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NUMERICAL STUDY OF HEAT SOURCE/SINK EFFECTS ON DISSIPATIVE MAGNETIC NANOFLUID FLOW FROM A NON-LINEAR INCLINED STRETCHING/SHRINKING SHEET

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Abstract: This paper numerically investigates radiative magnetohydrodynamic mixed convection boundary layer flow of nanofluids over a nonlinear inclined stretching/shrinking sheet in the presence of heat source/sink and viscous dissipation. The Rosseland approximation is adopted for thermal radiation effects and the Maxwell-Garnetts and Brinkman models are used for the effective thermal conductivity and dynamic viscosity of the nanofluids respectively. The governing coupled nonlinear momentum and thermal boundary layer equations are rendered into a system of ordinary differential equations via local similarity transformations with appropriate boundary conditions. The non-dimensional, nonlinear, well-posed boundary value problem is then solved with the Keller box implicit finite difference scheme. The emerging thermo-physical dimensionless parameters governing the flow are the magnetic field parameter, volume fraction parameter, power-law stretching parameter, Richardson number, suction/injection parameter, Eckert number and heat source/sink parameter. A detailed study of the influence of these parameters on velocity and temperature distributions is conducted. Additionally the evolution of skin friction coefficient and Nusselt number values with selected parameters is presented. Verification of numerical solutions is achieved via benchmarking with some limiting cases documented in previously reported results, and generally very good correlation is demonstrated. This investigation is relevant to fabrication of magnetic nanomaterials and high temperature treatment of magnetic nano-polymers.

Keywords: Keller-Box Method; Non-linear Stretching/Shrinking Sheet; Heat Source/Sink; Nanofluid; power-law stretching parameter; magnetic nanomaterials processing.

1. INTRODUCTION

Nanofluids constitute a subsection of molecular liquids designed to operate at the nanoscale. The rapid growth of nanotechnology has witnessed a significant interest in such

fluids across the entire breadth of engineering, including aerospace, manufacturing, energy technologies and medical industries. It is well-known that the term nanofluid was introduced by Choi [1] in 1995, to describe a fluid comprising solid nanoparticles with size typically of 1to 100 nm suspended in a liquid. Common base fluids are water, ethylene glycol, oil and lubricants. Nanoparticles which include aluminium, copper, silver and titanium metals with/without their oxides are of great scientific interest as they are effectively a bridge between bulk materials and molecular structures. The thermal conductivity of the nanoparticles is high as compared to the conventional fluids, as verified in experimental studies conducted by Eastman et al. [2] and Xuan and Lin [3] shown that with a small volumetric fraction of nanoparticles (typically less than 5%), the thermal conductivity of the base fluid is enhanced by 10-20%. Recently Selimefendigil and Oztop [4] reported that 14.11 % of averaged heat transfer enhancement is obtained when both cavities are filled with nanofluids at the highest value of nanoparticle volume fractions. Therefore, these nanofluids are capable of promoting energy efficiency, improving thermal conductivity and thermal properties of heat transport of base fluid. Nanofluids have therefore found significant applications in diverse areas including rocket fuels, cooling of nuclear reactors, manufacturing of nanopolymer sheets, bath cooling of a metallic plates and wires, glass fabrication etc. Recently many interesting studies have been reported by various researchers which includes Power law fluids in a cavity (Selimefendigil and Oztop [5]), Oldroyd-B fluids (Hayat et al. [6]), Maxwell fluids (Abbasi and Shehzad [7]), nanofluid filled in lid driven square enclosure with a rotating cylinder (Selimefendigil and Oztop [8]), Squeezing nanofluid flows (Hayat et al. [9]), Ferrofluid flow in a partially heated square enclosures (Selimefendigil and Oztop [10]) .In certain polymeric processing operations, materials are stretched or contracted at high temperature through slits under various thermal conditions to modify the properties. Mathematical modelling of such processes provides an important compliment to experimental laboratory investigations. Numerical analysis of viscous flow and heat transfer over a nonlinearly stretching sheet has been conducted for a Newtonian fluid by Cortell [11] with various thermal boundary conditions using a Runge-Kutta (RK) algorithm. Rana et al. [12] employed a finite element method to simulate two-dimensional non-Newtonian nanofluid stretching sheet flow from a slit with viscous heating and deformation effects. Furthermore numerous reviews on thermal enhancing properties of nanofluids have been addressed in [13-15].

Magnetohydrodynamic (MHD) viscous incompressible flow of electrically conducting fluid also features in an extensive range of technologies including magnetic materials processing, heat transfer control, purification of crude oil, Hall generators etc. In such flows a Lorentzian magnetic body force is generated transverse to the direction of the applied magnetic field which is instrumental in regulating high temperature plasmas, energy flux and also damping oscillations. Magnetic nanofluids are colloidal suspensions containing magnetizable nanoparticles which possess magnetic, fluid and thermal properties. Fourth order R-K method based shooting technique has been employed by Freidoonimehr et al. [16] to solve the differential equations describing the unsteady MHD free convection flow in a nanofluid past a permeable accelerating stretching vertical surface in the form of assisting flow. Makinde et al. [17] studied the combined effects of buoyancy force and convective on MHD stagnation point nanofluid flow from a vertically heating heated stretching/shrinking sheet as well as Makinde et al. [18] also studied MHD flow of variable viscosity nanofluid over radially stretching convective surface. Selimefendigil and Oztop [19-21] adopted FEM to investigate the influence of inclined magnetic field under different geometries which includes backward facing step, cavity with oscillating lid and isothermal cylinders portioned with a conductive ring respectively. As well as influence of inclined

magnetic field imposed to upper and lower triangular domains by Selimefendigil *et al.* [22]. Hayat *et al.* [23] used a homotopy method to analyze the three-dimensional hydromagnetic viscous flow of nanofluid subject to convective surface boundary conditions. Abolbashari *et al.* [24] employed HAM to study the entropy analysis in an unsteady magneto hydrodynamic nanofluid regime adjacent to an accelerating stretching permeable surface with the water as the base fluid. The analytical solution for two dimensional MHD mixed convection viscoelastic fluid flow over a porous wedge with thermal radiation is investigated by Rashidi *et al.* [25] by adopting HAM. Heat and Mass Transfer of a steady MHD convective and Slip flow due to a rotating disk with viscous dissipation and Ohmic heating reported by Rashidi and Erfani [26] by adopting DTM with Pade approximation. Very recently MHD nanofluid flow in stretching/shrinking convergent / divergent channel with Duan-Rach Approach (DRA) by Dogonchi and Ganji [27], buoyancy flow and heat transfer of MHD flow with KKL (Koo- Kleinstreuer -Li) effective thermal conductivity and viscosity correlation model by Dogonchi and Ganji [28].

As elaborated earlier, transport phenomena from a stretching/shrinking sheet have attracted many researchers owing to the relevance of this type of flow to materials processing operations including extrusion of polymer sheets, annealing of copper sheets in metallurgy etc. The pioneering work in this area was presented by Sakiadis [29-30]. Crane [31] extended the Sakiadis model to study the forced convection flow from a stretching sheet in a viscous incompressible fluid. Goldstein [32] elaborated that the shrinking flow is essentially a backward flow and the mass suction is needed to maintain the flow. It is worth mentioning here that the stretching sheet velocity formulation need not necessarily be a linear one. In polymeric extrusion processes nonlinear stretching is common. Gupta and Gupta [33] further verified that the stretching of the sheet is not necessarily linear for heat and mass transfer problems in the presence of suction/blowing. Motivated by emerging applications of nanopolymers, Hamad and Ferdows [34] reported similarity solutions for viscous flow and heat transfer of nanofluid over a non-linearly stretching sheet with an assumption that the stretching velocity and transverse magnetic field is varied as a power function of the distance from the origin. They observed that behavior of the fluid flow changes with the type of nanoparticles type and furthermore also considered stagnation point, porous medium, internal heat generation and suction effects. Nonlinearity in the stretching sheet process has been addressed with quadratic (power-law) and also exponential models. Akyildiz and Siginer [35] obtained Galerkin-Legendre spectral solutions for thermal boundary layer flow over a nonlinear stretching sheet with a power-law stretching model. Stagnation point flow over a permeable stretching/shrinking sheet in a copper-water nanofluid was investigated by Bachok et al. [36]. Steady state two-dimensional stagnation-point flow of a water based nanofluid over an exponentially stretching/shrinking sheet was investigated with a computational shooting method by Bachok et al. [37]. They observed that the similarity solution for the steady stagnation-point flow over an exponentially stretching/shrinking sheet is larger than compared with the linear stretching/shrinking sheet case solution. Rana and Bhargava [38] investigated laminar boundary layer fluid flow which results from the non-linear stretching of flat surface in a nanofluid with a finite element method.

Heat generation/ absorption effects arise in many thermo fluid processes including cooling of electronic equipment, hot spot/sink modification of polymer manufacture, cooling/heating of plastic products etc. Thermal radiation heat transfer also arises in high temperature materials synthesis. Selimefendigil and Oztop [39] reported that the elastic modulus of the side walls can be used to control the fluid flow and heat transfer inside the cavity and cylindrical nano particles gives the best performance in terms of heat transfer enhancement. Khan *et al.* [40] investigated non-aligned magnetized stagnation point flow of variable viscosity nanofluids

from a stretching sheet with radiative heat flux effects. Very recently Selimefendigil and Oztop [41] reported that as the value of the elastic modulus of the inclined wall and nanoparticle volume fraction increase, local and average heat transfer enhances. Gorla and Gireesha [42] presented dual solutions for stagnation point flow and heat transfer of Williamson viscoelastic nanofluids from a stretching/shrinking sheet under convective boundary conditions, showing that thermal boundary layer thickness increases with Williamson parameter (viscoelastic effect). Khan *et al.* [43] studied three-dimensional flow of nanofluid over a non-linearly stretching sheet with radiative flux effects. Selimefendigil and Oztop [44] reported that the local and averaged heat transfer enhances as the value of the solid volume fraction of the nanoparticle increases and this more effective for higher values of Richardson number.

Although significant studies have been reported of magnetic, radiative and nanofluid flows from horizontal stretching/contracting sheets, relatively sparse attention has been afforded to inclined stretching/contracting sheet magnetized nanofluid flows in the presence of a heat source/sink. Therefore, the objective of present investigation is to extend the work reported by Hamad and Ferdows [34] and Pal *et al.* [45] by considering heat source/sink effects in addition to viscous dissipation for two different water based Newtonian nanofluids in transport from an inclined non-linear stretching/shrinking sheet. An implicit finite difference scheme due to Keller [46] has been adopted for solving the coupled non-linear ordinary differential equation system emerging. Extensive details of the mathematical formation of the problem, numerical method of solution, grid independence study and validation are presented. The effects of various governing physical parameters on velocity and temperature profiles are discussed via figures and tables in section 5. Finally, a summary of noteworthy results are presented in section 6. The current simulations are relevant to electromagnetic nanofluid materials processing under high temperature.

2. MATHEMATICAL FORMULATION OF THE MODEL

Consider the steady, two-dimensional, laminar, incompressible, magnetohydrodynamic dissipative flow of an electrically-conducting nanofluid from an inclined stretching or shrinking sheet, orientated at an angle, α ($0^0 \le \alpha \le 90^0$) to the vertical. The physical model is illustrated in Fig. 1



Fig. 1. Flow configuration and coordinate system

The stretching of the sheet, which physically represents a nano polymer, is induced by applying two equal and opposite forces simultaneously along the x-axis. By keeping the origin fixed, the sheet is stretched with nonlinear velocity $u_w(x) = cx^n$, where c is a constant and n is a nonlinear stretching parameter. The x-axis is directed along the continuous stretching/shrinking sheet and the y-axis is measured normal to the x-axis. It is assumed that flow takes place for $y \ge 0$ and the temperature at the stretching/shrinking sheet takes a constant value $T_w > 0$ while the temperature of the ambient nanofluid takes the constant value T_{∞} as $y \rightarrow \infty$. The inclination angles $0^0,90^0$ and $0^0 < \alpha < 90^0$ represent the vertical, horizontal and general inclined stretching (or shrinking) sheet respectively. A non-uniform magnetic field of strength $B(x) = B_o x^{(m-1)/2}$ is applied in the transverse direction, where B_o is constant related to magnetic field and $m(\neq -1)$ is a power law exponent. Furthermore, the base fluid and the nanoparticles are in thermal equilibrium and no-slip occurs between them. Under these aforementioned assumptions the continuity, momentum and energy equations following [45], in the presence of thermal radiation, magnetic field, viscous dissipation and heat generation/absorption for the mixed convection flow can be shown to take the form:

Continuity equation $\frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} = 0$ Momentum equation

(1)

$$u\frac{\partial u}{\partial x} + v\frac{\partial u}{\partial y} = \frac{\mu_{nf}}{\rho_{nf}}\frac{\partial^2 u}{\partial y^2} + \frac{(\rho\beta)_{nf}}{\rho_{nf}}g(T - T_{\infty})\cos(\alpha) - \frac{\sigma_{nf}B^2(x)}{\rho_{nf}}u$$
(2)

Energy equation.

$$u\frac{\partial T}{\partial x} + v\frac{\partial T}{\partial y} = \frac{\mu_{nf}}{\rho_{nf}}\frac{\partial^2 T}{\partial y^2} + \frac{1}{(\rho c_p)_{nf}}\frac{\partial q_r}{\partial y} + \frac{\mu_{nf}}{(\rho c_p)_{nf}}\left(\frac{\partial u}{\partial y}\right)^2 + \frac{Q_0}{(\rho c_p)_{nf}}(T_w - T_\infty)$$
(3)

The following boundary conditions are imposed at the stretching/shrinking sheet and in the freestream:

$$at y = 0; \qquad \begin{cases} u_w(x) = \pm cx^n \\ v = v_w \\ T = T_w(x) = T_\infty + bx^n \\ T = T_\infty \end{cases}$$
(4)
$$as y \to \infty \qquad \begin{cases} u \to 0 \\ T = T_\infty \end{cases}$$

Here u and v are the velocity components along the x- axis and y-axis directions respectively and c is a constant for which c > 0 corresponds to the stretching sheet and c < 0 for the shrinking sheet, T is the temperature of the nanofluid, g is the acceleration due to gravity, v_w is the wall mass flux with $v_w < 0$ for suction and $v_w > 0$ for injection respectively. Furthermore, μ_{nf} is the coefficient of dynamic viscosity of the nanofluid, β_{nf} is the thermal expansion coefficient of the nanofluid, α_{nf} is the thermal diffusivity of the nanofluid, ρ_{nf} is the effective density of the nanofluid, and $(\rho c_p)_{nf}$ is the heat capacitance of the nanofluid which are defined as follows:

$$\alpha_{nf} = \frac{k_{nf}}{(\rho c_p)_{nf}}, \ \mu_{nf} = \frac{\mu_f}{(1-\phi)^{2.5}}, \ \rho_{nf} = (1-\phi)\rho_f + \phi\rho_s, \ (\rho\beta)_{nf} = (1-\phi)(\rho\beta)_f + \phi(\rho\beta)_s, (\rho c_p)_{nf} = (1-\phi)(\rho c_p)_f + \phi(\rho c_p)_s, \\ \frac{k_{nf}}{k_f} = \frac{(k_s + 2k_f) - 2\phi(k_f - k_s)}{(k_s + 2k_f) + 2\phi(k_f - k_s)}.$$

In the open literature different correlations exist for the electrical conductivity of nanofluids. Correlations which are functions of particle size, temperature and solid particle volume fractions were also developed. Very recently, Selimefendigil and Oztop ([21]) utilized Maxwell's electrical conductivity model which is used to calculate the effective electrical conductivity of a random suspension of spherical nanoparticles. In this study, the electrical conductivity of the nanofluid is a linear interpolation of base fluid and nanoparticle volume fraction is utilized and is given by:

$$(\sigma)_{nf} = (1 - \phi)(\sigma)_f + \phi(\sigma)_s \tag{5}$$

Where ϕ is the solid volume fraction of the nanofluid, ρ_f is the reference density of the fluid fraction, ρ_s is the reference density of the solid fraction, μ_f is the viscosity of the fluid fraction, β_f thermal expansion coefficient of the fluid, β_s is the thermal expansion coefficient of the nanoparticles, k_s is the thermal conductivity of the solid fraction, k_f is the electrical conductivity of the fluid and k_{nf} is the thermal conductivity of the nano fluid. With an assumption for the optically thick boundary layer we adopt Rosseland's diffusion approximation for the radiative heat flux q_r as given by $q_r = -\frac{4\sigma^*}{3k^*}\frac{\partial T^4}{\partial y}$, where σ^* is the Stephen-Boltzmann constant and k^* is the Rosseland mean absorption coefficient. The term T^4 due to radiation can be expressed as a linear function of temperature itself. Therefore, T^4 can be approximated by Taylor's series about T_{∞} after neglecting the higher order terms as $T^4 = 4T_{\infty}^3 T - 3T_{\infty}^4$. Therefore via substituting $\frac{\partial q_r}{\partial y} = -\frac{16\sigma^* T_{\infty}^3}{3k^*}\frac{\partial^2 T}{\partial y^2}$ in the energy conservation Eq. (3) the following form of the equation emerges:

$$u\frac{\partial T}{\partial x} + v\frac{\partial T}{\partial y} = \frac{\mu_{nf}}{\rho_{nf}}\frac{\partial^2 T}{\partial y^2} + \frac{1}{(\rho c_p)_{nf}}\frac{16\sigma^* T_{\infty}^3}{3k^*}\frac{\partial^2 T}{\partial y^2} + \frac{\mu_{nf}}{(\rho c_p)_{nf}}\left(\frac{\partial u}{\partial y}\right)^2 + \frac{Q_0}{(\rho c_p)_{nf}}(T_w - T_{\infty})$$

$$(6)$$

Proceeding with the analysis, it is pertinent to introduce the following similarity transformations:

$$\psi = \left[\frac{2\nu_f x u_w(x)}{(m+1)}\right]^{1/2} f(\eta), \ \eta = \left[\frac{(m+1)u_w(x)}{2\nu_f x}\right] y, \ \theta(\eta) = \frac{T - T_{\infty}}{T_w - T_{\infty}}, \ n = 2m$$
(7)

Where, v_f is the kinematic viscosity of the fluid and the stream function ψ is defined as $u = \frac{\partial \psi}{\partial y}$, $v = -\frac{\partial \psi}{\partial x}$ which identically satisfies the Eq. (1).

Now by substituting Eq. (7) and the aforementioned nanofluid properties into the Eqs. (2), (6) and the corresponding boundary conditions of the problem considered in Eq. (4), the governing boundary layer equations reduce to the following system of highly coupled nonlinear ordinary differential equations, in terms of a single independent variable (η):

$$f''' + (1 - \phi)^{2.5} \left\{ \begin{pmatrix} (1 - \phi) + \phi \frac{\rho_s}{\rho_f} \end{pmatrix} \left(ff'' - \frac{2m}{m+1} f'^2 \right) - Mf' + \\ \frac{2}{m+1} \left((1 - \phi) + \phi \frac{(\rho\beta)_s}{(\rho\beta)_f} \right) (Ri\cos(\alpha))\theta \end{pmatrix} \right\} = 0$$
(8)

$$\frac{1}{\Pr_{eff}}\theta'' + \left((1-\phi) + \phi \frac{(\rho c_p)_s}{(\rho c_p)_f}\right) \left(\left(\frac{2m+1}{m+1}\right)f\theta' - \left(\frac{4m}{m+1}\right)f'\theta\right) + \frac{Ec}{(1-\phi)^{2.5}}(f'')^2 + \frac{1}{m+1}\frac{Q}{\Pr}\theta = 0$$
(9)

The corresponding transformed boundary conditions for the stretching/shrinking sheet flow are given by:

$$at \quad \eta = 0 \qquad \begin{cases} f = S \\ f' = \pm 1 \\ \theta = 1 \\ \theta \to 0 \end{cases}$$
(10)
$$as \quad \eta \to \infty \qquad \begin{cases} f' \to 0 \\ \theta \to 0 \\ \theta \to 0 \end{cases}$$

Where $M = \frac{2\sigma_{nf}B_0^2}{c(m+1)\rho_f}$ is the magnetic field parameter, $Ri = \frac{Gr}{\text{Re}_x^2}$ is the Richardson number, $Gr = \frac{g\beta(T_w - T_w)x^3}{v_f^2}$ is the local Grashof number, $\text{Re}_x = xu_w(x)/v_f$ is the local

Reynolds number based on the stretching/shrinking velocity $u_w(x)$, $Ec = \frac{u_w^2}{(c_p)_f (T_w - T_\infty)}$ is

the Eckert number,
$$\Pr_{eff} = \frac{\Pr}{\left(\frac{k_{nf}}{k_f} + Nr\right)}$$
 is the effective Prandtl number (Magyari and

Pantokratoras [47]), $S = -\frac{2v_w x^{-(m-1)/2}}{(m+1)\sqrt{cv_f}}$ is the mass flux parameter which is either S > 0 for

suction or S < 0 for injection, $Nr = -\frac{16\sigma^* T_{\infty}^3}{3k_f k^*}$ is the radiation-conduction parameter and

 $Q = \frac{Q_0 2v_f x}{k_f u_w(x)}$ is the heat source/sink parameter. Furthermore, the physical quantities of engineering interest in materials processing operations are the skin friction coefficient C_f or the shear stress and the local Nusselt number or heat transfer coefficient Nu_x which may be defined by:

$$C_{f} = \frac{\mu_{nf}}{\rho_{f} u_{w}^{2}} \left(\frac{\partial u}{\partial y}\right)_{y=0}, Nu_{x} = \frac{-xk_{nf}}{k_{f} (T_{w} - T_{\infty})} \left(-\frac{\partial T}{\partial y}\right)_{y=0}$$
(11)

Using Eq. (7) and Eq. (11) the local skin friction coefficient and the local Nusselt number can be expressed as

$$\operatorname{Re}_{x}^{1/2} C_{f} = \frac{1}{(1-\phi)^{2.5}} \left(\frac{m+1}{2}\right)^{1/2} f''(0), \operatorname{Re}_{x}^{-1/2} Nu_{x} = -\frac{k_{nf}}{k_{f}} \left(\frac{m+1}{2}\right)^{1/2} \theta'(0)$$
(12)

3. NUMERICAL SOLUTION OF NONLINEAR BOUNDARY VALUE PROBLEM

The system of nonlinear coupled and inhomogeneous ordinary differential equations Eq. (8) and Eq. (9) subject to the boundary conditions in Eq. (10) are solved numerically using an implicit finite difference scheme known as the Keller-Box method [48]. Furthermore, this method is found to be suitable in dealing with nonlinear parabolic partial differential equations. It has been implemented in an extensive range of nanofluid and magnetohydrodynamic transport problems and readers are referred to [48]-[52]. Further

details of this method are available for convection flows in the monograph of Cebeci and Bradshaw ([53]). This method has four fundamental steps.



Fig. 2. Net rectangle for finite difference approximation

The first step involves converting the Eqs. (8) - (9) into a system of first order ordinary differential equations. Thus, the coupled differential equations of third order in $f(\eta)$ and second order in $\theta(\eta)$ has been reduced to a system of five simultaneous equations of first order for five unknowns as follows.

$$f'(\eta) = p; p'(\eta) = q; \theta'(\eta) = t;$$

$$q'(\eta) = (1-\phi)^{2.5} \left((1-\phi) + \phi \left(\frac{\rho_s}{\rho_f}\right) \right) \left(\frac{2m}{m+1}p^2 - fq\right);$$

$$+ Mp - \frac{2}{m+1} \left((1-\phi) + \phi \left(\frac{(\rho\beta)_s}{(\rho\beta)_f}\right) \right) RiCos(\alpha)\theta;$$

$$t'(\eta) = \Pr_{eff} \left(\left((1-\phi) + \phi \left(\frac{(\rho c_p)_s}{(\rho c_p)_f}\right) \right) \left(\left(\frac{4m}{m+1}\right)p\theta - \left(\frac{2m+1}{m+1}\right)ft \right) \right) - \left(\frac{Ec}{(1-\phi)^{2.5}}\right) q^2 - \left(\frac{1}{m+1}\frac{Q}{\Pr}\right)\theta$$

In the second step derivatives are approximated in the new system of first order equations with central difference approximations by considering the net rectangle in the $x\eta - plane$ as shown in Fig. 2 and the net points are defined as $x_0 = 0$, $x_n = x_{n-1} + k_n$, $\eta_0 = 0$, $\eta_j = \eta_{j-1} + h_j$

 $n = 1, 2, 3...J; j = 1, 2, 3...J and \eta_j = \eta_{\infty}$. Here k_n is the Δx -spacing and h_j is the $\Delta \eta$ -spacing and n, j are just the sequences of numbers that indicate the coordinate location. The centering midpoint $\left(x_{n-\frac{1}{2}}, \eta_{j-\frac{1}{2}}\right)$ of the segment are obtained by using the following finite difference approximations.

$$\left(\begin{array}{c} \right)_{j}^{n-\frac{1}{2}} = \frac{1}{2} \left[\left(\begin{array}{c} \right)_{j}^{n} + \left(\begin{array}{c} \right)_{j}^{n-1} \right]; \quad \left(\frac{\partial(\cdot)}{\partial x} \right)_{j-\frac{1}{2}}^{n-\frac{1}{2}} = \frac{1}{k_{n}} \left[\left(\begin{array}{c} \right)_{j-\frac{1}{2}}^{n} + \left(\begin{array}{c} \right)_{j-\frac{1}{2}}^{n-1} \right]; \\ \left(\begin{array}{c} \right)_{j-\frac{1}{2}}^{n} = \frac{1}{2} \left[\left(\begin{array}{c} \right)_{j}^{n} + \left(\begin{array}{c} \right)_{j-1}^{n} \right]; \quad \left(\frac{\partial(\cdot)}{\partial \eta} \right)_{j-\frac{1}{2}}^{n-\frac{1}{2}} = \frac{1}{h_{j}} \left[\left(\begin{array}{c} \right)_{j}^{n-\frac{1}{2}} + \left(\begin{array}{c} \right)_{j-1}^{n-\frac{1}{2}} \right]; \\ \end{array} \right];$$

In the third step the emerging nonlinear algebraic equations are linearized with Newton's method by using iterates of the form $\binom{i+1}{j} = \binom{i}{j} + \delta(\binom{i}{j}$ and then cast into matrix vector form. Finally, the linearized algebraic equations are solved using a block tri-diagonal elimination scheme implemented in MATLAB software with the suitable initial solution. This method is unconditionally stable (Cebeci and Bradshaw [53]), has a second order accuracy and is relatively easy to program, thus making it highly attractive for engineering analysis. For this iterative scheme to solve the system of equations, a convergence criterion is required. This is specified as follows: when the difference between two successive approximations is sufficiently small ($\leq 10^{-5}$) the solutions are taken to have converged to the requisite accuracy. Mathematical details are omitted for brevity.

Physical properties	H_2O	Си	Al_2O_3
Cp(j/kg k)	4179	385	765
$\rho(kg/m3)$	997.1	8933	3970
K(W/m k)	0.613	401	40
$\beta X 10^{-5} (1/k)$	21	1.67	0.85
σ (S/m)	5.5×10^{-6}	59.6×10^6	35×10^{6}

Table 1: Thermo-physical properties of water and nanoparticles

In the computations, the thermo-physical properties of water and metal nanoparticles (H_2O , Cu and Al_2O_3) are specified according to Table 1 (Khan *et al.* [40].)

4. GRID INDEPENDENCE STUDY

In order to ensure the obtained numerical solutions are independent of mesh density i.e. grid specification, the effects of grid size on the solutions are studied. The boundary conditions for $y \ at \propto$ are replaced by a sufficiently large value where the velocity and temperature profiles approach to zero. The MATLAB code is run with three different grid sizes 801×801 , 1001×1001 and 1201×1201 as shown in the Table 2 for stretching and shrinking sheet cases and in each case very good agreement is observed between the profiles. Finally, in the present study, the far field boundary condition η_{∞} is replaced by a sufficiently large value $\eta_{\text{max}} = 10$ and for all the computations in this numerical study the adopted grid size is 1001×1001 with step size of 0.001.

	$f'(\eta)$: Velocity Profiles					$\theta(\eta)$: Temperature Profiles						
	f' = +1 $f' = -1$			f' = +1			f' = -1					
8	01	1001	1201	801	1001	1201	801	1001	1201	801	1001	1201
	1	1	1	-1	-1	-1	1	1	1	1	1	1
0.	.9794	0.9794	0.9794	-0.9966	-0.9966	-0.9966	0.9953	0.9953	0.9953	0.9964	0.9964	0.9964
0.	.9597	0.9597	0.9597	-0.9931	-0.9931	-0.9931	0.9904	0.9904	0.9904	0.9929	0.9929	0.9929
(0.941	0.941	0.941	-0.9897	-0.9897	-0.9897	0.9856	0.9856	0.9856	0.9893	0.9893	0.9893
0.	.9232	0.9232	0.9232	-0.9863	-0.9863	-0.9863	0.9806	0.9806	0.9806	0.9858	0.9858	0.9858
0.	.9061	0.9061	0.9061	-0.9829	-0.9829	-0.9829	0.9756	0.9756	0.9756	0.9822	0.9822	0.9822
0.	.8897	0.8897	0.8897	-0.9795	-0.9795	-0.9795	0.9706	0.9706	0.9706	0.9787	0.9787	0.9787
(0.874	0.874	0.874	-0.9761	-0.9761	-0.9761	0.9655	0.9655	0.9655	0.9752	0.9752	0.9752
0.	.8588	0.8588	0.8588	-0.9727	-0.9727	-0.9727	0.9604	0.9604	0.9604	0.9717	0.9717	0.9717
0.	.8443	0.8443	0.8443	-0.9693	-0.9693	-0.9693	0.9553	0.9553	0.9553	0.9682	0.9682	0.9682

Table 2. Grid independence study for different grid sizes when $\phi = 0.05$

5. VALIDATION OF NUMERICAL RESULTS

To ascertain the correctness of the numerical values obtained through the implicit finite difference scheme, a comparison of skin friction coefficient and Nusselt number is made with results obtained through the numerical scheme in some limiting cases. For various values of power law exponent parameter, values of -f''(0) and $-\theta'(0)$ with Ec = 0 and Ec = 0.1 are compared in the absence of heat source/sink parameter and are documented in Table 3. This allows verification of the Keller box solutions with those reported by Hamad and Ferdows [34] for a stretching sheet case.

Furthermore, a comparison is also made for the case of absence of heat source/sink for horizontal stagnation point flow over a stretching/shrinking sheet which corresponds to the case studied by Pal *et al.* [46] wherein the Runge-Kutta RKF45 method with a shooting technique was employed. These comparisons are presented quantitatively in Table 4. It is evident from Table 3 that present the Keller box finite difference numerical values correlate closely with the solutions obtained by Hamad and Ferdows [34] which confirms the accuracy of the present results. Very good correlation is also achieved for both the shrinking and stretching sheet cases with the solutions of Pal *et al.* [45] in Table 4. Confidence in the present Keller box solutions is therefore justifiably high.

Table 3. Comparison of -f''(0) for various values of *m* and $-\theta'(0)$ for several values of *m* and *Ec* when Pr = 5.0, M = 0, Ri = 0, Nr = 0, $Q = 0 \phi = 0$ and $\alpha = \pi/2$ for a stretching sheet

- <i>f</i> "(0)				$-\theta'(0)$			
т	Hamad and Ferdows [34]	Present	т	Hamad and Ferdows [34]	Present results	Hamad and Ferdows [34]	Present results
		results		Ec = 0		Ec = 0.1	l
0.5	0.8897	0.88976	0.75	3.1246	3.12463	3.0156	3.01562
1	1.0043	1.00457	1.5	3.5672	3.56735	3.4566	3.45661
3	1.1481	1.14812	7	4.1848	4.1851	4.1354	4.13562

		Stretc	hing sheet	Shrinking sheet				
Pr _{eff}	Dulal Pal et al. [45]		Present results		Dulal Pal et al. [45]		Present results	
-55	f''(0)	$-\theta'(0)$	f''(0)	$-\theta'(0)$	f''(0)	$-\theta'(0)$	f''(0)	$-\theta'(0)$
2.5	-1.0721	2.3838	-1.07211	2.38389	6.1208	12.900	6.12084	12.90123
3.0	-0.8389	1.6065	-0.83898	1.60654	0.5687	5.8575	0.56872	5.85756
3.5	-0.8413	1.7548	-0.84135	1.75486	0.6223	6.8193	0.62236	6.81931

Table 4 Comparison of Skin friction and Nusselt number for various values of Pr_{eff} when Q = 0 and $\alpha = \pi/2$

Table 5 Values of Skin friction and Nusselt number for various values of S, Q and Ec when $Pr_{eff} = 2.5$

	0	Ec	Stretchi	Stretching Sheet		Shrinking Sheet	
S	Q		$\operatorname{Re}_{x}^{1/2} C_{f}$	$\operatorname{Re}_{x}^{-1/2} Nu_{x}$	$\operatorname{Re}_{x}^{1/2} C_{f}$	$\operatorname{Re}_{x}^{-1/2} Nu_{x}$	
0.25	0.5	0.01	-32.514	3.6879	1.6029	2.1036	
0.25	1	0.01	-32.514	3.7859	1.5682	2.3841	
0.25	1.5	0.01	-32.514	3.879	1.5337	2.641	
0.25	2	0.01	-32.514	3.9681	1.4994	2.8782	
0.25	1.5	0.1	-32.514	3.7859	1.5682	2.641	
0.25	1.5	0.2	-32.514	3.1979	1.5683	2.2213	
0.25	1.5	0.3	-32.514	2.6099	1.5683	1.8017	
0.25	1.5	0.4	-32.514	2.0219	1.5684	1.3821	
0.75	0.5	0.01	-34.0052	4.693	1.8148	4.856	
0.75	1	0.01	-34.0052	4.7794	1.7754	5.0094	
0.75	1.5	0.01	-34.0052	4.863	1.7361	5.1567	
0.75	2	0.01	-34.0052	4.9441	1.6971	5.2983	
0.75	1.5	0.1	-34.0052	4.7794	1.7754	5.1567	
0.75	1.5	0.2	-34.0052	3.9634	1.7755	4.6894	
0.75	1.5	0.3	-34.0052	3.1475	1.7756	4.2221	
0.75	1.5	0.4	-34.0052	2.3315	1.7756	3.7548	

Additionally in Table 5 computations are provided for the variation of skin friction $\operatorname{Re}_x^{1/2} C_f$ and Nusselt number (wall heat transfer rate) i.e. $\operatorname{Re}_x^{1/2} Nu_x$ for both the stretching sheet and shrinking sheet cases, with variation in suction parameter (S >0), heat source (Q>0) and Eckert number (Ec). For the stretching sheet case (extending sheet), skin friction is decreased with increasing suction i.e. the flow is decelerated. Conversely skin friction is enhanced for the shrinking sheet case with greater suction. With greater heat source i.e. heat generation, Nusselt number is enhanced for both the stretching sheet case. With increasing Eckert number the skin friction is not influenced tangibly for the stretching sheet case. However a significant reduction in Nusselt number arises for the shrinking sheet case over the same range of variation in Eckert number. The conversion of kinetic energy into thermal energy via viscous heating enhances temperatures in the boundary layer. This serves to heat the nanofluid and decreases the rate of heat transfer at the sheet surface (wall) manifesting in a fall in Nusselt numbers for both the shrinking or stretching scenarios.

consistent with other studies including Rana *et al.* [12] and Pal *et al.* [45]. The solutions in Table 5 also provide a useful benchmark for other researchers who may wish to extend the present model and validate different numerical procedures against the present Keller box computations.

6. RESULTS AND DISCUSSION

Comprehensive numerical computations have been carried out to study the effects of diverse parameters on thermo-fluid characteristics in the nanofluid boundary layer regime. Graphical distributions of the influence of magnetic field parameter (M), volume fraction parameter (ϕ), suction parameter (S), power law stretching parameter (m), inclination angle (α), effective Prandtl number (\Pr_{eff}), Eckert number (Ec) and Richardson number (Ri) on velocity, temperature, local skin friction ($\operatorname{Re}_x^{1/2} C_f$) and local Nusselt number ($\operatorname{Re}_x^{-1/2} Nu_x$) profiles are presented in Figs. 3 – 34. In this paper we computed the results for the above physical parameters by fixing the value $\phi = 0.05$, $\Pr = 6.8$, Nr = 1.0 and the parameter values for which the numerical computations are carried out are presented in the respective figure legends. Furthermore, The CPU took 6.52 seconds to compute the velocity profiles and 5.37 seconds to compute the temperature profiles for 1001 nodal points with the Intel core i3 processor under windows platform, which are computed by using the Matlab command *tic; { Statements**} toc;*.

Two different water based nanofluids $Cu - H_2O$ and $Al_2O_3 - H_2O$ are considered for both the stretching sheet (f' = +1) and the shrinking sheet (f' = -1) cases for velocity and temperature profiles. It is worth mentioning here that the momentum boundary layer thickness for $Cu - H_2O$ nanofluid is greater than the other water based nanofluid $Al_2O_3 - H_2O$ and this is attributable to the higher density of Cu compared with Al_2O_3 . The velocity profiles for stretching sheet/shrinking sheet commence with the surface velocity and decay to zero asymptotically at a distance sufficiently far from the plate surface. Furthermore, the velocity and temperature distributions for $Cu - H_2O$ exceed those of the $Al_2O_3 - H_2O$ profiles, and this is associated with the high thermal conductivity of Cu relative to Al_2O_3 which in turn leads to lower momentum boundary layer thickness and higher thermal boundary layer thickness of $Cu - H_2O$ nanofluid compared with $Al_2O_3 - H_2O$ nanofluid.

The impact of transverse magnetic field, as characterized in the magnetic parameter, M, on nanofluid velocity profiles is depicted in Figs. 3 and 4. An increase of magnetic field M parameter in the transverse direction to flow field induces a reduction in the velocity distributions for both cases of a stretching sheet (c > 0) and a shrinking sheet (c < 0). It is noteworthy that for the stretching sheet case the velocity $f'(\eta)$ commences with the sheet velocity and then decays to zero asymptotically at the edge of hydrodynamic boundary layer. However for the shrinking sheet case the velocity $f'(\eta)$ starts with sheet velocity, attains a maximum value near the vicinity of sheet surface and thereafter decays to zero in the freestream. Only the stretching sheet case therefore produces a monotonic decay. Effectively the momentum boundary layer thickness increases with an increase in magnetic field i.e. M for water based nanofluids. The deceleration in the boundary layer flow is due to the presence of a Lorentz magnetohydrodynamic drag force which acts perpendicular to the magnetic field. This resistive force inhibits the flow.

Figs. 5 and 6 respectively present the influence of magnetic field parameter M on temperature distribution for $Cu - H_2O$ and $Al_2O_3 - H_2O$. We infer from both Figs. 5 and 6 that temperature profiles are increased with an increase in magnetic field parameter. The supplementary work expended in dragging the nanofluid against the action of the magnetic field is dissipated as thermal energy. This heats the nanofluid, elevates temperatures and also increases thermal boundary layer thickness for both stretching and shrinking sheets. The stretching sheet temperature distribution is a consistent monotonic decay from the wall (sheet) to the freestream (peak temperature is always at the wall), whereas the shrinking sheet case follows a parabolic profile with a peak in temperature some distance from the wall.

Figs. 7-10 illustrate the influence volume fraction (ϕ) of spherical shaped nanoparticles on velocity and temperature distributions for stretching and shrinking sheet cases with $Cu - H_2O$ and $Al_2O_3 - H_2O$ nanofluids. Whenever ϕ increases, the velocity profiles are decreased in Figs. 7 and 8 for both stretching and shrinking sheets and temperature profiles are increased in Figs. 9 and 10 for both stretching and shrinking sheets. However, the thermal conductivity of water based nanofluids increases as the nanoparticle size increases due to the low viscosity of the base fluid which promotes the particle clustering and this in turn leads to interconnecting channels for thermal energy to propagate. Therefore as volume fraction increases the thermal conductivity of water based nanofluid is enhanced. Therefore, momentum boundary layer thickness is decreased and thermal boundary layer thickness is increased. Furthermore, inspection of the graphs demonstrates that the velocity and temperature profiles for $Al_2O_3 - H_2O$ nanofluid are markedly lower in magnitude than that of $Cu - H_2O$ nanofluid since Cu has a significantly higher conductivity than the Al_2O_3 .

Figs. 11 and 13 present the effect of the sheet power-law parameter (m) on velocity and temperature profiles for $Cu - H_2O$ and $Al_2O_3 - H_2O$ nanofluids for the stretching sheet case and Figs. 12 and 14 for the shrinking sheet case. It is observed from Figs. 11 and 12 that the velocity profiles are decreased with an increase of power-law parameter and decay from a maximum at the sheet surface asymptotically to zero in the freestream. Similarly for the shrinking sheet, an increase in power-law parameter decreases the velocities. However the profiles grow from a minimum at the wall to achieve a maximum in the free stream for the shrinking sheet, which is the opposite trend i.e. in Figs. 12 and 14 velocity is consistently decreased with increasing values of (m). Therefore more intensive stretching or shrinking of the sheet induces deceleration in the flow. We infer from Fig. 13 that temperature profiles are decreased near surface of the sheet and increased in the region away from the sheet surface with an increase in power-law parameter. Furthermore Fig. 14 demonstrates that the fluid temperature profiles exhibit a parabolic distribution. In both stretching and shrinking sheet cases, generally the copper-water nanofluid attains higher temperatures than the aluminium oxide water nanofluid.

Figs. 15 and 16 present the nanofluid temperature distributions for both the stretching and shrinking (contracting) sheet cases for different values of heat source parameter (Q > 0). We do not consider the heat sink (Q < 0) case. Fig. 15 illustrates that an increase of Q leads to increase in the temperature profiles in the thermal boundary layer regime, owing to the generation of energy in the thermal boundary layer. The nanofluid is energized by the presence of a heat source. Therefore, when heat is absorbed the buoyancy force also accelerates the flow. The stretching sheet temperature profile however follows a monotonic decay from the wall to the free stream. In Fig. 16 although for the shrinking sheet, there is also a boost in temperature profiles with heat source (Q>0), the profiles consistently exhibit a temperature overshoot near the surface of the sheet. This overshoot is displaced progressively further from the sheet surface with greater heat source (generation) which increases the magnitudes of temperatures throughout the boundary layer. Therefore greater heat source serves to increase thermal boundary layer thickness. Again it is evident that copper water nanofluid temperatures exceed those computed for the aluminum oxide water nanofluid case.

Figs. 17 and 18 depict the influence of angle of inclination (α) on the evolution of velocity distributions for both stretching and shrinking sheet cases. It is clearly observed from Fig. 17 that velocity is decreased with an increase of angle of inclination for the stretching sheet case, implying that the nanofluid experiences increased drag at the sheet surface. Furthermore, the buoyancy effects decrease by a factor of gravity component $\cos(\alpha)$ as the inclination angle is increased. Hence the fluid attains higher magnitudes of velocity for the vertical stretching sheet case compared with the inclined stretching sheet. Magnitudes are consistently positive however indicating that backflow is never attained at any angle of inclination of the sheet. Similarly Fig. 18 shows that with increasing inclination angle, the shrinking sheet flow is also decelerated i.e. smaller magnitudes of velocity are computed. The decrease in buoyancy force therefore also decelerates the flow for the shrinking sheet case; however the shrinking sheet exhibits consistently negative values corresponding to flow reversal, a trend which is not observed in the stretching sheet case.

Figs. 19 and 20 present the effect of Richardson number (Ri) on the velocity profiles for both the stretching and shrinking sheet cases. The heat and cooling of the sheet surface and absence of free convection currents are physically represented by different values of Richardson number, specifically Ri > 0, Ri < 0 and Ri = 0 respectively. By increasing the Richardson number, the thermal buoyancy force term is increased in Eqn. (8) i.e. the momentum equation. Fig. 19 demonstrates that the velocity profiles are increased for stretching sheet case whereas Fig. 20 clearly indicates the opposite i.e. that the nanofluid flow is decelerated for the shrinking sheet case with greater Richardson number i.e. values are increasingly negative for velocity. If the Richardson number is much less than unity, buoyancy is relatively insignificant. If it is much greater than unity, buoyancy is dominant. If the Richardson number is of order unity, as considered in the present graphs, the flow is buoyancy-driven: the energy of the flow derives from the potential energy in the system originally. The larger buoyancy force caused by greater Richardson number serves to accelerate the flow in a stretching sheet whereas it decelerates the flow in a shrinking sheet. Buoyancy therefore exerts a very profound effect on the flow development for the different scenarios of stretching and shrinking. In general the copper-water nanofluid achieves better acceleration than the aluminium-water nanofluid.

The influence of suction parameter (S) on velocity profiles in the cases of stretching and shrinking sheet cases are shown in Figs. 21 and 22 respectively. The velocity profiles for water based nanofluids $Cu - H_2O$ and $Al_2O_3 - H_2O$ decrease with an increase of the suction parameter for the stretching sheet whereas they increase for the shrinking sheet. The increase in suction draws nanofluid laterally through the sheet surface. This generates an adherence of the nanofluid boundary layer to the stretching sheet, destroys momentum in the fluid near the sheet surface and consequently stabilizes the momentum boundary layer growth. Therefore, nanofluid momentum boundary layer thickness is increased with greater suction as shown in Fig. 21. Conversely for the shrinking sheet (Fig. 22) the flow is accelerated with greater suction (less negative velocity values arise) and this decreases momentum boundary layer thickness. As a result, suction can be used effectively for controlling the momentum boundary layer growth/decay by using stretching/shrinking sheets respectively. Again copper water nanofluid achieves better flow acceleration than the aluminium oxide water nanofluid.

Figs. 23 and 24 illustrate the influence of Eckert number (Ec) on temperature profiles. The correlation between the kinetic energy in the flow and the boundary layer enthalpy difference is simulated via Eckert number. Due to internal friction heating between molecules of the fluid, mechanical energy is converted to thermal energy which heats the fluid in stretching sheet flow (Fig. 23). Therefore, an increase in Eckert number causes an increase in thermal energy contributing to the flow and will enhance the temperature of the water based nanofluids in the stretching sheet and also manifest in greater thermal boundary layer thickness. However the nature of shrinking sheet flow (contraction of the nanofluid sheet) generates the opposite response and temperatures are found to be decreased with greater Eckert number. The impact of viscous dissipation therefore is influenced by the nature of the boundary layer for a contracting sheet, and these aspects are of some importance in materials processing operations. However irrespective of whether the sheet is stretching or shrinking (contracting), the copper water nanofluid attains higher temperatures than the aluminium oxide water nanofluid.

Figs. 25 and 26 illustrate the variations in the temperature profiles for different values of effective Prandtl number (Pr_{eff}) for the stretching and shrinking sheet cases respectively. The Prandtl number refers to the relative contribution of momentum diffusion to thermal diffusion in the boundary layer regime. An iincrease in Pr_{eff} generally results in a decrease in the temperature distribution in the thermal boundary layer for both stretching and shrinking sheet cases. However very close to the wall (sheet) in the shrinking sheet case there is a short-lived weak increase in temperature profiles. This anomaly is however eliminated very quickly and the dominant trend is for a reduction in temperatures with greater effective Prandtl number. Smaller values of Pr_{eff} are equivalent to an increasing thermal conductivity, and therefore heat is able to diffuse away from the heated surface more rapidly than at higher values of Pr_{eff} . Consequently the rate of heat transfer near the sheet surface is reduced. Therefore, an increase in the value of Pr_{eff} causes a reduction in the thickness of the thermal boundary layer for both shrinking and stretching sheet cases. Furthermore the copper water nanofluid attains greater thermal boundary layer thickness than the aluminium oxide water nanofluid case.

Figs. 27-34 illustrate the response in skin friction $(\operatorname{Re}_{x}^{1/2} C_{f})$ and Nusselt number ($\operatorname{Re}_{x}^{1/2} Nu_{x}$) for the $Cu - H_{2}O$ nanofluid, with variation in selected thermo-physical parameters. Figs. 27-28 present, for both stretching and shrinking sheet cases, the values of $\operatorname{Re}_{x}^{1/2} C_{f}$ and $\operatorname{Re}_{x}^{1/2} Nu_{x}$ for suction parameter ($0 \le S \le 1$) vs. the dimensionless parameters which includes Ri, m, ϕ and M. Evidently with increasing Ri and m (power law parameter) the values of $\operatorname{Re}_{x}^{1/2} C_{f}$ are decreased for stretching sheet case whereas the converse trend is observed for the shrinking sheet case. Fig. 29 demonstrates that the values of $\operatorname{Re}_{x}^{1/2} C_{f}$ are decreased for increasing values of ϕ and M in the stretching sheet case where as for shrinking sheet case the reverse trend is observed in Fig. 30. It is also evident from Figs. 31 and 33 that the $\operatorname{Re}_{x}^{1/2} Nu_{x}$ values are decreased with increasing values of Ri and M for the stretching sheet case while with increasing values of ϕ and m the values of $\operatorname{Re}_{x}^{1/2} Nu_{x}$ are decreased for the shrinking sheet scenario, initially with lower values of S and thereafter the opposite trend is observed for increasing values of *S* in Figs. 32 and 34. The values of $\operatorname{Re}_{x}^{1/2} Nu_{x}$ are increased with increasing values of ϕ and *m* for the stretching sheet case in Figs. 31 and 33 while the same trend is observed with increasing values of *Ri* and *M* for the shrinking sheet case as shown in Figs. 32 and 34. We further note that in all computations the radiative-conductive parameter (Nr) has been fixed and is not explicitly considered.

7. CONCLUSIONS

Magnetohydrodynamic radiative mixed convection and dissipative boundary layer flow of nanofluid from a nonlinear inclined stretching/shrinking sheet in the presence of heat source/sink and viscous dissipation has been studied theoretically and numerically in this paper. The governing coupled nonlinear momentum and thermal boundary layer equations are transformed into ordinary differential equations by using local similarity transformations. The emerging nonlinear boundary value problem is solved with the Keller-Box implicit finite difference method. The originality of the present study entails an elaboration of the influence of governing parameters on velocity and temperature distributions for stretching/shrinking sheet cases utilizing two different types of water based nanofluids $Cu - H_2O$ and $Al_2O_3 - H_2O$ under nonlinear boundary conditions. Verification of the Keller box solutions has been achieved via comparison with previously published reports and generally very close correlation is observed. The principal findings of the current simulation may be summarized thus:

- The velocity profiles are decreased with increasing values of magnetic field parameter, volume fraction parameter and power-law parameter for both stretching sheet and shrinking sheet cases.
- For the stretching sheet case the velocity profiles are increased with increasing Richardson number and are decreased with increasing suction parameter whereas the opposite trend is computed for the shrinking sheet case.
- The temperature distribution values are increased with greater magnetic field parameter, volume fraction parameter and power-law parameter for both stretching and shrinking sheet cases.
- With increasing Eckert number the temperature values are increased for the stretching sheet case and the opposite trend is observed for the shrinking sheet case.
- With increasing power-law parameter, temperature is decreased initially and then increased with suction parameter.
- With increasing effective Prandtl number, temperature is decreased in the case of a stretching sheet whereas the converse behavior is found for a shrinking sheet case.
- For the stretching sheet case, the skin friction coefficient and local Nusselt number are decreased by decreasing the Richardson number and magnetic field parameter values. Moreover, an increase in the power-law parameter and volume fraction parameter results in a decrease in the skin friction coefficient whereas the reverse trend is observed for the local Nusselt number with increasing power-law parameter and volume fraction parameter.
- For the shrinking sheet case with an increase in Richardson number and magnetic field parameter, the local Nusselt number and skin friction coefficient are both increased. However with increasing power-law parameter and volume fraction parameter values, the skin friction coefficient is increased whereas the local Nusselt number is decreased initially and thereafter increased with suction parameter values.

Appendix I

Nomen	clature	<i>k</i> *	Mean absorption coefficient
(u,v)	Velocity components along (x, y) axes	Greek	symbols
	(ms^{-1})	α	Thermal diffusivity coefficient $(m^2 s^{-1})$
u _w	Stretching/Shrinking sheet velocity	$\alpha_{_f}$	Thermal diffusivity of the fluid $(m^2 s^{-1})$
Ψ	Stream function	α_s	Thermal diffusivity of the solid $(m^2 s^{-1})$
η	Similarity variable	α_{nf}	Thermal diffusivity of the nanofluid
f	Dimensionless velocity	nj	$(m^2 s^{-1})$
8	Acceleration due to gravity (ms^{-2})	ß	Thermal expansion coefficient (K^{-1})
m h	Nonlinear stretching parameter	р R	Coefficient of thermal expansion of the fluid
D C	Stretching/shrinking parameter (>0 for	${oldsymbol{ ho}}_f$	Coefficient of thermal expansion of the fund
	stretching sheet and <0 for shrinking sheet)	0	(K ⁻)
M S	Dimensionless magnetic field parameter	β_s	Coefficient of thermal expansion of the solid
0	Suction/injection parameter		(K^{-1})
e Nr	Thermal radiation parameter	$ ho_{f}$	Density of the fluid friction (Kgm^{-3})
$\operatorname{Re}_{x}^{2}$	Reynolds number	$ ho_{s}$	Density of the solid friction (Kgm^{-3})
Ri	Richardson number (Buoyancy parameter)	$ ho_{\it nf}$	Density of the nanofluid (Kgm^{-3})
Ec	Eckert number	v	Kinematic viscosity $(m^2 s^{-1})$
Nu_x	Nusselt number	V _f	Kinematic viscosity of the fluid $(m^2 s^{-1})$
Pr Pr	Prandtl number	,	Dynamic viscosity (Nsm^{-2})
Г г _{eff}		μ	Dynamic viscosity of the fluid (Nsm^{-2})
\mathcal{C}_f	Skin friction coefficient	μ_{f}	Dynamic viscosity of the finite (<i>Ivsm</i>)
Gr	Thermal Grashof number	$\mu_{\scriptscriptstyle nf}$	Dynamic viscosity of the nanofluid
ь Во	External uniform magnetic field		(Nsm^{-2})
a	Thermal radiative heat flux	σ	Electrical conductivity (sm^{-1})
4 r Ks	Thermal conductivity of the solid	$\sigma_{\scriptscriptstyle s}$	Electrical conductivity of the solid (sm^{-1})
	$(Wm^{-1}K^{-1})$	$\sigma_{_f}$	Electrical conductivity of the fluid (sm^{-1})
K_{f}	Thermal conductivity of the fluid	$\sigma_{\scriptscriptstyle n\!f}$	Electrical conductivity of the nanofluid
5	$(Wm^{-1}K^{-1})$		(sm^{-1})
K_{nf}	Thermal conductivity of the nanofluid	σ^{*}	Stefan–Boltzmann constant
	$(Wm^{-1}K^{-1})$	C_p	Specific heat at constant pressure
Т	Local temperature of the fluid (K)		$(Jm^{-3}K^{-1})$
T_{w}	Temperature of the fluid at the wall (K)	(ρc_p)	nf Heat capacitance of the nanofluid
T_{∞}	Free stream temperature (K)		$(Jm^{-3}K^{-1})$

$(\rho c_n)_f$	Heat capacitance of the fluid $(Jm^{-3}K^{-1})$	f	Fluid Phase
	(I - 3 V - 1)	S	Solid phase
$(\rho c_p)_s$	Heat capacitance of the solid $(Jm^{+}K^{+})$	nf	Nanofluid
ϕ	Nanoparticle volume fraction parameter	W	Condition at the wall
θ	Non-dimensional temperature	∞	Condition at freestream
· ·	- 4		

Subscripts

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Fig. 4. The dimension less velocity profiles for different values of M for stretching sheet.







Fig. 6. The dimension less temperature profiles for different values of M for shrinking sheet.



Fig. 7. The dimension less velocity profiles for different values of ϕ for stretching sheet.



Fig. 8. The dimension less velocity profiles for different values of ϕ for stretching sheet.



Fig. 9. The dimension less temperature profiles for different values of ϕ for stretching sheet.



Fig. 10. The dimension less temperature profiles for different values of ϕ for shrinking sheet.







Fig. 12. The dimension less velocity profiles for different values of *m* for stretching sheet.







Fig. 14. The dimension less temperature profiles for different values of *m* for shrinking sheet.







Fig. 16. The dimension less temperature profiles for different values of Q for shrinking sheet.







Fig. 18. The dimension less velocity profiles for different values of α for shrinking sheet.







Fig. 20. The dimension less velocity profiles for different values of *Ri* for shrinking sheet.







Fig. 22. The dimension less velocity profiles for different values of S for shrinking sheet.







Fig. 24. The dimension less temperature profiles for different values of *Ec* for shrinking sheet.



Fig. 25. The dimension less temperature profiles for different values of Pr_{eff} for stretching sheet.



Fig. 26. The dimension less temperature profiles for different values of Pr_{eff} for shrinking sheet.







Fig. 28. Variation of the skin friction coefficient with *Ri and m* for shrinking sheet.





Fig. 30. Variation of the skin friction coefficient with ϕ and M for shrinking sheet.



Fig. 31. Variation of the local Nusselt number with *Ri and m* for stretching sheet.



Fig. 32. Variation of the local Nusselt number with *Ri and m* for shrinking sheet.



Fig. 33. Variation of the local Nusselt number with ϕ and M for stretching sheet.



Fig. 34. Variation of the local Nusselt number with ϕ and M for shrinking sheet.

Highlights

- Inclined stretching/shrinking sheet magnetic nanofluid flow studied.
- Keller's box method employed for numerical solution.
- Heat source/sink, radiation and viscous dissipation effects examined.
- Stronger heat source increases thermal boundary layer thickness.
- Results are relevant to high-temperature magnetic nano-materials processing.