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# **ELECTRO-MAGNETO-HYDRODYNAMIC PERISTALTIC PUMPING OF COUPLE STRESS BIOFLUIDS THROUGH A COMPLEX WAVY MICRO-CHANNEL**

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## **ABSTRACT**

Biomimetic propulsion mechanisms are increasingly being explored in engineering sciences. Peristalsis is one of the most efficient of these mechanisms and offers considerable promise in microscale fluidics. Electrokinetic peristalsis has recently also stimulated significant attention. Electrical and magnetic fields also offer an excellent mode for regulating flows. Motivated by novel applications in electro-conductive microchannel transport systems, the current article investigates analytically the electromagnetic pumping of non-Newtonian aqueous electrolytes via peristaltic waves in a two-dimensional microchannel with different peristaltic waves propagating at the upper and lower channel wall (complex wavy scenario). The Stokes couple stress model is deployed to capture micro-structural characteristics of real working fluids. The unsteady two-dimensional conservation equations for mass and momentum conservation, electro-kinetic and magnetic body forces, are formulated in two dimensional Cartesian co-ordinates. The transport equations are transformed from the wave frame to the laboratory frame and the electrical field terms rendered into electrical potential terms via the Poisson-Boltzmann equation, Debye length approximation and ionic Nernst Planck equation. The dimensionless emerging linearized electro-magnetic boundary value problem is solved using integral methods. The influence of Helmholtz-Smoluchowski velocity (characteristic electro-osmotic velocity), couple stress length parameter (measure of the polarity of the fluid), Hartmann magnetic number, and electro-osmotic parameter on axial velocity, volumetric flow rate, time-averaged flow rate and streamline distribution are visualized and interpreted at length.

*Keywords: Peristalsis; Electro-Osmosis; Magnetohydrodynamics; Trapping; Biomimetic Propulsion; Bioinspired EMHD Micropumps.*

### **1. INTRODUCTION**

2

Peristalsis is an efficient mechanism for conveying fluids in biology via the involuntary continuous contraction and expansion of distensible vessel walls. It is encountered in pharyngeal transport (swallowing) [1], embryonic lung morphogenesis [2], intestinal pumping [3], bat wing vasomotion [4], spermatozoa transport [5], phloem trans-location in botany [6], medical endoscope design [7], earthworm locomotion [8, 9]. This mechanism of propulsion has also inspired more efficient soft robotic propulsion systems featuring complex actuator designs aimed at mimicking natural peristaltic motions [10, 11]. In addition to the many experimental investigations of peristaltic motion which have been reported, considerable interest has also emerged in mathematical and computational simulations of peristaltic flows. In such studies many different wall properties, physiological fluids and types of synchronous vessel oscillation have been considered. An early study of peristaltic mixing of chime in the digestive system was presented by Lew *et al*. [12] using a low Reynolds number Newtonian fluid model and considering a circular cylindrical tube involving a series of traveling nodal constrictions. They computed solutions for the influence of internode distances and depth of nodal constrictions on peristaltic efficiency. Bertuzzi *et al*. [13] analysed theoretically the pumping of solid spherical boluses in contractile membrane geometries under peristaltic waves. They computed numerically the sequence of deformed configurations of the membrane and the displacement of the bolus and also elaborated on applications in uterine contraction and erythroctye transport in narrow capillaries). Moradi *et al.* [14] employed an immersed boundary conditions method (IBC) and spectral algorithm to simulate the peristaltic flows in annular geometries by considering superposition of the flow in a smooth annulus and modifications associated with the surface waves, observing that alterations in the mean axial pressure gradient vary proportionally to the second power of the wave amplitude for waves with sufficiently low amplitudes. Simulations of peristaltic micropump flows have been presented by Tsui [15] using a lumped-element method. Rathish Kumar [16] analyzed numerically two-dimensional peristaltic flow with a nonlinear streamline quadrature up-winding non-iterative finite element method, noting that progressive waves with high amplitude and low wave numbers produce efficient peristaltic flows. Lin *et al.* [17] examined computationally the fluid-structure interaction in micro-pumps using an effective spring model incorporating both hydrodynamic and electrostatic forces. They evaluated in detail the influence of impact of geometry, materials and pump loading on peristaltic pumping performance. Further studies of peristaltic pumping analysis and design have been communicated by Natarajan and Mokhtarzadeh-Dehghan [18], Fauci [19], Jaffrin [20] (considering inertial curvature effects), Berg *et al.* [21] (who considered a discrete, twostage peristaltic microfluidics pump). Afifi and Gad [22] derived perturbation solutions for peristaltic flow interacting with periodic blood flow for a viscous incompressible fluid flow in a porous medium. Radhakrishnamacharya and Srinivasulu [23] studied the influence of wall elasticity (tension, damping and mass characterizing parameters) on peristaltic Newtonian flow and heat transfer in a two dimensional uniform channel. Chu [24] considered the hydrodynamic stability of peristaltic waves in a deformable conduit using a preconditioned complex-matrix solver.

Electrokinetics [25] has developed into a major branch of modern fluid dynamics. It arises in many medical applications including blood flows, microfluidics, chromatography, plasma separation and colloidal suspension fabrication and manipulation. Electrokinetics deals with the interaction between heterogeneous fluids contacting charged particles and static or alternating electric fields. It is important in simulating transport processes in ionic solutions in the vicinity of electrically-charged interfaces. Many sophisticated phenomena arise in electro-kinetics including electro-osmosis, zeta potential, dielectrics, diffusiophoresis, streaming potential/current, capillary osmosis, sedimentation potential etc. The proliferation of micro- and nanoscaled devices in bioengineering systems has witnessed significant developments in electro-kinetics. Kang *et al.* [26] reported in fabrication of electrokinetic micropumps. Yang *et al.* [27] considered AC electro-osmotic (ACEO) pumping on a symmetric gold electrode array. Many other studies have been communicated including Paul *et al*. [28], Sayar and Farouk [29] (who simulated coupled multifield flow in a piezoelectrically actuated valveless micropump device for liquid transport). Tripathi *et al*. [30] used a linearized analytical model to elucidate the effects of electro-osmotic velocity on peristaltic pumping of blood in capillaries.

Magnetohydrodynamics is also an important area of modern engineering sciences. This field involves the manipulation of electrically-conducting fluids with applied magnetic fields. In the realm of peristaltic pumping, magnetic fluids have also been considered. Relevant works include Mekheimer [31] who studied the influence of radial magnetic field thermal diffusion in peristaltic pumping of a Newtonian viscous liquid in a vertical annular regime. Further studies have been presented for magnetohydrodynamic peristalsis for a variety of working fluids including Johnson-Segalman viscoelastic fluids [32], nanofluids [33, 34], variable viscosity liquids [35], hyperbolic tangent nanofluids [36], magnetic viscous fluids [37], reactive micropolar fluids [38] and viscoelastic two-phase (dusty) magnetic fluids [39]. Ramos [40] has lucidly reviewed the advantages and drawbacks of electro/magnetic micropumps including peristaltic designs, emphasizing the deterioration, corrosion and electrochemical bubble issues which can cause flow obstructions and lower pumping efficiency in purely magnetohydrodynamic pumps. Motivated by exploring the combined influence of axial electric field and transverse magnetic field in micropumps, Tripathi *et al.* [41] presented a theoretical study of combined electrokinetic magnetohydrodynamic peristaltic transport with electrical double layer effects. They observed that higher magnetic field (Hartmann number) decreases flow rate, local wall shear stress, axial velocity whereas it elevates pressure difference. They also noted that with higher electro-osmotic parameter (i.e. smaller Debye length), there is an enhancement in flow rates.

Microstructural characteristics of working fluids cannot be simulated with many of the non-Newtonian fluid models discussed earlier. An interesting microstructural model is the *couple stress* model. Since the classical continuum (Navier-Stokes) theory ignores particle- size effects, a micro-continuum theory propounded by Stokes [42] was developed to simulate particle size effects. The Stokes micro-continuum theory is the generalization of the classical theory of fluids where polar effects such as the presence of couple stresses, body couples, and an anti-symmetric stress tensor are taken into consideration. In this model, the couple stress effects are considered as a consequence of the action of a deforming body on its neighbourhood. In the context of peristaltic flows, several investigations have considered couple stress fluids, which may provide a deeper insight into characteristics of working fluids in physiological applications and microscale pumps. Interesting simulations of couple stress peristaltic flow include Mekheimer and Abd elmaboud [43] for annular endoscopic geometries with an inner rigid tube and outer tube with a sinusoidal wave traveling along its wall. Magnetic field effects on couple stress fluid pumping by peristalsis were assessed by Tripathi and Bég [44] with a focus on gastric magnetic endoscopy. Ramesh and Devakar [45] elaborated on heat transfer in magnetic couple stress peristaltic flows with porous media drag effects. A similar study for coaxial (annular) transport was conducted by Tripathi and Bég [46]. Electrical field effects on couple stress flows have also been reported. Relevant studies in this regard include Rudraiah *et al*. [47] on stability in a permeable material and also Rudraiah *et al*. [48] on transient electrokinetic diffusion in couple stress flows in the haemolysis process. These studies have all confirmed the non-trivial influence of the polar length effect in modifying velocity and pressure distributions in couple stress transport

Thusfar however to the authors' knowledge there has been no study reported investigating the *combined effects of magnetic field and electrical field on peristaltic flow of couple stress fluids*. This is the focus of the present investigation. It extends the existing work in the field which has previously been confined to electrofluid thermal viscoelastic dielectric peristalsis [49], electrokinetic Jefferys (viscoelastic) peristaltic pumping [50] and electro-osmotic power-law peristaltic pumping [51]. The present work is relevant to simulation of real working fluids in electromagnetic biomimetic microscale pumps utilizing the peristaltic propulsion mechanism [52]. Such pumps avoid contamination problems, minimize maintenance and also achieve greater longevity and efficiency which may have immense potential in bio-inspired portable intravenous drip systems for medical treatments in the  $21<sup>st</sup>$ century.

#### **2. MATHEMATICAL MODEL**

The geometric model for the electro-kinetic transport through a finite length ( *L* ) microporous-channel under two different peristaltic waves propagating along the upper and lower

walls, depicted in **Fig.1**, is modelled as Cho and Chen [53]:  
\n
$$
\overline{h}(\overline{x}, \overline{t}) = a + \overline{\phi}_1 \sin \frac{2\pi}{\lambda} (\overline{x} - c\overline{t}) + \overline{\phi}_2 \sin \frac{4\pi}{\lambda} (\overline{x} - c\overline{t}),
$$
\n(1)

where  $a, \phi_1, \phi_2, \lambda, \overline{x}, c, \overline{t}$  are the half-width of the channel, amplitude of the different peristaltic waves along the microchannel walls, wavelength, axial coordinate, wave velocity, and time and  $a, \phi_1$ , and  $\phi_2$  satisfy the condition  $a \leq \phi_1 + \phi_2$ . We analyse the electro-magnetohydrodynamics of oscillating flow of couple stress fluids through a complex wavy channel under peristaltic waves. All classical electromagnetic phenomena are described by the Maxwell field equations. In **fig. 1** we further note that the peristaltic wave propagates from the left reservoir (Anode, +ve ion) to the right reservoir (Cathode, -ve ion) with a wave velocity *c*. In the presence of static axial electric field and static transverse magnetic field, the mass and momentum conservation equations for incompressible couple stress fluid are modified with addition of Lorentz force per unit volume, and written as:

$$
\frac{d\rho}{dt} + \rho \operatorname{div}(\vec{q}) = 0,\tag{2}
$$

$$
\frac{d\vec{q}}{dt} + \rho \operatorname{div}(\vec{q}) = 0,
$$
\n
$$
\rho \frac{d\vec{q}}{dt} = \rho \vec{f} + \frac{1}{2} \operatorname{curl}(\rho \vec{C}) + \operatorname{div}(\vec{\tau}^{(s)}) + \frac{1}{2} \operatorname{curl}(\operatorname{div}(\vec{M})) + \rho_e \vec{E} + \vec{J} \times \vec{B},
$$
\n(3)

where  $\rho$  is the density of the fluid,  $\tau^{(s)}$  is the symmetric part of the force stress diad, M is the couple stress diad and  $f$ ,  $C$  are the body force per unit mass and body couple per unit mass respectively,  $\vec{q}$  is the velocity vector. Here  $\rho_e \equiv z_+ n_+ e + z_- n_- e$ , denotes the charge number density of the aqueous solution present, where *e* is the charge, *n<sup>+</sup> and n-* are the number densities of cations and anions respectively,  $z_+$  and  $z_-$  are cation and anion valencies, and  $\vec{E}$ ,  $\vec{J}$  and  $\vec{B}$  represent the electric field, current density and magnetic flux density (magnetic field strength). The constitutive equations concerning the force stress  $t_{ij}$ and the rate of deformation tensor  $d_{ij}$  are given by:



**Figure 1:** Schematic of the peristaltic transport of an aqueous electrolyte solution with couple stress through a parallel micro-channels induced by axial electric field and transverse magnetic field.

magnetic field.  
\n
$$
t_{ij} = -p\delta_{ij} + \lambda div(\vec{q})\delta_{ij} + 2\mu d_{ij} - \frac{1}{2}\varsigma_{ijk}(m_{ik} + 4\eta w_{k,rr} + \rho C_k).
$$
\n(4)

The couple stress tensor  $m_{ij}$  that arises in the theory has following linear constitutive relation, as described by Stokes [44]:

$$
m_{ij} = \frac{1}{3} m \delta_{ij} + 4 \eta w_{j,i} + 4 \eta' w_{i,j},
$$
\n(5)

where  $w = \frac{1}{2} \text{curl}(q)$ 1 2  $w = \frac{1}{2}$ *curl*  $(q)$  is the spin vector,  $w_{i,j}$  is the spin tensor, *m* is the trace of couple stress tensor  $m_{ij}$ , *p* is the fluid pressure and  $\rho C_k$  is the body couple vector. A comma in the suffixes denotes covariant differentiation and  $w_{k,rr}$  stands for  $w_{k,11} + w_{k,22} + w_{k,33}$ . The

quantities  $\lambda$  and  $\mu$  are the viscosity coefficients and  $\eta$ ,  $\eta'$  are the couple stress viscosity coefficients. These material constants are constrained by the inequalities,

$$
\mu \ge 0; \ 3\lambda + 2\mu \ge 0; \ \eta \ge 0; \ |\eta'| \le \eta. \tag{6}
$$

If the fluid is incompressible, in the absence of body forces and body couples, and *axial external electric field* (*Ex*) and *transverse magnetic field* (*By*) effects (i.e. mutually orthogonal) are taken into consideration, the reduced governing equations for mass and momentum conservation may be expressed as:

$$
\frac{\partial \overline{u}}{\partial \overline{x}} + \frac{\partial \overline{v}}{\partial \overline{y}} = 0,\tag{7}
$$

$$
\overline{\partial x} + \overline{\partial y} = 0,
$$
\n
$$
\rho \left( \frac{\partial \overline{u}}{\partial \overline{t}} + \overline{u} \frac{\partial \overline{u}}{\partial \overline{x}} + \overline{v} \frac{\partial \overline{u}}{\partial \overline{y}} \right) = -\frac{\partial \overline{p}}{\partial \overline{x}} + \mu \nabla^2 \overline{u} - \eta \nabla^4 \overline{u} - \sigma B_x^2 \overline{u} + \rho_e E_x,
$$
\n(8)

$$
\rho \left( \frac{\partial \overline{v}}{\partial \overline{t}} + \overline{u} \frac{\partial \overline{v}}{\partial \overline{x}} + \overline{v} \frac{\partial \overline{v}}{\partial \overline{y}} \right) = -\frac{\partial \overline{p}}{\partial \overline{y}} + \mu \nabla^2 \overline{v} - \eta \nabla^4 \overline{v} . \tag{9}
$$

The penultimate term on the right hand side of eqn. (8) denotes the *Lorentzian magnetic body force* and the last term represents the *electrokinetic body force*. In this model, we consider the case where the peristaltic transport of an aqueous ionic solution of couple stress fluids is altered by means of an externally applied electric field and transverse magnetic field along the length of channel. The positive ions  $n_+$  and negative ion  $n_-$  are both assumed to have bulk concentration (number density)  $n_0$ , and a valency of  $z_+$  and  $z_-$  respectively. For simplicity, we consider the electrolyte to be a  $z:z$  symmetric electrolyte, i.e.  $z_{+} = -z_{-} = z$ . The charge number density is related to the electrical potential in the transverse direction  $\varphi$ through the Poisson equation:

$$
\nabla^2 \overline{\varphi} = -\frac{\rho_e}{\varepsilon},\tag{10}
$$

where  $\varepsilon$  is the permittivity of the electromagnetic couple stress fluid. Further, in order to determine the potential distribution, we need to describe the charge number density. For this, the ionic number distributions of the individual species are given by the Nernst-Planck equation for each species as:

equation for each species as:  
\n
$$
\frac{\partial n_{\pm}}{\partial t} + u \frac{\partial n_{\pm}}{\partial x} + v \frac{\partial n_{\pm}}{\partial y} = D \left( \frac{\partial^2 \overline{n}_{\pm}}{\partial x^2} + \frac{\partial^2 \overline{n}_{\pm}}{\partial y^2} \right) \pm \frac{Dze}{k_B T} \left( \frac{\partial}{\partial x} \left( \overline{n}_{\pm} \frac{\partial \overline{\phi}}{\partial x} \right) + \frac{\partial}{\partial y} \left( \overline{n}_{\pm} \frac{\partial \overline{\phi}}{\partial y} \right) \right),
$$
\n(11)

where we have assumed equal ionic diffusion coefficients for both the species, and that the mobility of the species is given by the Einstein formula where D represents the diffusivity of the chemical species, T is the average temperature of the electrolytic solution and  $k<sub>B</sub>$  is Boltzmann constant. Proceeding with the analysis, we normalize the Poisson and Nernst-Planck equation with the following non-dimensional parameters:  $x = \frac{\overline{x}}{2}, y = \frac{\overline{y}}{a}, t = \frac{\overline{t}c}{2}, u = \frac{\overline{u}}{a}, v = \frac{\overline{v}}{k_{0}},$  $\frac{x}{\lambda}$ ,  $y = \frac{y}{a}$ ,  $t = \frac{tc}{\lambda}$ ,  $u = \frac{u}{c}$ ,  $v = \frac{v}{kc}$  $=\frac{\overline{x}}{2}$ ,  $y = \frac{\overline{y}}{2}$ ,  $t = \frac{\overline{t}c}{2}$ ,  $u = \frac{\overline{u}}{2}$ ,  $v = \frac{\overline{v}}{4}$ , 0 , *B*  $\frac{ze\varphi}{1-\overline{n}}, n=\frac{\overline{n}}{2}$  $k_{B}T$ <sup>"</sup> n  $\varphi = \frac{ze\varphi}{\sqrt{E}}$ ,  $n = \frac{n}{\sqrt{2}}$ . We further note that the nonlinear terms in the Nernst Planck equations are  $O(Pek^2)$ , where  $Pe = Re Sc$  represents the ionic Peclet

number, *Re* is Reynolds number and  $Sc = \mu / \rho D$  denotes the Schmidt number. Therefore, the nonlinear terms may be dropped in the limit that *Re, Pe, k* <<1. In this limit, Poisson's equation is obtained as:

$$
\frac{\partial^2 \varphi}{\partial y^2} = -\kappa^2 \left( \frac{n_+ - n_-}{2} \right),
$$
\n(12)

where  $\kappa = aez$ ,  $\frac{2n_0}{\kappa}$  $\mathbf{B}^I$   $\mathcal{A}_d$  $\kappa = aez \sqrt{\frac{2n_0}{\varepsilon K_B T}} = \frac{a}{\lambda_d}$  $= aez \sqrt{\frac{2n_0}{\kappa} \tau} = \frac{a}{\lambda}$ , is known as the electro-osmotic parameter and  $\lambda_d \propto \frac{1}{\kappa}$  $\lambda_d \propto \frac{1}{\kappa}$  is

Debye length or characteristic thickness of electrical double layer (EDL). The ionic distribution may be determined by means of the simplified Nernst Planck equations:

$$
0 = \frac{\partial^2 n_{\pm}}{\partial y^2} \pm \frac{\partial}{\partial y} \left( n_{\pm} \frac{\partial \varphi}{\partial y} \right),
$$
 (13)

subjected to  $n_{\pm} = 1$  at  $\varphi = 0$  and  $\partial n_{\pm}/\partial y = 0$  where  $\partial \phi / \partial y = 0$  (bulk conditions). These yield the much celebrated Boltzmann distribution for the ions:

$$
n_{\pm} = e^{\mp \varphi} \,. \tag{14}
$$

Combining equation (12) and (14), we obtain the Poisson-Boltzmann paradigm for the potential determining the electrical potential distribution

$$
\frac{\partial^2 \varphi}{\partial \bar{y}^2} = \kappa^2 \sinh(\varphi).
$$
 (15)

In order to make further analytical progress, we must simplify equation (15). Equation (15) may be linearized under the *low-zeta potential approximation*. This assumption is not *ad hoc*

since for a wide range of pH values, the magnitude of zeta potential is less than 25 mV. Therefore, equation (15) may be contracted to:

$$
\frac{\partial^2 \varphi}{\partial y^2} = \kappa^2 \varphi, \tag{16}
$$

which may be solved subjected to  $\mathbf{0}$  $\boldsymbol{0}$ *y y*  $\varphi$ =  $\frac{\partial \varphi}{\partial \varphi}$  =  $\hat{o}$ and  $\varphi|_{\eta=y} = 1$ , the potential function is obtained

as: 
$$
\varphi = \frac{\cosh(\kappa y)}{\cosh(\kappa h)},
$$
 (17)

To simplify the governing equations, we invoke a number of non-dimensional parameters, specifically non-dimensional pressure 2  $p = \frac{\overline{p}a^2}{a},$  $\mu$ c $\lambda$  $=\frac{pa}{\lambda}$ , and wavelength-based Reynolds number  $Re = \frac{c\lambda}{\lambda}$  $\mu/\rho$  $=\frac{c\lambda}{c}$ . The nonlinear terms in the momentum equation are found to be  $O(Re k^2)$ ,

where  $k = -\frac{a}{\lambda}$  denotes the ratio of the transverse length scale to the axial length scale. Employing lubrication theory approximations, the governing conservation equations are reduced to:

$$
\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0\,,\tag{18}
$$

$$
\frac{\partial p}{\partial x} = \frac{\partial^2 u}{\partial y^2} - l^2 \frac{\partial^4 u}{\partial y^4} - Ha^2 u + \kappa^2 u_e \varphi.
$$
\n(19)

The associated velocity boundary conditions are:

$$
u\big|_{y=h} = 0 \; , \frac{\partial u}{\partial y}\big|_{y=0} = 0 \; , \frac{\partial^2 u}{\partial y^2}\big|_{y=h} = 0 \; \frac{\partial^3 u}{\partial y^3}\big|_{y=0} = 0 \, , \tag{20}
$$

where,  $u_e = -\frac{E_x}{\mu}$  $u_e = -\frac{E}{\epsilon}$ *c*  $\varepsilon\zeta$  $\mu$  $=-\frac{E_xE_y}{\sqrt{2}}$  is the Helmholtz-Smoluchowski velocity or characteristic electroosmotic velocity,  $l = \frac{1}{l} \sqrt{\frac{\eta}{l}}$ , *a*  $\eta$  $\mu$  $\frac{1}{\epsilon} = \frac{1}{\epsilon} \int_{-\epsilon}^{\epsilon}$  is the couple stress length parameter, which is a characteristic measure of the polarity of the fluid model and this parameter is identically zero in the case of

non-polar fluids,  $Ha = \sqrt{\frac{\sigma}{\mu}}aB_x$  $\mu$  $=\sqrt{\frac{6}{a}}$ , Hartmann number, which measures the strength of magnetic body force (Lorentzian force) relative to the viscous force. The reduced fourth order momentum equation (19) allows a parametric study of the couple stress, magnetic body force and electro-osmotic effects via the variation in the  $l$ ,  $Ha$  and  $\kappa$  parameters.

# **3. ANALYTICAL SOLUTIONS**

Solving Eqn. (19) with boundary conditions (20), the axial velocity is obtained as:  
\n
$$
u = C_1 e^{\frac{y}{\sqrt{2}} \sqrt{\frac{1}{l^2} - \frac{\sqrt{1-4Ha^{2}/2}}{l^2}}} + C_2 e^{\frac{-y}{\sqrt{2}} \sqrt{\frac{1}{l^2} - \frac{\sqrt{1-4Ha^{2}/2}}{l^2}}} + C_3 e^{\frac{y}{\sqrt{2}} \sqrt{\frac{1}{l^2} + \frac{\sqrt{1-4Ha^{2}/2}}{l^2}}} + C_4 e^{\frac{-y}{\sqrt{2}} \sqrt{\frac{1}{l^2} + \frac{\sqrt{1-4Ha^{2}/2}}{l^2}}}
$$
\n
$$
-\frac{4\left(\frac{\partial p}{\partial x}(-Ha^2l^2 + l^2\kappa^2 - l^4\kappa^4) + Ha^2l^2u_e\kappa^2\cosh(y\kappa)\operatorname{sech}(hk)\right)}{Ha^2\left(1 + \sqrt{1-4Ha^2l^2} - 2l^2\kappa^2\right)\left(-1 + \sqrt{1-4Ha^2l^2} + 2l^2\kappa^2\right)},
$$
\n(21)

where,

$$
C_{1} = -\frac{2e^{\frac{h}{\sqrt{2}}\sqrt{\frac{1-\sqrt{1-4Ha^{2}l^{2}}{l^{2}}}}}}{\left(1+e^{\frac{h}{\sqrt{2}}\sqrt{\frac{2-\sqrt{1-4Ha^{2}l^{2}}}{l^{2}}}}\right)Ha^{2}\sqrt{1-4Ha^{2}l^{2}}}\left(1+\sqrt{1-4Ha^{2}l^{2}}+Ha^{2}\right)+u_{e}\kappa^{2}Ha^{2}\left(-1-\sqrt{1-4Ha^{2}l^{2}}+2l^{2}\kappa^{2}\right)}\right)}{4+e^{\frac{h}{\sqrt{2}-2\sqrt{1-4Ha^{2}l^{2}}}}Ha^{2}\sqrt{1-4Ha^{2}l^{2}}\left(1+\sqrt{1-4Ha^{2}l^{2}}-2l^{2}\kappa^{2}\right)\left(-1+\sqrt{1-4Ha^{2}l^{2}}+2l^{2}\kappa^{2}\right)},
$$

$$
C_{2} = -\frac{2e^{\frac{h}{\sqrt{2}}\sqrt{\frac{1-\sqrt{1-4Ha^{2}l^{2}}{l^{2}}}}}}{\left(1+e^{h\sqrt{\frac{2-2\sqrt{1-4Ha^{2}l^{2}}}{l^{2}}}}\right)Ha^{2}\sqrt{1-4Ha^{2}l^{2}}}\left(\kappa^{2}\left(-1+l^{2}\kappa^{2}\right)+Ha^{2}\right)+u_{e}\kappa^{2}Ha^{2}\left(-1-\sqrt{1-4Ha^{2}l^{2}}+2l^{2}\kappa^{2}\right)\right)}{4\left(1+e^{h\sqrt{\frac{2-2\sqrt{1-4Ha^{2}l^{2}}}{l^{2}}}}\right)Ha^{2}\sqrt{1-4Ha^{2}l^{2}}\left(1+\sqrt{1-4Ha^{2}l^{2}}-2l^{2}\kappa^{2}\right)\left(-1+\sqrt{1-4Ha^{2}l^{2}}+2l^{2}\kappa^{2}\right)},
$$

$$
C_{3} = \frac{2e^{\frac{h}{\sqrt{2}}\sqrt{\frac{1+\sqrt{1-4Ha^{2}l^{2}}}{l^{2}}}}}{\left(1+e^{\frac{\sqrt{2}h\sqrt{\frac{1+\sqrt{1-4Ha^{2}l^{2}}}{l^{2}}}}}{\sqrt{1-4Ha^{2}l^{2}}}\right)Ha^{2}\sqrt{1-4Ha^{2}l^{2}}}\left(1+\sqrt{1-4Ha^{2}l^{2}}-2l^{2}\kappa^{2}\right)\left(-1+\sqrt{1-4Ha^{2}l^{2}}+2l^{2}\kappa^{2}\right)}\right)}{ \left(1+e^{\frac{\sqrt{2}h\sqrt{\frac{1+\sqrt{1-4Ha^{2}l^{2}}}{l^{2}}}}}{\sqrt{1-4Ha^{2}l^{2}}}\right)Ha^{2}\sqrt{1-4Ha^{2}l^{2}}\left(1+\sqrt{1-4Ha^{2}l^{2}}-2l^{2}\kappa^{2}\right)\left(-1+\sqrt{1-4Ha^{2}l^{2}}+2l^{2}\kappa^{2}\right)}\right)}
$$

$$
C_{4} = -\frac{2e^{\frac{h}{\sqrt{2}}\sqrt{\frac{1+\sqrt{1-4Ha^{2}t^{2}}}{l^{2}}}}}{1+e^{\frac{\sqrt{2}h\sqrt{\frac{1+\sqrt{1-4Ha^{2}}t^{2}}}{l^{2}}}}}{\sqrt{1-4Ha^{2}t^{2}}}\left(1+\sqrt{1-4Ha^{2}t^{2}}-2t^{2}\kappa^{2}\right)\left(-1+\sqrt{1-4Ha^{2}t^{2}}+2t^{2}\kappa^{2}\right)
$$
\n
$$
\left\{\frac{\partial p}{\partial x}\left(-1+\sqrt{1-4Ha^{2}t^{2}}\right)\left(\kappa^{2}\left(-1+t^{2}\kappa^{2}\right)+Ha^{2}\right)-u_{e}\kappa^{2}Ha^{2}\left(-1+\sqrt{1-4Ha^{2}t^{2}}+2t^{2}\kappa^{2}\right)\right\}.\tag{22}
$$

The volumetric flow rate is given by integrating axial velocity across the microchannel width:

$$
Q = \int_{0}^{h} u dy
$$
 (23)

Using Eqn. (12) in Eqn. (13), we get:  
\n
$$
Q = -\frac{h}{Ha^2} \frac{\partial p}{\partial x} + \frac{u_e \kappa \tanh(h\kappa)}{Ha^2 - \kappa^2 + l^2 \kappa^4} + \sqrt{\frac{2l^2}{1 - \sqrt{1 - 4Ha^2l^2}}} \left\{ C_1 \left( -1 + e^{-\frac{h\sqrt{\frac{1 - \sqrt{1 - 4Ha^2l^2}}{l^2}}}{\sqrt{2}}} \right) + C_2 \left( 1 - e^{-\frac{h\sqrt{\frac{1 - \sqrt{1 - 4Ha^2l^2}}{l^2}}}{\sqrt{2}}} \right) \right\}
$$
\n
$$
+ \sqrt{\frac{2l^2}{1 + \sqrt{1 - 4Ha^2l^2}}} \left\{ C_3 \left( -1 + e^{-\frac{h\sqrt{\frac{1 + \sqrt{1 - 4Ha^2l^2}}{l^2}}}{\sqrt{2}}} \right) + C_4 \left( 1 - e^{-\frac{h\sqrt{\frac{1 + \sqrt{1 - 4Ha^2l^2}}{l^2}}}{\sqrt{2}}} \right) \right\}.
$$
\n(24)

The transformations between a wave frame  $(x_w, y_w)$  moving with velocity c and the fixed frame  $(x, y)$  are given by :

$$
x = x_w - ct, \quad y = y_w, \quad u = u_w + c, \quad v = v_w,
$$
 (25)

where  $(u_w, v_w)$  and  $(u, v)$  are the velocity components in the wave (laboratory) and fixed frame respectively.

The volumetric flow rate in the wave frame is given by

$$
q_w = \int_0^h u_w dy_w = \int_0^h (u - 1) dy_w,
$$
\n(26)

which, on integration, yields:

$$
q_w = Q - h \tag{27}
$$

Averaging the volumetric flow rate along one time period, we obtain:

$$
\overline{Q} = \int_{0}^{1} Qdt = \int_{0}^{1} (q_w + h)dt ,
$$
\n(28)

which, on integration, yields

$$
\overline{Q} = q_w + 1 = Q + 1 - h \tag{29}
$$

Rearranging the terms of Eq.(24) and solving for pressure gradient yields:

Rearranging the terms of Eq.(24) and solving for pressure gradient yields:  
\n
$$
\frac{\partial p}{\partial x_w} = + \overline{Q} - 1 + h - \frac{u_e k \tanh(hk)}{Ha^2 - k^2 + l^2 k^4} + \sqrt{\frac{2l^2}{1 - \sqrt{1 - 4Ha^2 l^2}}} \left\{ \frac{Ha^2}{h} C_1 \left( 1 + e^{\frac{h}{\sqrt{2}} \sqrt{\frac{1 - \sqrt{1 - 4Ha^2 l^2}}{l^2}}} \right) - C_2 \left( 1 - e^{-\frac{h}{\sqrt{2}} \sqrt{\frac{1 - \sqrt{1 - 4Ha^2 l^2}}{l^2}}} \right) \right\}
$$
\n
$$
- \sqrt{\frac{2l^2}{1 + \sqrt{1 - 4Ha^2 l^2}}} \left\{ C_3 \left( -1 + e^{\frac{h}{\sqrt{2}} \sqrt{\frac{1 + \sqrt{1 - 4Ha^2 l^2}}{l^2}}} \right) + C_4 \left( 1 - e^{-\frac{h}{\sqrt{2}} \sqrt{\frac{1 + \sqrt{1 - 4Ha^2 l^2}}{l^2}}} \right) \right\}.
$$
\n(30)

*Pressure rise along one wavelength* is defined as:

$$
\Delta p = \int_0^1 \frac{\partial p}{\partial x_w} dx_w \,. \tag{31}
$$

Using Eqn. (21), the *stream function* (obeying the Cauchy-Riemann equations,  $u_w$ *w u y*  $=\frac{\partial \psi}{\partial x}$  $\hat{c}$ and

$$
v_w = -\frac{\partial \psi}{\partial x_w} \text{ takes the form:}
$$
\n
$$
\psi = -\frac{h}{Ha^2} \frac{\partial p}{\partial x_w} + \frac{u_e \kappa \tanh(h\kappa)}{Ha^2 - \kappa^2 + l^2 \kappa^4} + \frac{2l^2}{\sqrt{1 - \sqrt{1 - 4Ha^2 l^2}}} \left\{ C_1 \left( e^{\frac{h}{\sqrt{2}} \sqrt{1 - \sqrt{1 - 4Ha^2 l^2}}} - 1 \right) + C_2 \left( 1 - e^{\frac{-h}{\sqrt{2}} \sqrt{1 - \sqrt{1 - 4Ha^2 l^2}}} \right) \right\} + \frac{2l^2}{\sqrt{1 + \sqrt{1 - 4Ha^2 l^2}}} \left\{ C_3 \left( e^{\frac{h}{\sqrt{2}} \sqrt{1 + \sqrt{1 - 4Ha^2 l^2}}} - 1 \right) + C_4 \left( 1 - e^{\frac{-h}{\sqrt{2}} \sqrt{1 + \sqrt{1 - 4Ha^2 l^2}}} \right) \right\}.
$$
\n(32)

## **4. NUMERICAL RESULTS AND DISCUSSION**

In this section, we visualize numerical results, evaluated via Mathematica symbolic software, to explore the influence of the key electro-magnetic and hydrodynamic parameters on the flow variables in **Figs. 2-5**. We consider the dual amplitude peristaltic wave scenario i.e. with two different wave amplitudes  $(\phi_1, \phi_2)$  at the upper and lower walls of the micro-channel.





**Fig.2.** Velocity profile (axial velocity vs. transverse coordinate) with  $\phi_1 = 0.2$ ,  $\phi_2 = 0.3$ , and (a)  $u_e = 1, l = 1, Ha = 0.1$  (b)  $\kappa = 0.5, l = 1, Ha = 0.1$  (c)  $\kappa = 0.5, u_e = 1, Ha = 0.1$  (d)  $\kappa = 0.5, u_e = 1, l = 1$ .





**Fig.3.** Volumetric flow rate vs. axial coordinate with  $\phi_1 = 0.2$ ,  $\phi_2 = 0.3$ ,  $\partial p / \partial x = 1$ , and (a)  $u_e = 1, l = 1, Ha = 0.1$  **(b)**  $\kappa = 0.5, l = 1, Ha = 0.1$  **(c)**  $\kappa = 0.5, u_e = 1, Ha = 0.1$  **(d)**  $\kappa = 0.5, u_e = 1, l = 1$ .





**Fig.4.** Time averaged volumetric flow rate vs. pressure rise across one wavelength with  $\phi_1 = 0.2, \phi_2 = 0.3,$ and **(a)**   $u_e = 1, l = 1, Ha = 0.1$ **(b)**   $\kappa = 0.5, l = 1, Ha = 0.1$ **(c)**   $\kappa = 0.5, u_e = 1, Ha = 0.1$  **(d)**  $\kappa = 0.5, u_e = 1, l = 1$ .



















**Fig.5.** Stream lines in wave form at  $\phi_1 = 0.2$ ,  $\phi_2 = 0.3$ ,  $\overline{Q} = 0.9$  for (a)  $\kappa = 2$ ,  $u_e = 5$ ,  $l = 0.1$ ,  $Ha = 1$ **(b)**  $\kappa = 5, u_e = 5, l = 0.1, Ha = 1$  **(c)**  $\kappa = 9, u_e = 5, l = 0.1, Ha = 1$  **(d)**  $\kappa = 5, u_e = 7, l = 0.1, Ha = 1$ **(e)**  $\kappa = 5, u_e = 9, l = 0.1, Ha = 1$  **(f)**  $\kappa = 5, u_e = 5, l = 0.25, Ha = 1$  **(g)**  $\kappa = 5, u_e = 5, l = 1, Ha = 1$ **(h)**  $\kappa = 5, u_e = 5, l = 0.1, Ha = 0.1$  **(i)**  $\kappa = 5, u_e = 5, l = 0.1, Ha = 0.3$ 

**Fig.2a-d** illustrate the influence of respectively a) electro-osmotic parameter (  $2n_0$  $\mathbf{B}$ **l**  $\mathcal{A}_d$  $\kappa = aez \sqrt{\frac{2n_0}{\varepsilon K_B T}} = \frac{a}{\lambda_d}$  $= aez \sqrt{\frac{2n_0}{x \cdot \overline{x}}} = \frac{a}{\lambda}$ ), b) Helmholtz-Smoluchowski velocity i.e. characteristic electro-

osmotic velocity ( $u_e = -\frac{L_x}{L_x}$  $u_e = -\frac{E}{\epsilon}$ *c*  $\varepsilon\zeta$  $\mu$  $=-\frac{E_x \varepsilon \zeta}{\lambda}$ , c) couple stress length parameter  $(l=\frac{1}{\lambda})\frac{\eta}{\lambda}$ , *a*  $\eta$  $\mu$  $=-\frac{1}{2}$ , and d)

Hartmann magnetic parameter ( $Ha = \sqrt{\frac{\sigma}{\mu}}aB_x$  $\mu$  $=\sqrt{\frac{6}{a}}$  on axial velocity (*u*). There is a progressive

reduction in axial flow with increasing electro-osmotic parameter, $\kappa$ , with greater transverse coordinate. Decreasing Debye length therefore results in a *damping in the axial flow*. The deceleration is induced by the electrokinetic body force in eqn. (19) i.e.  $\kappa^2 u e \varphi$ . This damping is generally sustained quite strongly except for higher values of transverse coordinate where the upper microchannel wall is approached and the reverse trend is observed here i.e.

acceleration in the axial flow. Fig 2b shows that with greater negative Helmholtz-Smoluchowski velocity,  $u_e$ , the axial flow is accelerated whereas with greater positive values the flow is decelerated. Generally the case of vanishing electrical field  $(u_e, =0)$  falls between the other profiles. With increasing couple stress length parameter (*l*) in fig. 2b there is a marked acceleration in the axial flow. Stronger couple stresses in the aqueous solution therefore encourage axial momentum development across the channel span. Fig 2d reveals that with increasing magnetic parameter*, Ha,* there is acceleration in the axial flow. This is maintained across the channel span. Magnetic field therefore induces the opposite response to electrical field in the regime. In all figs 2a-d the maximum axial flow velocity is computed at the lower microchannel wall and there is decay in velocity across the channel span to a minimum in the vicinity of the upper channel wall.

Figs. 3a-d visualize the influence of respectively a) electro-osmotic parameter (i.e.  $2n_0$  $\mathbf{B}$ *d*  $\kappa = aez \sqrt{\frac{2n_0}{\varepsilon K_B T}} = \frac{a}{\lambda_d}$  $= aez \sqrt{\frac{2n_0}{x \cdot \overline{x}}} = \frac{a}{\lambda}$ ), b) Helmholtz-Smoluchowski velocity i.e. characteristic electro-

osmotic velocity  $(u_e = -\frac{L_x}{L_x})$  $u_e = -\frac{E}{\epsilon}$ *c*  $\varepsilon\zeta$  $\mu$  $=-\frac{E_x \varepsilon \zeta}{\lambda}$ , c) couple stress length parameter  $(l=\frac{1}{\lambda})\frac{\eta}{\lambda}$ , *a*  $\eta$  $\mu$  $=-\frac{1}{4}$ , and

d)Hartmann magnetic parameter ( $Ha = \sqrt{\frac{\sigma}{a}}$  $\mu$  $=\sqrt{-aB_y}$  on volumetric flow rate (*Q*). These graphs

are plotted against axial coordinate. The irregularity in the profiles is associated with the complex dual amplitude peristaltic waves imposed at the two microchannel walls. With increasing electro-osmotic parameter, $\kappa$ , the flow rate is significantly enhanced (fig 3a). With increasing negative Helmholtz-Smoluchowski velocity, *ue*, flow rates are generally enhanced strongly. The converse behaviour is computed with positive Helmholtz-Smoluchowski velocity. In the former case the electrical field is directed along the positive x-axis and in the latter case it is in the reverse axial direction. Therefore with axial electrical field aligned with the direction of propagation of peristaltic waves, the flow is accelerated. It is inhibited when the electrical field is in the opposite direction to wave propagation. This confirms that that aligned axial electrical field and electro-kinetic effects are beneficial to the peristaltic pumping process, as elaborated by Goswami *et al.* [54] although they considered only powerlaw rheological fluids. With increasing couple stress effect (fig. 3c) there is also a substantial enhancement in flow rate which is associated with the acceleration in the axial flow owing to

greater couple stresses. The couple stress parameter,  $l = \frac{1}{n} \sqrt{\frac{\eta}{n}}$ , *a*  $\eta$  $\mu$  $=-\frac{1}{4}$ , is inversely proportional to the Newtonian dynamic viscosity and directly proportional to the polar viscosity. As this parameter is increased there is progressively less viscous resistance to the propulsion of aqueous electrolyte in the microchannel which manifests in axial acceleration. Fig. 3d shows that with greater Hartmann number, there is a consistently strong enhancement in volumetric flow rate, confirming the axial flow acceleration observed in the flow velocity computations in fig. 2d. This is achieved despite the fact that the viscous force still exceeds magnetic Lorentzian body force for all the cases in fig. 3d  $(Ha \le 1)$ . Transverse magnetic field is therefore assistive to peristaltic pumping.

**Figs 4a-d** depict the distribution in time averaged volumetric flow rate ( *Q* ) with pressure rise ( $\Delta p$ ) for variation in a) electro-osmotic parameter (i.e.  $\kappa = ae_z \sqrt{\frac{2n_0}{m}}$  $\mathbf{B}^I$   $\mathcal{A}_d$  $\kappa = aez \sqrt{\frac{2n_0}{\varepsilon K_B T}} = \frac{a}{\lambda_d}$  $= aez_1 \frac{2n_0}{\sqrt{a^2 + 2}} = \frac{a}{2}$ , b)

Helmholtz-Smoluchowski velocity i.e. characteristic electro-osmotic velocity ( $u_e = -\frac{E_x}{\sigma}$  $u_e = -\frac{E}{\epsilon}$ *c*  $\varepsilon\zeta$  $\mu$  $=-\frac{L_x c_5}{L_x}$ ),

c) couple stress length parameter  $(l = \frac{1}{l} \sqrt{\frac{\eta}{l}}$ , *a*  $\eta$  $\mu$  $=-\frac{1}{2}$ , and d) Hartmann magnetic parameter (

 $Ha = \sqrt{\frac{\sigma}{a}}aB_x$  $\mu$  $=\int_{0}^{\infty} aB$ , There is consistently a linear growth in flow rate with pressure rise i.e. greater pressures generate stronger peristaltic flow rates and fluxes. With increasing electro-kinetic parameter (decreasing Debye length), the time averaged flow rate magnitudes are strongly reduced (fig. 4a). An increase in assistive axial electrical field as simulated via negative Helmholtz-Smoluchowski velocity (fig. 4b) is also observed to significantly enhance time averaged flow rates in the microchannel. The opposite behaviour is observed for the case of an opposing axial electrical field (positive Helmholtz-Smoluchowski velocity). In both figs. 4a and b, there is no cross-over of profiles i.e. the influence of electro-kinetic parameter and Helmholtz-Smoluchowski velocity is sustained at all values of pressure rise. In fig. 4c there is initially a reduction in time averaged volumetric flow rate ( *Q* ) with greater couple stress parameter i.e. for low and intermediate values of pressure rise, more strongly polar viscous fluids induce flow reversal (negative flow rates). However after a critical value of pressure rise, this trend is reversed and increasing couple stress parameter is found to enhance time averaged volumetric flow rate. Fig 4d shows that for small pressure rise, increasing magnetic field effect (higher Hartmann number) reduces the time averaged volumetric flow rate, whereas at intermediate to larger values of pressure rise there is an accentuation in time

averaged volumetric flow rate. With stronger pressure difference, increasing magnetic field therefore achieves more efficient peristaltic pumping in the micro-channel regime.

**Figs. 5a-i** illustrate the streamline distributions with variation electro-osmotic parameter  $(\kappa)$ , Helmholtz-Smoluchowski velocity (*ue*), couple stress parameter (*l*) and Hartmann magnetic number (*Ha*). This visualization allows a better examination of the so-called trapping phenomenon, wherein an internally circulating bolus of the fluid is formed by closed streamlines. Figs 5a-c simulate a variation in electro-osmotic parameter  $(k)$ , with all other parameters fixed. As we progress through these figures there is the synthesis of increasingly more boluses in the central zone of the channel. Streamlines are strongly intensified in the core region of the channel. Boluses also grow in magnitude in the vertical direction more dramatically than in the lateral direction. Figs. 5d, e clearly indicate that with an increase in positive Helmholtz-Smoluchowski velocity  $(u_e)$  from 7 to 9, there is an intensification in the bolus formation again in the central zone. Furthermore there are more internal boluses generated in the alternate larger boluses across the channel. The imposition of a reversed axial electrical field therefore encourages the synthesis of more trapped zones in the regime. Figs 5f, g show that as couple stress parameter (*l*) increases from 0.25 to 1, there is a relaxation in the streamline distribution throughout the channel. The intense bolus formations evident at lower couple stress parameter values vanish and a longer, stretched zones appear in the central core of the channel. The flow is accelerated with stronger polar viscosity (higher l values) and clearly this induces elimination in the trapping zone architecture in the regime. Finally figs. 5h, i present the impact of increasing Hartmann number (*Ha* rises from 0.1 to 0.3) on the bolus dynamics. There is again a significant relaxation in the contours with increasing magnetic field effect. The transverse magnetic field eliminates distinct boluses formed at the upper and lower channel walls; diminished boluses appear closer to the channel centre line (longitudinal axis, *y* =0).

#### **5. CONCLUSIONS**

A mathematical study has been presented for evaluating the combined effects of transverse magnetic field and axial electrical field on peristaltic pumping of couple stress aqueous electrolyte in a two-dimensional micro-channel with different peristaltic waves propagating at the upper and lower channel wall (complex wavy scenario). The Stokes couple stress non-Newtonian model is utilized to simulate micro-structural characteristics of biological fluids. Using a coordinate system transformation, Debye length approximation and appropriate nondimensional variables, the time-dependent conservation equations for mass and momentum conservation with electro-kinetic and magnetic body forces are solved to derive exact expressions for axial velocity, volumetric flow rate, pressure rise, time-averaged volumetric flow rate. The computations have shown that:

- With increasing electro-osmotic parameter, axial velocity is decreased, the flow rate is significantly elevated, time averaged flow rate magnitudes are strongly reduced and more boluses (trapped zones) are generated in the central zone of the channel.
- With increasing negative Helmholtz-Smoluchowski velocity (i.e. assistive axial electrical field) axial flow is accelerated, flow rates are increased and time averaged flow rates are also enhanced.
- With increasing positive Helmholtz-Smoluchowski velocity (i.e. opposing axial electrical field) axial flow is decelerated and both flow rate and time averaged flow rate are reduced. Furthermore streamline contours are stronger and there is an increase in the quantity of boluses in the central core zone of the channel.
- With increasing couple stress parameter, axial velocity is enhanced, flow rate is increased, and for higher values of pressure rise the time-averaged volumetric flow rate is also enhanced. Additionally streamline contours are more relaxed with higher values of couple stress parameter resulting in the elimination of bolus numbers in the central core of the channel.
- With increasing Hartmann number, the axial flow is strongly accelerated, volumetric flow rate is elevated, and at higher pressure differences the time-averaged volumetric flow rate is also increased. It is further noteworthy that increasing magnetic field (Hartmann number) leads to vanishing of boluses near the upper and lower channel walls.

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