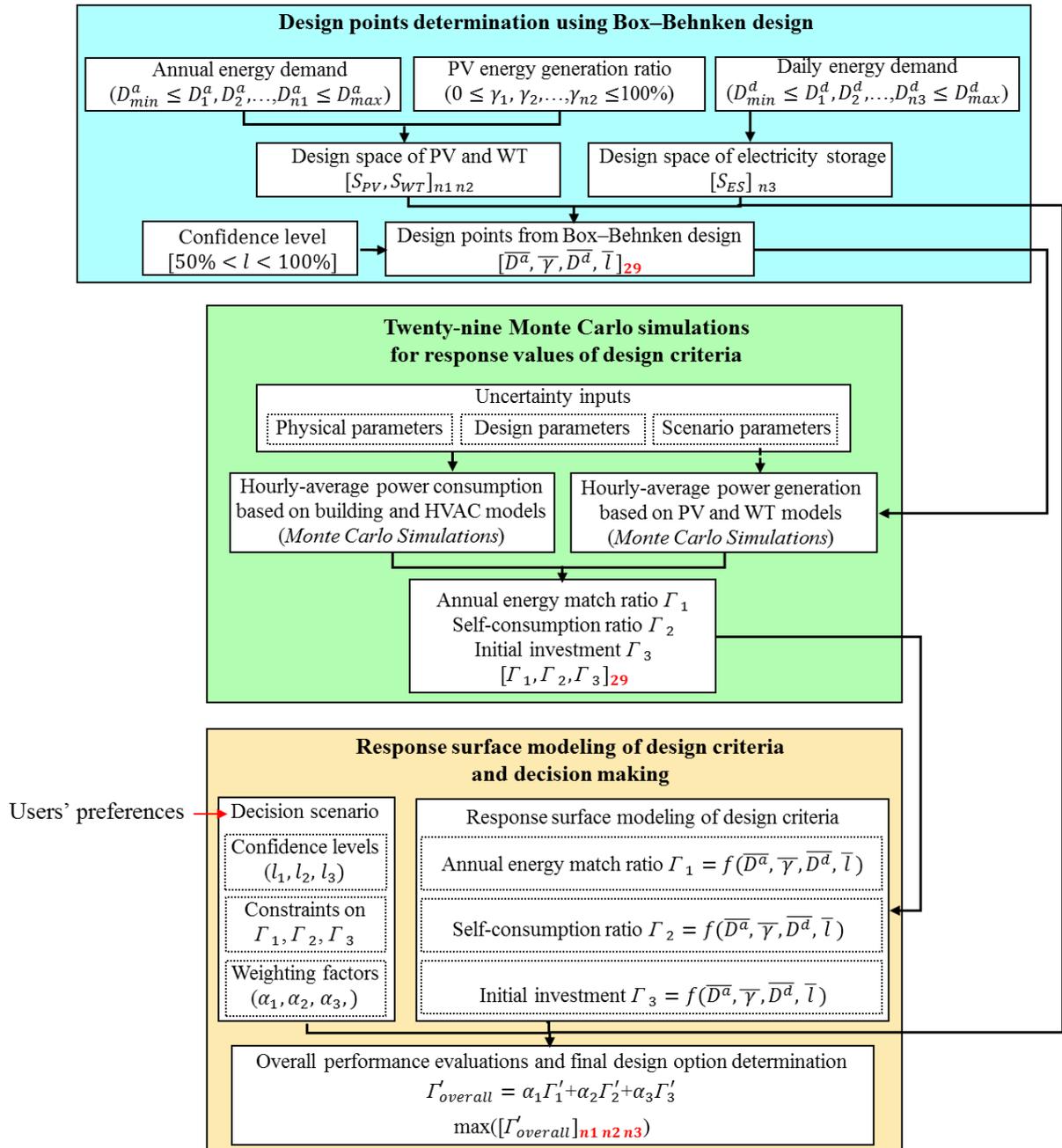
### *2.1 Overview of proposed response-surface-model-based system sizing method*

Figure 1 shows the proposed response-surface-model-based system sizing method for nearly/net ZEBs under uncertainty. It includes three main parts: (1) to determine the design points using Box-Behnken design; (2) to calculate the response values of each design criterion for the determined design points by running Monte Carlo simulations; and (3) to establish the response surface model for each design criterion based on the calculated response values, and to evaluate the overall performances of all design options for the decision making using the established response surface models.

The response surface model is a polynomial regression model representing the relationship between the design criteria and the design parameters (Equation 1 with second order) [36]. The coefficients ( $\beta_o$ ,  $\beta_p$ ,  $\beta_{pp}$  and  $\beta_{pq}$ ) in Equation 1 can be identified by the multiple regression technique. To increase the accuracy of the response surface models, the collinearity of the design points needs to be reduced. The collinearity can be reduced by increasing the orthogonality of the design points with Design of Experiment methods [39, 41]. As one of the most widely used Design of Experiment methods, Box-Behnken design is employed in this study [38, 46]. Design Expert software can be directly used to make the response surface modeling user-friendly [52].

$$y = \beta_o + \sum_{p=1}^k \beta_p x_p + \sum_{p=1}^k \beta_{pp} x_p^2 + \sum_{p=1}^k \sum_{q>p}^k \beta_{pq} x_p x_q \quad (1)[36]$$

where  $y$  is the response parameter (i.e., the design criterion) or the transformation of the response parameter (e.g., transformation of natural log and square root [52, 53]);  $\beta_o$ ,  $\beta_p$ ,  $\beta_{pp}$  and  $\beta_{pq}$  are the coefficients;  $x_p$  and  $x_q$  are the  $p^{th}$  and  $q^{th}$  design parameters respectively, and totally there are  $k$  different design parameters.



**Fig.1.** Schematic diagram of response-surface-model-based system sizing method for nearly/net ZEBs under uncertainty.

2.2 Design points determination using Box-Behnken design

Design points for establishing response models are selected from the design space and the allocated confidence levels. In this study, the renewable energy system consists of

PV and WT and electric storage [32]. Sizes of PV and WT are selected according to building annual energy demand ( $D^a$  kWh) and renewable energy generation percentage of PV ( $\gamma$  %) (Equations 2 and 3) [16]. The energy generation percentage of PV is defined as a ratio of the energy generated annually by PV to the annual energy generation of the building. Hence, the design space of PV and WT is determined by all combinations of the annual energy demand and energy generation percentage of PV (i.e.,  $n_1 \times n_2$  in Figure 1). The lower and upper limits of the annual energy demand ( $D_{min}^a$  kWh,  $D_{max}^a$  kWh) can be identified either based on the statistical characteristics of the annual energy demand (Equations 4 and 5) [42] or using the worst scenario method [16]. The electric storage is sized to achieve short-term grid independence (e.g., from several hours to days), and its size is suggested to be equivalent to one to three times of the daily energy demand [54-56]. In order to cover the recommended sizing range, the design space of the electric storage is set to from one half of the daily energy demand to four times of the daily energy demand. The confidence level ( $l$  %) means the cumulative probability to achieve the designed performance in a selected criterion. The confidence level is limited within 50~100%.

$$S_{PV} = \frac{\gamma D^a}{G_{PV}^a} \quad (2)[16]$$

$$S_{WT} = \frac{(1 - \gamma)D^a}{G_{WT}^a} \quad (3)[16]$$

where  $D^a$  (kWh) is the annual energy demand of the nearly/net ZEB;  $G_{PV}^a$  (kWh/m<sup>2</sup>) and  $G_{WT}^a$  (kWh/kW) are the annual energy generation from PV of one square meter and WT with a rated power of one kilowatt respectively;  $\gamma$  (%) is the energy generation percentage of PV;  $S_{PV}$  (m<sup>2</sup>) and  $S_{WT}$  (kW) are the area of PV and rated power of WT respectively.

$$D_{max}^a = \mu_{D^a} + c\sigma_{D^a} \quad (4)[42]$$

$$D_{min}^a = \mu_{D^a} - c\sigma_{D^a} \quad (5)[42]$$

where  $D_{min}^a$  (kWh) and  $D_{max}^a$  (kWh) are the minimal and maximal values of the annual energy demand of a nearly/net ZEB respectively;  $\mu_{D^a}$  (kWh) and  $\sigma_{D^a}$  (kWh)

are the mean value and standard deviation of the annual energy demand distribution respectively;  $c$  is a constant.

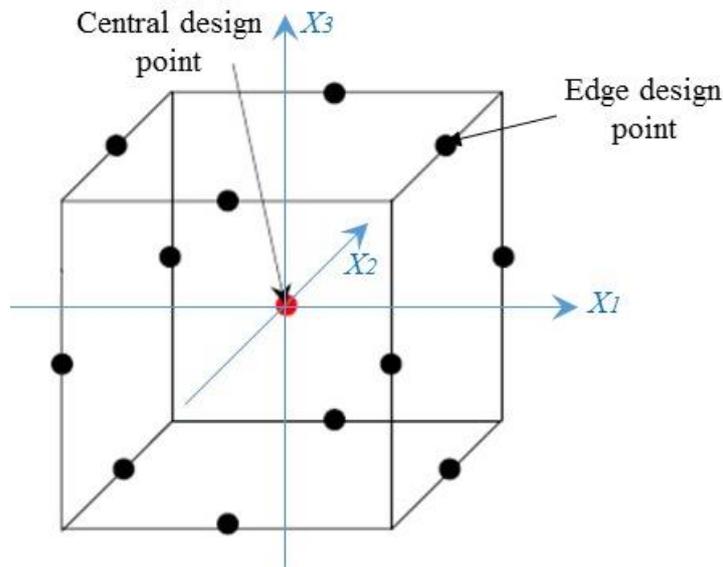
To determine the design points, the Box-Behnken design is used. First, all design parameters are coded into -1~1 (Equation 6), and three levels for each design parameter are defined: -1 for low level, 0 for medium level and 1 for high level. Then, Box-Behnken design determines the design points in a way to avoid extreme design conditions where all the design parameters are at high/low levels simultaneously. For instance, Figure 2 shows the geometry of Box-Behnken design with three design parameters ( $X_1$ ,  $X_2$  and  $X_3$ ) [41]. The design points are selected at each edge and the central point rather than the corners, because the corners represent extreme conditions. The number of design points using Box-Behnken design is determined by the number of design parameters and repetitive number of the central design point (Equation 7). The central design point is repeated to account for errors caused by the experiments/simulations [36].

$$\bar{x} = \frac{2(x - x_{min})}{x_{max} - x_{min}} - 1 \quad (6)[52]$$

where  $\bar{x}$  is the coded value (i.e., normalized value) of the design parameter;  $x$  is the original value of the design parameter;  $x_{min}$  and  $x_{max}$  are the minimal and maximal original values of the design parameter.

$$N = 2k(k - 1) + C \quad (7)[52]$$

where  $C$  is the repetitive number of the central design point;  $k$  is the number of the design parameters; and  $N$  is the number of the design points determined by Box-Behnken design.



**Fig.2.** Demonstration of design point determination using Box-Behnken design: geometry of design points with three design parameters.

### 2.3 Monte Carlo simulations for response values of design criteria

The response values of the design criteria for the design points from Box-Behnken design (Section 2.2) are calculated based on 400-year Monte Carlo simulations [16]. Monte Carlo simulations are employed to produce the hourly building energy generation and consumption, as three types of input parameter uncertainties are considered (Table 1). Physical parameters refer to physical properties of building materials. Design parameters refer to pre-set working conditions during the planning process. Scenario parameters refer to real-time operations [57]. The scenario parameters of wind velocity and solar radiation are the primary sources of uncertainty for WT energy generation and PV energy generation respectively [59]. Wind velocity and solar radiation are quantified to follow Rayleigh distribution [60] (simplified from Weibull distribution [61]) and normal distribution [62] respectively. Parameter uncertainties associated with the building energy consumption are quantified using statistical distributions as presented in Table 1. Truncation and rounding are conducted to make the parameters from the statistical distributions realistic [29]. Since Monte

Carlo simulations have been widely used to treat the uncertainty for the robust design of buildings [33], the detailed process of Monte Carlo simulations are not given in this study but can be found in References [16, 29].

**Table 1.** Parameter-uncertainty distributions affecting building energy consumption.

Uncertainty type	Parameter	Distribution type	Base value	Distribution
Physical parameters [29, 63, 64]	U value of window (kJ/(hm <sup>2</sup> K))	Normal distribution	8.17	N (8.17, 0.4 <sup>2</sup> )
	Internal shading coefficient	Normal distribution	0.5	N(0.5, 0.1 <sup>2</sup> )
	External shading coefficient	Normal distribution	0.2	N(0.2, 0.05 <sup>2</sup> )
	Internal conductive heat transfer rate (kJ/(hm <sup>2</sup> K))	Normal distribution	11	N(11, 0.5 <sup>2</sup> )
	External conductive heat transfer rate (kJ/(hm <sup>2</sup> K))	Triangular distribution	68.4	T(43.2, 68.4, 82.8)
Design parameters [29, 64, 65]	Occupant number	Normal distribution	16	N (16, 2 <sup>2</sup> )
	Computer number	Normal distribution	16	N (16, 3 <sup>2</sup> )
	Light ratio	Normal distribution	1	N (1, 0.2 <sup>2</sup> )
	Infiltration (ACH)	Normal distribution	0.2	N (0.2, 0.05 <sup>2</sup> )
	Ventilation (ACH)	Normal distribution	10	N (10, 0.5 <sup>2</sup> )
Scenario parameters [29, 66, 67]	Ambient temperature (°C)	Normal distribution	TMY	N (TMY, 0.01TMY <sup>2</sup> )
	Ambient relative humidity (%)	Normal distribution	TMY	N (TMY, 0.01TMY <sup>2</sup> )

*Note: ACH is air change per hour [25]; TMY represents hourly data from the typical meteorology year; the base values are from Reference [29].*

The design criteria of nearly/net ZEBs include AEMR, SCR and initial investment of the renewable energy system [11, 16]. Equations 8 and 9 describe the calculations of

AEMR and SCR of the  $j^{th}$  year from the hourly building energy generation and consumption respectively. A confidence level is used to describe the cumulative probability of achieving the designed performance in a selected criterion during the 400-year Monte Carlo simulations. For instance, an AEMR with a value of  $AEMR_l$  and a confidence level of  $l$  means that the cumulative probability for AEMR of 400-year Monte Carlo simulations to be larger than the value of  $AEMR_l$  is  $l$  (Figure 3). The initial investment is calculated by Equation 10 [32].

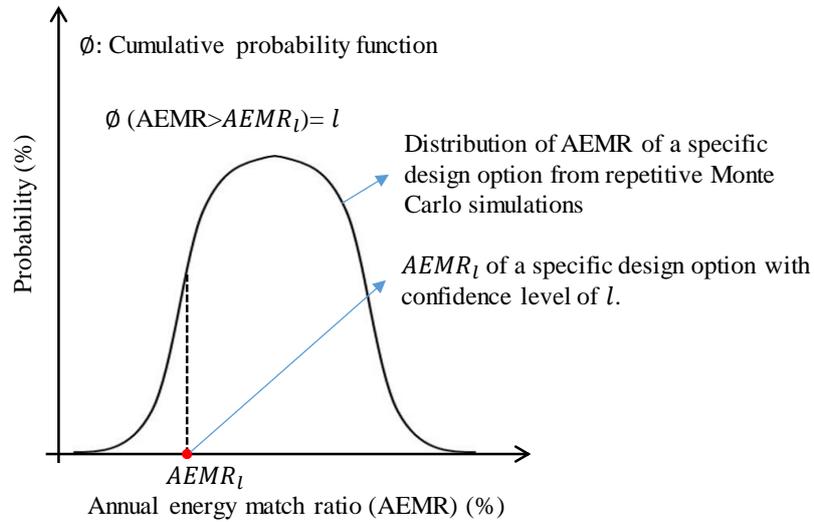
$$AEMR_j = \frac{\sum_{i=8760(j-1)+1}^{8760j} (POW_{PV,ij} + POW_{WT,ij})}{\sum_{i=8760(j-1)+1}^{8760j} POW_{con,ij}} \times 100\% \quad (8)[16]$$

$$SCR_j = \frac{\sum_{i=8760(j-1)+1}^{8760j} (POW_{PV,ij} + POW_{WT,ij} - \Delta ES_{ij} - EI_{ij})}{\sum_{i=8760(j-1)+1}^{8760j} (POW_{PV,ij} + POW_{WT,ij})} \times 100\% \quad (9)[21]$$

where  $AEMR$  (%) is the annual energy match ratio;  $EI$  ( $kW$ ) is the energy exporting to the grid ( $EI > 0$ );  $POW_{PV}$  ( $kW$ ) and  $POW_{WT}$  ( $kW$ ) are the hourly-average power generation from installed PV and WT respectively;  $SCR$  (%) is the self-consumption ratio;  $\Delta ES$  ( $kW$ ) is the variation of stored electricity in the electric storage, and larger than zero when the stored electricity increases; subscripts  $i$  and  $j$  are  $i^{th}$  hour and  $j^{th}$  year respectively.

$$II = \rho_{PV} S_{PV} + \rho_{WT} S_{WT} + \rho_{ES} S_{ES} \quad (10)[32]$$

where  $II$  ( $HKD$ ) is the initial investment of the renewable energy system;  $S_{ES}$  ( $kWh$ ),  $S_{PV}$  ( $m^2$ ) and  $S_{WT}$  ( $kW$ ) are the capacity of the electric storage, area of PV and rated power of WT respectively;  $\rho_{ES}$  ( $HKD/kWh$ ),  $\rho_{PV}$  ( $HKD/m^2$ ) and  $\rho_{WT}$  ( $HKD/kW$ ) are the unit price of the electric storage, PV and WT respectively.



**Fig.3.** Usage demonstration of confidence level: AEMR determination with a specific confidence level.

#### 2.4 Response surface modeling of design criteria and decision making

Response surface models of AEMR and SCR (Equation 1) are established based on the determined design points (Section 2.2) and corresponding response values from Monte Carlo simulations (Section 2.3). The least square method is used to identify the coefficients in Equation 1 for AEMR and SCR, and the backward elimination procedure is used to enhance the data fit by reducing insignificant terms [39, 68]. Firstly, a full model including all terms in Equation 1 is established by multiple regression analysis with the least square method. Then, the partial probability values (P-value) of included terms are estimated by ANOVA (i.e., Analysis of Variance) tests. Lastly, the terms with P-values higher than 0.05 (indicating statistically insignificant terms) are removed. The quality of the response surface models can be evaluated by comparison with Monte Carlo simulations for the design points which are not involved in the model establishment [36]. The initial investment is assumed to be determined by the size of the renewable energy system [32]. Thus the response surface model of the initial investment is the same as Equation 10.

The response-surface-model-based decision making is as follows. Firstly, for all design options of the renewable energy system from the design space (i.e.,  $n_1 \times n_2 \times n_3$  in Figure 1), the values of AEMR ( $\Gamma_1$ ), SCR ( $\Gamma_2$ ) and initial investment ( $\Gamma_3$ ) are calculated using the obtained response surface models and user-defined confidence levels. Secondly, the user-defined constraints (i.e., lower/upper limits) on each design criterion are used to exclude the design options failing to meet the constraints, by determining the corresponding overall performance as zero. Thirdly, values of design criteria of the remaining design options are normalized as Equation 11, and the overall performances are evaluated with user-defined weighting factors (Equation 12) [16, 69]. Lastly, the design option with the maximal overall performance is selected as the optimal one.

$$\Gamma' = \frac{\Gamma - \Gamma_{least}}{\Gamma_{most} - \Gamma_{least}} \times 100\% \quad (11)[16]$$

where  $\Gamma'$  is the normalized value of a design criterion;  $\Gamma$  is the value of a design criterion;  $\Gamma_{least}$  and  $\Gamma_{most}$  are the worst and best performance respectively.

$$\Gamma'_{overall} = \alpha_1 \Gamma'_1 + \alpha_2 \Gamma'_2 + \alpha_3 \Gamma'_3 \quad (12)[16]$$

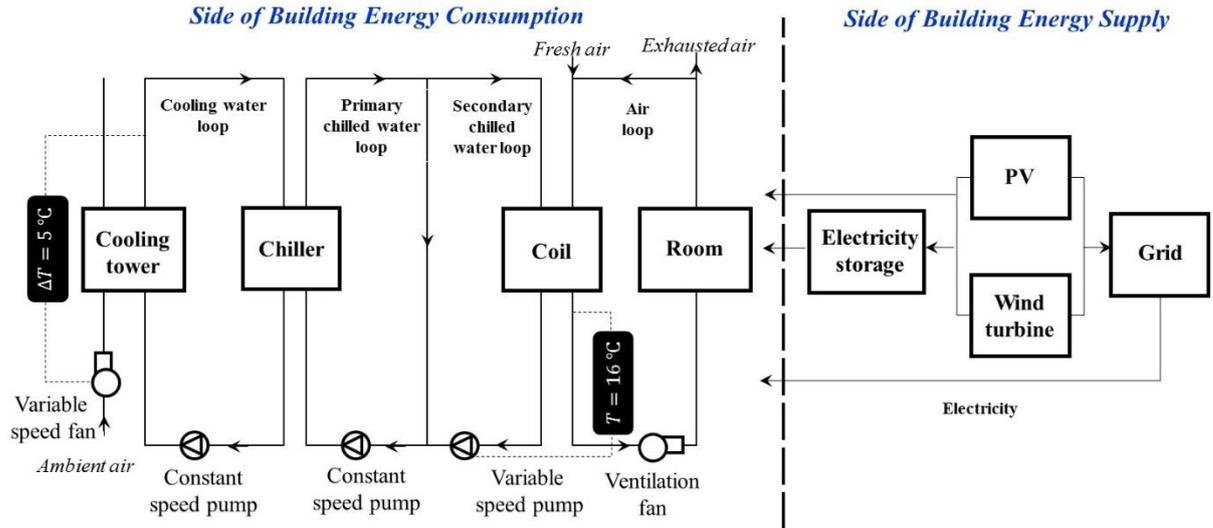
where  $\Gamma'_{overall}$  is the overall performance of a specific design option;  $\Gamma'_1$ ,  $\Gamma'_2$  and  $\Gamma'_3$  are the normalized value of AEMR, SCR and initial investment respectively;  $\alpha_1$ ,  $\alpha_2$  and  $\alpha_3$  are the weighting factors assigned to AEMR, SCR, and initial investment respectively, and their sum is one.

### 3. Case studies

#### 3.1 Simulation models of the nearly/net ZEB

TRNSYS [70] is used to establish the simulation platform for a nearly/net ZEB (Figure 4). This simulation platform has been used for several studies of the design of nearly/net ZEBs [16, 29, 32]. Here, for readability, the simulation models are briefly described as follows, and more detailed descriptions are given by References [16, 29, 32]. The nearly/net ZEB is a ten-storey academic building (Type 56) located in subtropical Hong Kong. Each storey is configured with two identical classrooms (7.6 m  $\times$  6 m  $\times$  3 m). One room has one west-facing window of 4 m  $\times$  1.5 m, and is equipped with 16

computers with a nominal power of 140 W of each, and eight halogen lights with a rated power of 55 W/m<sup>2</sup> of each. Sixteen occupants stay in the room from 6 am to 10 pm. To provide a satisfactory indoor environment, the room temperature and relative humidity are set at 25°C and 50% respectively [71, 72]. The infiltration rate is assumed to be 0.2 ACH. Other main parameters of the building model are listed in Table 1.



**Fig.4.** Schematic diagram of the nearly/net ZEB [16, 29, 32].

The hourly-average power generation from PV (Type 562) and WT (Type 90) are estimated by Equations 13 and 14 respectively [70]. Key parameters of PV and WT models are summarized in Table 2.

$$Pow_{PV} = S_{pv} \times \tau_n \times \alpha_n \times (IAM) \times I_T \times \eta \quad (13)[29]$$

where  $IAM$  is the overall incidence angle modifier;  $I_T$  ( $kW/m^2$ ) is the solar radiation;  $Pow_{PV}$  ( $kW$ ) is the hourly-average power generation from the installed PV;  $S_{pv}$  ( $m^2$ ) is the PV area;  $\alpha_n$  and  $\tau_n$  are the absorptance coefficient and transmittance coefficient respectively of the solar radiation normal to PV; and  $\eta$  is the overall efficiency of PV.

$$Pow_{WT} = S_{WT} \times C_p \times \rho \times A_R \times v^3 \quad (14)[29]$$

where  $A_R$  ( $m^2$ ) is the rotor area;  $C_p$  ( $m^2/s^2$ ) is the function of the axial induction factor;  $Pow_{WT}$  ( $kW$ ) is the hourly-average power generation from the installed WT;

$S_{WT}$  is the rated power of WT;  $\rho$  ( $kg/m^3$ ) is the air density; and  $v$  ( $m/s$ ) is the free stream wind speed.

**Table 2.** Key parameters used in TRNSYS for PV and WT [16, 29, 70].

Renewable energy	Parameter	Value	Unit
PV (Type 562)	Back resistance	1	$hm^2K/kJ$
	Top emissivity	0.9	-
	Back emissivity	0.9	-
	Absorptance	0.9	—
	Refractive index	1.526	—
	Cover conductivity	5.04	$kJ/(hmK)$
	Cover thickness	0.00635	m
	Extinction coefficient	4	$m^{-1}$
WT (Type 90)	Site elevation	0	m
	Data collection height	30	m
	Turbine power loss	15	%
	Rated power	20	kW

The electric storage is operated as follows (Equations 15 to 18 [32]). The surplus energy generation is first stored in the electric storage. After the energy storage is fully charged, the rest electricity is exported to the grid. Conversely, the insufficient energy generation is first complemented by the stored electricity. After the energy storage is fully discharged, the rest energy is imported from the grid.

$$\Delta ES_i = \begin{cases} \min(S_{ES} - ES_{store,i}, POW_{mis}) & \text{if } POW_{mis} \geq 0 \\ \max(-ES_{store,i}, POW_{mis}) & \text{if } POW_{mis} < 0 \end{cases} \quad (15)[32]$$

$$ES_{store,i} = \sum_{n=1}^{i-1} \Delta ES_n \quad (16)[32]$$

$$Pow_{mis} = Pow_{PV,i} + Pow_{WT,i} - Pow_{con,i} \quad (17)[32]$$

$$EI_i = Pow_{mis} - \Delta ES_i \quad (18)[32]$$

where  $EI$  ( $kW$ ) is the energy interaction between the nearly/net ZEB and grid, and an  $EI$  larger than zero means exporting energy;  $ES_{store}$  ( $kWh$ ) is the electricity stored;  $Pow_{con}$  is the building hourly-average power consumption;  $Pow_{mis}$  ( $kW$ ) is the mismatch between the building hourly-average power generation and consumption, and a  $Pow_{mis}$  larger than zero means the energy generation is surplus;  $Pow_{PV}$  ( $kW$ ) and  $Pow_{WT}$  ( $kW$ ) are the building hourly-average power generation from installed PV and WT respectively;  $S_{ES}$  ( $kWh$ ) is the capacity of the electric storage;  $\Delta ES$  ( $kW$ ) is the variation of stored electricity, and a  $\Delta ES$  larger than zero means charging electricity; subscripts  $i$  and  $n$  are the  $i^{th}$  and  $n^{th}$  hour respectively.

Energy consumption components of the HVAC system mainly include a water-cooled chiller (Equation 19), pumps of the cooling water loop and primary and secondary chilled water loops (Equation 20) and fans used in the cooling tower and for room ventilation (Equation 21) [70]. Key parameters of the HVAC model are summarized in Table 3, which are the optimal design results for the studied building from Reference [25].

$$Pow_{con,chi} = \frac{FFLP \times Q_c}{COP_{nom}} \quad (19)[70]$$

where  $COP_{nom}$  is the nominal COP of chiller;  $FFLP$  is the fraction of full load power [25];  $Pow_{con,chi}$  ( $kW$ ) is the hourly-average power consumption of chiller;  $Q_c$  ( $kW$ ) is the cooling capacity of chiller.

$$Pow_{con,pum} = \frac{\dot{m}_{wat} \times \Delta P_{wat}}{\eta_{pum} \times \rho_{wat}} \quad (20)[25]$$

where  $Pow_{con,pum}$  ( $kW$ ) is the hourly-average power consumption of pumps;  $\dot{m}_{wat}$  ( $kg/s$ ) is the water flow rate;  $\eta_{pum}$  is the pump efficiency;  $\rho_{wat}$  ( $kg/m^3$ ) is the water density;  $\Delta P_{wat}$  ( $Pa$ ) is the pressure drop of water flow.

$$Pow_{con,fan} = \frac{\dot{m}_{air} \times \Delta P_{air}}{\eta_{fan} \times \rho_{air}} \quad (21)[25]$$

where  $Pow_{con,fan}$  (kW) is the hourly-average power consumption of fans;  $\dot{m}_{air}$  (kg/s) is the air flow rate;  $\eta_{fan}$  is the fan efficiency;  $\rho_{air}$  (kg/m<sup>3</sup>) is the air density;  $\Delta P_{air}$  (Pa) is the pressure drop of air flow.

**Table 3.** Key parameters used in TRNSYS for HVAC model [25, 70].

Components	Parameter	Value	Unit
Chiller (Type 666)	Rated capacity	195.91	kW
	Rated COP	5.02	-
	CHW set point temperature	7	°C
Variable speed Pump (Type 741)	Rated flow rate	33200	kg/hr
	Overall pump efficiency	0.6	-
	Motor efficiency	0.9	-
Constant speed Pump (Type 742)	Inlet fluid flow rate	33200	kg/hr
	Overall pump efficiency	0.6	-
	Motor efficiency	0.9	-
	Pressure drop	100	kPa
Cooling tower (Type 510)	Rated fan power	18450	kJ/hr
	Design fluid flow rate	55300	kg/hr
	Design air flow rate	42600	kg/hr
	Design inlet fluid temperature	32	°C
	Design outlet fluid temperature	29	°C
	Design ambient air temperature	35	°C
	Design wet bulb temperature	25	°C
Ventilation fan (Type 744)	Rated power	7800	kJ/hr
	Rated flow rate	77100	kg/hr
	Inlet air humidity	50%	-

### 3.2 Determination of design points

Using the ZEB model (Section 3.1), the maximal and minimal annual energy demands are determined as 283,313 *kWh* and 263,516 *kWh* respectively (calculated from Equations 4 and 5 with 3 times of the standard deviation respectively). The annual energy generation from PV of one square meter and WT of one kilowatt rated power are 151 *kWh* and 569 *kWh* respectively (calculated in a manner similar to Equation 5). The daily energy demand is 1793 *kWh* (calculated in a manner similar to Equation 4), and thus the minimal and maximal sizes of the electric storage are set to be 897 *kWh* and 7172 *kWh* respectively. The design points determined by Box-Behnken design are presented in Table 4. The central design point is repeated for five times as the default in Design Expert 8.0. There are totally 29 design points (Equation 7).

**Table 4.** Design points from Box-Behnken design and corresponding sizes of PV, WT and electric storage and confidence level.

Design points	$\overline{D^a}$ (coded)	$\overline{\gamma}$ (coded)	$\overline{D^d}$ (coded)	$\overline{l}$ (coded)	PV ( $m^2$ )	WT ( <i>kW</i> )	Electric storage ( <i>kWh</i> )	Confidence level (%)
1	0	0	0	0	904	240	4034	75
2	1	-1	0	0	0	498	4034	75
3	0	1	1	0	1809	0	7172	75
4	0	0	-1	1	904	240	897	100
5	0	-1	0	1	0	481	4034	100
6	0	-1	0	-1	0	481	4034	50
7	0	0	0	0	904	240	4034	75
8	1	0	0	-1	937	249	4034	50
9	0	-1	-1	0	0	481	897	75
10	0	0	1	1	904	240	7172	100
11	-1	0	1	0	872	232	7172	75
12	0	0	0	0	904	240	4034	75
13	1	0	1	0	937	249	7172	75
14	-1	1	0	0	1743	0	4034	75
15	1	0	-1	0	937	249	897	75

16	0	1	-1	0	1809	0	897	75
17	0	1	0	-1	1809	0	4034	50
18	-1	0	0	-1	872	232	4034	50
19	1	1	0	0	1874	0	4034	75
20	-1	0	0	1	872	232	4034	100
21	-1	0	-1	0	872	232	897	75
22	-1	-1	0	0	0	463	4034	75
23	0	-1	1	0	0	481	7172	75
24	0	0	1	-1	904	240	7172	50
25	1	0	0	1	937	249	4034	100
26	0	1	0	1	1809	0	4034	100
27	0	0	-1	-1	904	240	897	50
28	0	0	0	0	904	240	4034	75
29	0	0	0	0	904	240	4034	75

Note:  $\overline{D^a}$  is the coded annual energy demand (Equation 6);  $\overline{\gamma}$  is the coded energy generation percentage of PV;  $\overline{D^d}$  is the coded daily energy demand;  $\overline{l}$  is the coded confidence level.

### 3.3 Development and validation of response surface models

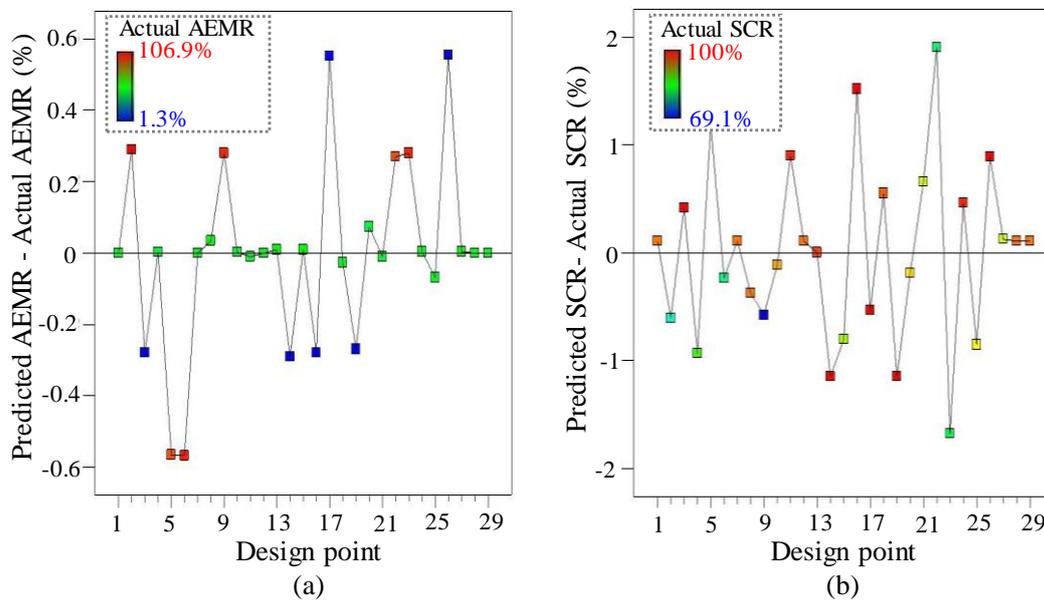
Equation 22 shows the response surface model of AEMR. The p-values of AEMR model and its terms are less than 0.0001, indicating that they are statistically significant. The predicted  $R^2$  of 0.9998 is in reasonable agreement with the adjusted  $R^2$  of 0.9999. The actual AEMR of the 29 design points runs from 1.3% to 106.9% (Figure 5(a)), which is calculated from Monte Carlo simulations (Section 2.3). The lower AEMR is produced when the energy is generated mainly by PV (i.e.,  $\gamma = 100\%$ ) and the required confidence level is high (e.g.,  $l = 100\%$ ), due to the more intermittent and uncertain energy generation of PV compared with WT [16]. The deviation between the AEMR predicted by Equation 22 and the actual one is within  $-0.6\% \sim 0.6\%$ . The mean absolute deviation is 0.16%. Equation 23 gives the response surface model of SCR. The p-values of SCR model and its terms are less than 0.039, indicating that they are statistically significant. The predicted  $R^2$  of 0.9693 is also in reasonable agreement with the adjusted  $R^2$  of 0.9869. The actual SCR of the 29 design points runs from 69.1% to 100% (Figure 5(b)), which is calculated by Monte Carlo simulations (Section 2.3). The smaller variation range of SCR compared with that of AEMR demonstrates the

effectiveness of the electric storage for mitigating the imbalance between the building energy generation and consumption. The deviation between SCR predicted by Equation 23 and the actual one is within -2.0%~2.0%. The mean absolute deviation is 0.63%.

$$AEMR=1.88\overline{D^a}-50.65\overline{\gamma}-1.40\overline{l}-1.84\overline{D^a}\overline{\gamma}+1.38\overline{\gamma}\overline{l}-0.84\overline{l}^2+52.25 \quad (22)$$

$$SCR=11.10\overline{\gamma}+3.87\overline{D^a}-1.79\overline{l}-3.32\overline{\gamma}\overline{D^a}+1.08\overline{\gamma}\overline{l}-6.19\overline{\gamma}^2-2.12\overline{D^a}^2-1.33\overline{l}^2+96.24 \quad (23)$$

where  $AEMR$  (%) is the annual energy match ratio;  $SCR$  (%) is the self-consumption ratio;  $\overline{D^a}$  is the coded annual energy demand;  $\overline{D^d}$  is the coded daily energy demand;  $\overline{l}$  is the coded confidence level;  $\overline{\gamma}$  is the coded energy generation percentage of PV.



Note: The 29 design points are used for establishment of response surface models.

**Fig.5.** Deviations between values predicted by response surface models and actual values calculated by Monte Carlo simulations: (a) Annual energy match ratio (AEMR) and (b) self-consumption ratio (SCR).

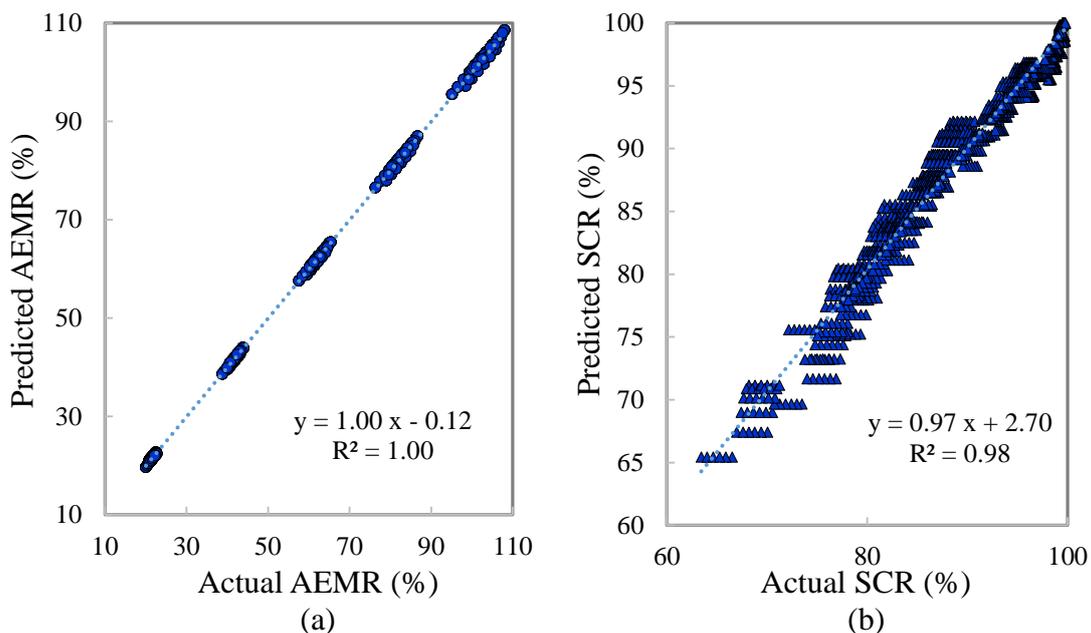
The response surface models are validated further by compared with the actual results of design points independent from the model establishment. 1296 different design points are selected (i.e., 1296 combinations of six different annual energy demands, six different energy generation percentages of PV, six different daily energy demands and six different confidence levels). The six annual energy demands ( $\overline{D^a}$  kWh) increase from the minimal annual energy demand (i.e.,  $D_{min}^a$  kWh) to the maximal one (i.e.,

$D_{max}^a$  kWh) with an equal interval of 20%. So do the six energy generation percentages of PV ( $\bar{\gamma}$  %), six daily energy demands ( $\bar{D}^d$  kWh) and six confidence levels ( $\bar{l}$  %). The 1296 design points are filtered that AEMR and SCR should be larger than 20% and 50% respectively, and 1080 design points remain. An excessively small AEMR is far beyond the requirements of a nearly/net ZEB and an excessively small SCR led to heavy grid stress [1, 19].

Figure 6 shows that both the predicted AEMR and SCR of the 1080 design points are almost of the diagonal function of  $y = x$  with the actual values. This indicates that the predicted values of AEMR and SCR from the response surface models are quite close to the actual values. Moreover, Figure 7 shows the histogram and cumulative probability of the discrepancy between the predicted and actual values (Equation 24). The absolute discrepancy of AEMR is less than 1.5% with a cumulative probability of 95%. The expected value of the absolute discrepancy is 0.6%. With regards to SCR, the absolute discrepancy is less than 3.5% with a cumulative probability of 95%, and is 1.2% in expectation. Therefore, the response surface models of AEMR and SCR are credible.

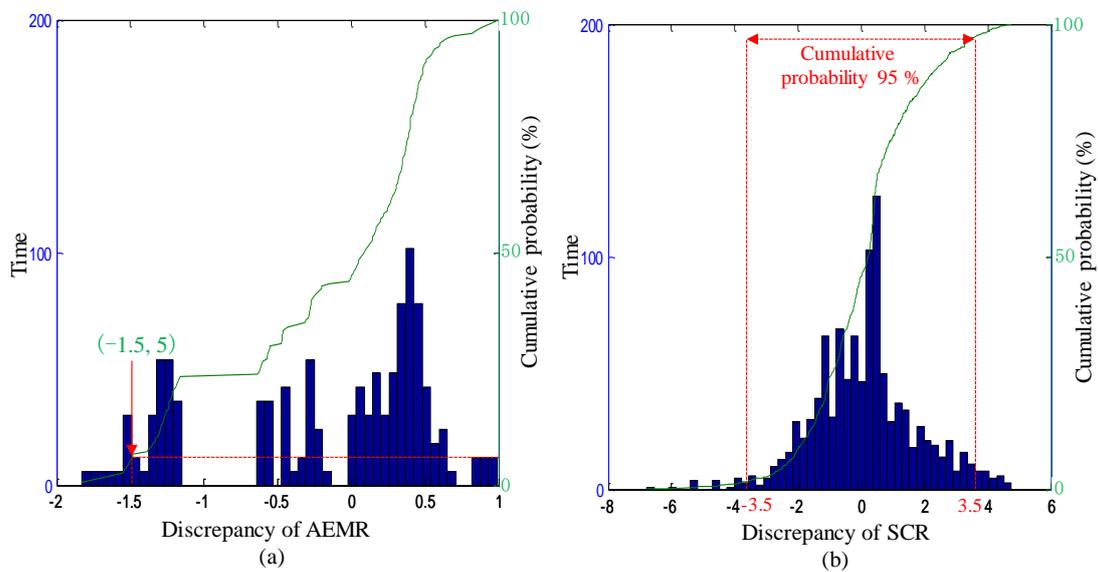
$$\text{Discrepancy} = \frac{\text{predicted value} - \text{actual value}}{\text{actual value}} \times 100\% \quad (24)[8]$$

where *predicted value* is from the proposed method; *actual value* is calculated by Monte Carlo simulations.



*Note: The included 1080 design points are not involved in the establishment of the response surface models.*

**Fig.6.** Comparisons between values predicted by response surface models and actual values calculated by Monte Carlo simulations: (a) Annual energy match ratio (AEMR) and (b) self-consumption ratio (SCR).



*Note: The included 1080 design points are not involved in the establishment of the response surface models; the discrepancy is calculated by Equation 24.*

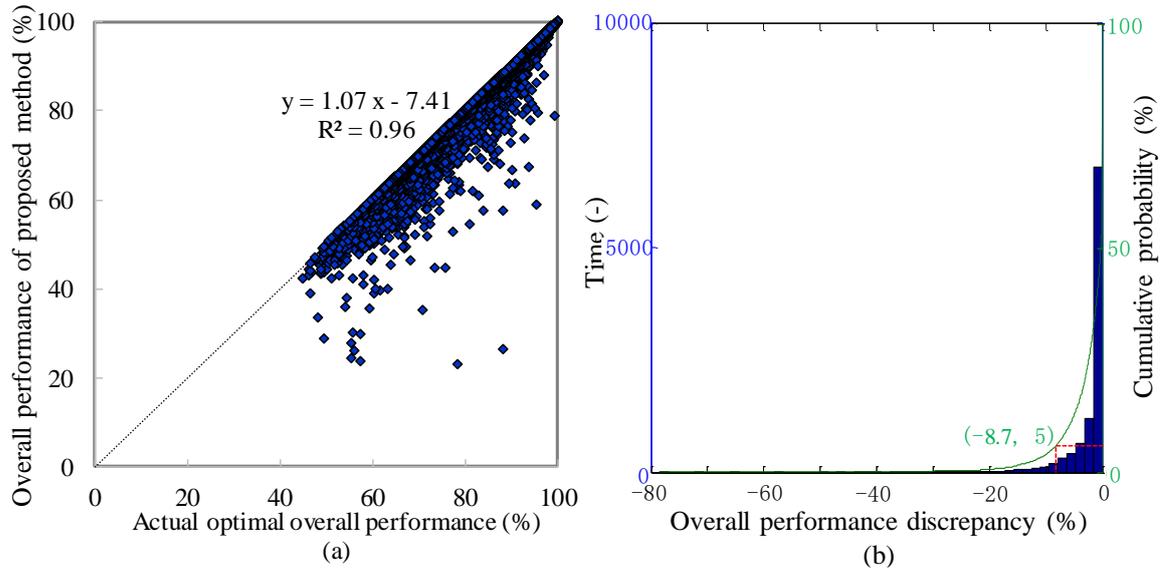
**Fig.7.** Histogram and cumulative probability of discrepancy between values predicted by response surface models and actual values calculated by Monte Carlo simulations: (a) Annual energy match ratio (AEMR) and (b) self-consumption ratio (SCR).

### 3.4 Validation of proposed method for system sizing

Due to the discrepancies between the predicted AEMR and SCR by the response surface models and the actual values calculated by Monte Carlo simulations (Figures 5-7), the overall performances of the design options calculated by the proposed method might deviate from the actual overall performances calculated by Monte Carlo simulations.

As a result, the proposed method might not sort out the optimal design option. The overall performance (Equation 12) of the selected design option by the proposed method and that of the optimal design option are firstly compared. 1331 different design options are considered (11 different sizes of PV, WT and the electric storage respectively with an equal interval of 10% from the minimal value to the maximal value, i.e.,  $n_1 = n_2 = n_3 = 11$  in Figure 1). Therefore, compared with conducting Monte Carlo simulations for all design options, the proposed method reduces the number of Monte Carlo simulations by 97.8% (from 1331 to 29).

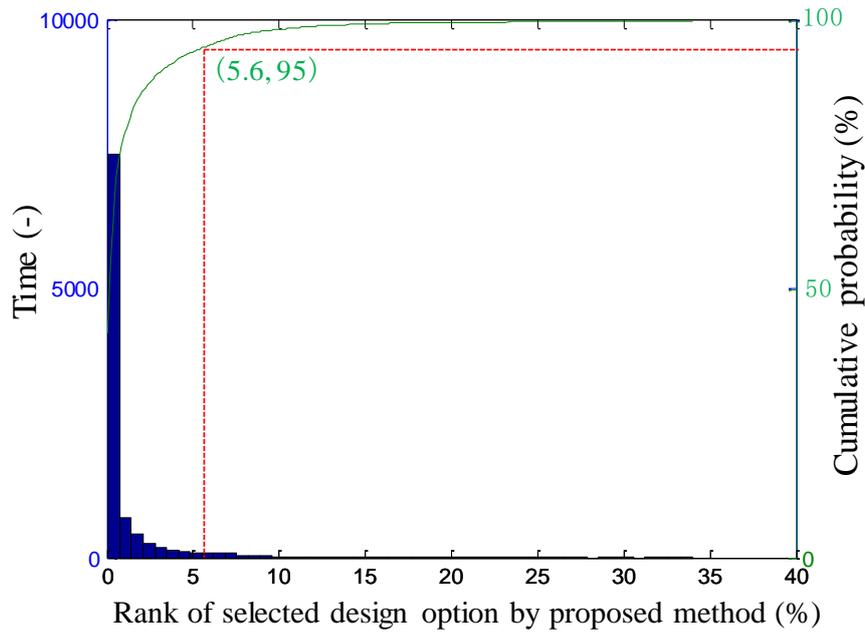
10,000 different decision scenarios are included. That is, 10,000 different combinations of users' preferences towards the confidence levels, constraints and weighting factors of AEMR, SCR and initial investment. The users' preferences are randomly produced with a uniform distribution. The confidence levels are limited within 50%~100% considering the robustness of the selected design option [15, 32]. The constraints are that AEMR is larger than 50%~100% [15] and SCR is larger than 60%~80% [17, 19]. For all the 10,000 decision scenarios, the overall performance of the selected design option by the proposed method is quite similar to that of the optimal design option, with almost a diagonal function of  $y = x$  between them (Figure 8(a)). This can be explained by the credible response surface models (Section 3.3). Figure 8(b) shows that the discrepancy of overall performances (Equation 24) between the selected design option by the proposed method and the optimal design option is -2.0% in expectation, and larger than -8.7% with a cumulative probability of 95%. In other words, the overall performance of the proposed method is slightly deteriorated by 2.0% in expectation, and the overall performance deterioration is less than 8.7% with a cumulative probability of 95%.



Note: Overall performance discrepancy is the calculated by Equation 24, and 10,000 different decision scenarios are considered.

**Fig.8.** (a) Comparisons of overall performances and (b) histogram and cumulative probability of overall performance discrepancy: Design option selected by proposed method and actual optimal design option.

The rank of selected design option by the proposed method among the 1331 different design options is further investigated for the 10,000 different decision scenarios (Figure 9). Rank 0% indicates that the selected design option by the proposed method is the best one among the 1331 design options. It is seen that the proposed method can sort out top 1.1% design option in expectation, and top 5.6% design option with a cumulative probability of 95%. Therefore, the proposed method largely reduces the number of Monte Carlo simulations by 97.8% (from 1331 to 29), and robustly sorts out the optimal design option in the statistical sense.



*Note: Rank 0% indicates that the selected design option by the proposed method is the best one among the 1331 design options, and 10,000 different decision scenarios are considered.*

**Fig.9.** Rank of design option selected by proposed method.

#### 4. Discussion

This study also supports the usage of the proposed method for sizing the energy consumption system (e.g., HVAC [32]) for nearly/net ZEBs. The proposed method could accurately predict AEMR and SCR based on the building energy generation and consumption (Section 3.3), indicating that the proposed method could accurately predict the building energy consumption. The accurately predicted building energy consumption could be used as the basis for sizing the energy consumption system [73]. Moreover, the proposed method is applicable not only to nearly/net ZEBs which are connected to the grid, but also to standalone ZEBs which are off-grid (e.g., in remote areas without access to the grid) [4]. For standalone ZEBs, the constraints on AEMR and SCR are both set to 100% (Figure 1), so that the buildings could generate sufficient energy for the annual energy consumption and all the generated energy is consumed by

the buildings without import/export of energy from/to the grid.

The overall performance of the proposed method could be enhanced further by improving the accuracy of response surface models. The accuracy of the response surface models could be increased by optimizing the Design of Experiment methods. In this study, only Box-Behnken design is considered. There are many other methods for Design of Experiment, e.g., central composite design and spacing filling design [39, 74]. Optimizing the Design of Experiment methods could optimally determine the design points to obtain response surface models with the highest accuracy [39]. The performance of Design of Experiment methods may vary among research areas [36], and the optimal Design of Experiment method for ZEBs needs to be identified in future.

In real applications, the detailed processes of the proposed method should be followed (Section 3). It is noted that the design criteria considered in this study are the most widely used ones for nearly/net ZEBs, but other design criteria might be included (e.g., embodied energy balance and CO<sub>2</sub> emission balance regarding the life cycle performance [4, 75]). Furthermore, the statistical distributions of parameters in Table 1 can be replaced by the specific data of the real application if available. The parameter uncertainties included in this study cover most of those significantly affecting the building energy generation and consumption [16, 25, 29, 56-67], but more parameter uncertainties (e.g., capacity degradation and cooling loss of HVAC [76]) can also be incorporated if they are of particular concerns in the future applications.

## **5. Conclusions**

This study proposes a response-surface-model-based system sizing method for nearly/net ZEBs under uncertainty. Firstly, response surface models of the design criteria are established based on Monte Carlo simulations for 29 design points. The design criteria include AEMR, SCR and initial investment, and the 29 design points are

determined by Box-Behnken design. Secondly, using the established response surface models, the overall performances (i.e., the weighted performance of design criteria) of all design options are evaluated. Finally, the design option with the maximal overall performance is selected as the optimal one. Without the proposed method, Monte Carlo simulations are required for thousands of possible design options to identify the optimal design option, which leads to computational load that is heavy or even impossible to handle in practice. Thus, the proposed method can substantially reduce the number of Monte Carlo simulations.

Cases studies on the sizing of PV, WT and electricity storage for a nearly/net ZEB show that the established response surface models of AEMR and SCR are fairly close to the actual values calculated by Monte Carlo simulations. The errors in the predicted AEMR and SCR by the response surface models are 0.6% and 1.2% in expectation respectively. The validated response surface models are used to evaluate the overall performances of 1331 design options of PV, WT and electric storage under 10,000 decision scenarios (i.e., users' preferences to the confidence levels, constraints and weighting factors of AEMR, SCR and initial investment). The proposed method significantly reduces the Monte Carlo simulations by 97.8%, and robustly sorts out top 5.6% design option with a cumulative probability of 95% and top 1.1% design option in expectation.

With the significantly reduced Monte Carlo simulations and high rank of the selected design option, the proposed method provides system designers a practical and efficient means for system sizing of nearly/net ZEBs under uncertainty.

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